

# Package ‘Momocs’

March 22, 2018

**Title** Morphometrics using R

**Version** 1.2.9

**Date** 2018-03-22

**Description** The goal of Momocs is to provide a complete, convenient, reproducible and open-source toolkit for 2D morphometrics. It includes most common 2D morphometrics approaches on outlines, open outlines, configurations of landmarks, traditional morphometrics, and facilities for data preparation, manipulation and visualization with a consistent grammar throughout. It allows reproducible, complex morphometric analyses and other morphometrics approaches should be easy to plug in, or develop from, on top of this canvas.

**License** GPL-2 | GPL-3

**URL** <https://github.com/MomX/Momocs/>

**BugReports** <https://github.com/MomX/Momocs/issues>

**Depends** R(>= 3.2)

**LazyData** true

**Imports** ape, dplyr, magrittr, graphics, geometry, geomorph, ggplot2, grDevices, jpeg, MASS, progress, RColorBrewer, rgeos, sp, utils

**Suggests** devtools, knitr, rmarkdown, testthat, covr, roxygen2

**VignetteBuilder** knitr

**RoxygenNote** 6.0.1

**NeedsCompilation** no

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**Repository** CRAN

**Date/Publication** 2018-03-22 22:25:52 UTC

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add\_ldk *Adds new landmarks on Out and Opn objects*

### Description

Helps to add new landmarks on a Coo object on top of existing ones. The number of landmarks must be specified and rows indices that correspond to the nearest points clicked on every outlines are stored in the \$ldk slot of the Coo object.

### Usage

```
add_ldk(Coo, nb.ldk)
```

### Arguments

Coo	an Out or Opn object
nb.ldk	the number of landmarks to add on every shape

### Details

Note that if no landmarks are already defined, then this function is equivalent to [def\\_ldk](#).

### Value

an Out or an Opn object with some landmarks defined

### See Also

Other ldk/slidings methods: [def\\_ldk](#), [def\\_slidings](#), [get\\_ldk](#), [get\\_slidings](#), [rearrange\\_ldk](#), [slidings\\_scheme](#)

### Examples

```
## Not run:
hearts <- slice(hearts, 1:5) # to make it shorter to try
# click on 3 points, 5 times.
hearts <- def_ldk(hearts, 3)
# Don't forget to save the object returned by def_ldk...
hearts2 <- add_ldk(hearts, 3)
stack(hearts2)
hearts2$ldk

## End(Not run)
```

---

andnow	<i>And now, what to do?</i>
--------	-----------------------------

---

### Description

`andnow`, given an object, return available methods for its class(es); `andnow_method`, given a function/method name, return supported classes.

### Usage

```
andnow(x)
```

```
andnow_method(x)
```

### Arguments

x                    any object, or class (quoted or not)

### Examples

```
#methods for data.frame
andnow(iris)

#methods for Coo objects
andnow(bot)

#classes supported by efourier
andnow_method("efourier")

# methods for plot
andnow_method("plot")
```

---

apodemus	<i>Data: Outline coordinates of Apodemus (wood mouse) mandibles</i>
----------	---

---

### Description

Data: Outline coordinates of Apodemus (wood mouse) mandibles

### Format

A `Out` object 64 coordinates of 30 wood molar outlines.

### Source

Renaud S, Pale JRM, Michaux JR (2003): Adaptive latitudinal trends in the mandible shape of *Apodemus* wood mice. *Journal of Biogeography* 30:1617-1628. <http://onlinelibrary.wiley.com/doi/10.1046/j.1365-2699.2003.00932.x/full>



**See Also**

Other datasets: [bot](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#), [wings](#)

---

arrange	<i>Arrange rows by variables</i>
---------	----------------------------------

---

**Description**

Arrange shapes by variables, from the \$fac. See examples and `?dplyr::arrange`.

**Usage**

```
arrange(.data, ...)
```

**Arguments**

<code>.data</code>	a Coo, Coe, PCA object
<code>...</code>	logical conditions

**Details**

dplyr verbs are maintained.

**Value**

a Momocs object of the same class.

**See Also**

Other handling functions: [at\\_least](#), [chop](#), [combine](#), [dissolve](#), [fac\\_dispatcher](#), [filter](#), [mutate](#), [rescale](#), [rm\\_harm](#), [rm\\_uncomplete](#), [rw\\_fac](#), [sample\\_frac](#), [sample\\_n](#), [select](#), [slice](#)

**Examples**

```
olea
# we create a new column
olea %>% mutate(id=1:length(.)) %$% fac$id
# same but now, shapes are arranged in a desc order, based on id
olea %>% mutate(id=1:length(.)) %>% arrange(desc(id)) %$% fac$id
```

---

`as_df`*Converts Momocs objects to data.frames*

---

**Description**

Used in particular for compatibility with the tidyverse

**Usage**

```
as_df(x)

## S3 method for class 'Coo'
as_df(x)

## S3 method for class 'Coe'
as_df(x)

## S3 method for class 'TraCoe'
as_df(x)

## S3 method for class 'PCA'
as_df(x)

## S3 method for class 'LDA'
as_df(x)
```

**Arguments**

`x` an object, typically a Momocs object

**Value**

a `data.frame`

**See Also**

Other bridges functions: [bridges](#), [complex](#), [export](#)

**Examples**

```
# smaller Out
lite_bot <- bot %>% slice(c(1, 2, 21, 22)) %>% coo_sample(12)
# Coo object
lite_bot %>% as_df %>% head
# Coe object
lite_bot %>% efourier(2) %>% as_df %>% head
# PCA object
lite_bot %>% efourier(2) %>% PCA %>% as_df %>% head
```

```
# LDA object
lite_bot %>% efourier(2) %>% PCA %>% LDA(~type) %>% as_df %>% head
```

---

at_least	<i>Retain groups with at least n shapes</i>
----------	---

---

## Description

Examples are self-speaking.

## Usage

```
at_least(x, fac, N)
```

## Arguments

x	any Momocs object
fac	the id of name of the \$fac column
N	minimal number of individuals to retain the group

## Note

if N is too ambitious the original object is returned with a message

## See Also

Other handling functions: [arrange](#), [chop](#), [combine](#), [dissolve](#), [fac\\_dispatcher](#), [filter](#), [mutate](#), [rescale](#), [rm\\_harm](#), [rm\\_uncomplete](#), [rw\\_fac](#), [sample\\_frac](#), [sample\\_n](#), [select](#), [slice](#)

## Examples

```
table(trilo$onto)
at_least(trilo, "onto", 9)
at_least(trilo, "onto", 16)
at_least(trilo, "onto", 2000) # too ambitious !
```

---

`bezier`*Calculates Bezier coefficients from a shape*

---

**Description**

Calculates Bezier coefficients from a shape

**Usage**

```
bezier(coo, n)
```

**Arguments**

`coo` a matrix or a list of (x; y) coordinates  
`n` the degree, by default the number of coordinates.

**Value**

a list with components:

- `$J` matrix of Bezier coefficients
- `$B` matrix of Bezier vertices.

**Note**

Directly borrowed for Claude (2008), and also called `bezier` there. Not implemented for open outlines but may be useful for other purposes.

**References**

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp.

**See Also**

Other bezier functions: [bezier\\_i](#)

**Examples**

```
set.seed(34)
x <- coo_sample(efourier_shape(), 5)
plot(x, ylim=c(-3, 3), asp=1, type='b', pch=20)
b <- bezier(x)
bi <- bezier_i(b$B)
lines(bi, col='red')
```

---

bezier_i	<i>Calculates a shape from Bezier coefficients</i>
----------	--

---

**Description**

Calculates a shape from Bezier coefficients

**Usage**

```
bezier_i(B, nb.pts = 120)
```

**Arguments**

B	a matrix of Bezier vertices, such as those produced by <a href="#">bezier</a>
nb.pts	the number of points to sample along the curve.

**Value**

a matrix of (x; y) coordinates

**Note**

Directly borrowed for Claude (2008), and called `beziercurve` there. Not implemented for open outlines but may be useful for other purposes.

**References**

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp.

**See Also**

Other bezier functions: [bezier](#)

**Examples**

```
set.seed(34)
x <- coo_sample(efourier_shape(), 5)
plot(x, ylim=c(-3, 3), asp=1, type='b', pch=20)
b <- bezier(x)
bi <- bezier_i(b$B)
lines(bi, col='red')
```

---

bot	<i>Data: Outline coordinates of beer and whisky bottles.</i>
-----	--

---

**Description**

Data: Outline coordinates of beer and whisky bottles.

**Format**

A `Out` object containing the outlines coordinates and a grouping factor for 20 beer and 20 whisky bottles

**Source**

Images have been grabbed on the internet and prepared by the package's authors. No particular choice has been made on the dimension of the original images or the brands cited here.

**See Also**

Other datasets: [apodemus](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#), [wings](#)

---

boxplot.OutCoe	<i>Boxplot of morphometric coefficients</i>
----------------	---

---

**Description**

Explores the distribution of coefficient values.

**Usage**

```
## S3 method for class 'OutCoe'
boxplot(x, retain = 6, drop = 0, center.y = TRUE, ...)
```

**Arguments**

<code>x</code>	the <code>Coe</code> object
<code>retain</code>	numeric the number of harmonics to retain
<code>drop</code>	numeric the number of harmonics to drop
<code>center.y</code>	logical whether to center the y-axis
<code>...</code>	useless here but maintain the consistency with generic boxplot

**Value**

a `ggplot2` object

**See Also**

Other Coe\_graphics: [hcontrib](#), [hist.OutCoe](#)

**Examples**

```
data(bot)
bot.f <- efourier(bot, 24)
boxplot(bot.f)
```

```
data(olea)
op <- opoly(olea)
boxplot(op)
```

---

boxplot.PCA

*Boxplot on PCA objects*

---

**Description**

Boxplot on PCA objects

**Usage**

```
## S3 method for class 'PCA'
boxplot(x, fac = NULL, nax, ...)
```

**Arguments**

x	PCA, typically obtained with <a href="#">PCA</a>
fac	factor, or a name or the column id from the \$fac slot
nax	the range of PC to plot (1 to 99pc total variance by default)
...	useless here

**Value**

a ggplot object

**Examples**

```
bot.f <- efourier(bot, 12)
bot.p <- PCA(bot.f)
boxplot(bot.p)
p <- boxplot(bot.p, 1)
#p + theme_minimal() + scale_fill_grey()
#p + facet_wrap(~PC, scales = "free")
```

---

breed	<i>Jitters Coe (and others) objects</i>
-------	---

---

### Description

This methods applies column-wise on the coe of any [Coe](#) object but relies on a function that can be used on any matrix. It simply uses [mnorm](#) with the mean and sd calculated for every column (or row). For a Coe object, on every colum, randomly generates coefficients values centered on the mean of the column, and with a sd equals to it standard deviates multiplied by rate.

### Usage

```
breed(x, ...)
```

## Default S3 method:

```
breed(x, fac, margin = 2, size, rate = 1, ...)
```

## S3 method for class 'Coe'

```
breed(x, fac, size, rate = 1, ...)
```

### Arguments

x	the object to permute
...	useless here
fac	a column, a formula or a column id from \$fac
margin	numeric whether 1 or 2 (rows or columns)
size	numeric the required size for the final object, same size by default
rate	numeric the number of sd for <a href="#">mnorm</a> , 1 by default.

### See Also

Other farming: [perm](#)

### Examples

```
m <- matrix(1:12, nrow=3)
breed(m, margin=2, size=4)
breed(m, margin=1, size=10)
```

```
bot.f <- efourier(bot, 12)
bot.m <- breed(bot.f, size=80)
bot.m %>% PCA %>% plot
```

```
# breed fac wise
# bot.f %>% breed(~type, size=50) %>% PCA %>% plot(~type)
```



---

bridges *Convert between different classes*

---

**Description**

Convert between different classes

**Usage**

l2m(l)

m2l(m)

d2m(d)

m2d(m)

l2a(l)

a2l(a)

a2m(a)

m2a(m)

m2ll(m, index = NULL)

**Arguments**

l	list with x and y coordinates as components
m	matrix of (x; y) coordinates
d	data.frame with two columns
a	array of (x; y) coordinates
index	numeric, the number of coordinates for every slice

**Value**

the data in the required class

**Note**

a2m/m2a change, by essence, the dimension of the data. m2ll is used internally to handle `coo` and `cur` in `Ldk` objects but may be useful elsewhere

**See Also**

Other bridges functions: [as\\_df](#), [complex](#), [export](#)

**Examples**

```

# matrix/list
wings[1] %>% coo_sample(4) %>%
  m2l() %T>% print %>%      # matrix to list
  l2m()                      # and back

# data.frame/matrix
wings[1] %>% coo_sample(4) %>%
  m2d() %T>% print %>%      # matrix to data.frame
  d2m                      # and back

# list/array
wings %>% slice(1:2) %$$
coo %>% l2a %T>% print %>%  # list to array
a2l                          # and back

# array/matrix
wings %>% slice(1:2) %$$
l2a(coo) %>%                # and array (from a list)
a2m %T>% print %>%          # to matrix
m2a                          # and back

# m2ll
m2ll(wings[1], c(6, 4, 3, 5)) # grab slices and coordinates

```

---

calibrate\_deviations    *Quantitative calibration, through deviations, for Out and Opn objects*

---

**Description**

Calculate deviations from original and reconstructed shapes using a range of harmonic number.

**Usage**

```

calibrate_deviations()

calibrate_deviations_efourier(x, id = 1, range, norm.centsize = TRUE,
  dist.method = edm_nearest, interpolate.factor = 1, dist.nbpts = 120,
  plot = TRUE)

calibrate_deviations_tfourier(x, id = 1, range, norm.centsize = TRUE,
  dist.method = edm_nearest, interpolate.factor = 1, dist.nbpts = 120,
  plot = TRUE)

calibrate_deviations_rfourier(x, id = 1, range, norm.centsize = TRUE,
  dist.method = edm_nearest, interpolate.factor = 1, dist.nbpts = 120,
  plot = TRUE)

```

```
calibrate_deviations_sfourier(x, id = 1, range, norm.centsize = TRUE,
  dist.method = edm_nearest, interpolate.factor = 1, dist.nbpts = 120,
  plot = TRUE)
```

```
calibrate_deviations_npoly(x, id = 1, range, norm.centsize = TRUE,
  dist.method = edm_nearest, interpolate.factor = 1, dist.nbpts = 120,
  plot = TRUE)
```

```
calibrate_deviations_opoly(x, id = 1, range, norm.centsize = TRUE,
  dist.method = edm_nearest, interpolate.factor = 1, dist.nbpts = 120,
  plot = TRUE)
```

```
calibrate_deviations_dfourier(x, id = 1, range, norm.centsize = TRUE,
  dist.method = edm_nearest, interpolate.factor = 1, dist.nbpts = 120,
  plot = TRUE)
```

### Arguments

x	and Out or Opn object on which to calibrate_deviations
id	the shape on which to perform calibrate_deviations
range	vector of harmonics (or degree for opoly and npoly on Opn) on which to perform calibrate_deviations. If not provided, the harmonics corresponding to 0.9, 0.95 and 0.99 are used.
norm.centsize	logical whether to normalize deviation by the centroid size
dist.method	a method such as <a href="#">edm_nearest</a> to calculate deviations
interpolate.factor	a numeric to increase the number of points on the original shape (1 by default)
dist.nbpts	numeric the number of points to use for deviations calculations
plot	logical whether to print the graph (FALSE is you just want the calculations)

### Details

Note that from version 1.1, the calculation changed and fixed a problem. Before, the 'best' possible shape was calculated using the highest possible number of harmonics. This worked well for `efourier` but not for others (eg `rfourier`, `tfourier`) as they are known to be unstable with high number of harmonics. From now on, Momocs uses the 'real' shape, as it is (so it must be centered) and uses [coo\\_interpolate](#) to produce `interpolate.factor` times more coordinates as the shape has and using the default `dist.method`, eg [edm\\_nearest](#), the latter finds the euclidean distance, for each point on the reconstructed shape, the closest point on this interpolated shape. `interpolate.factor` being set to 1 by default, no interpolation will be made in you do not ask for it. Note, that interpolation to decrease artefactual errors may also be done outside `calibrate_deviations` and will be probably be removed from it in further versions.

Note also that this code is quite old now and would need a good review, planned for 2018.

For \*poly methods on Opn objects, the deviations are calculated from a degree 12 polynomial.

**Value**

a ggplot object and the full list of intermediate results. See examples.

**See Also**

Other calibration: [calibrate\\_harmonicpower](#), [calibrate\\_r2](#), [calibrate\\_reconstructions](#)

**Examples**

```
b5 <- slice(bot, 1:5) #for the sake of speed
b5 %>% calibrate_deviations_efourier()
b5 %>% calibrate_deviations_rfouier()
b5 %>% calibrate_deviations_tfourier()
b5 %>% calibrate_deviations_sfourier()

o5 <- slice(olea, 1:5) #for the sake of speed
o5 %>% calibrate_deviations_opoly()
o5 %>% calibrate_deviations_npoly()
o5 %>% calibrate_deviations_dfouier()
```

---

calibrate\_harmonicpower

*Quantitative calibration, through harmonic power, for Out and Opn objects*

---

**Description**

Estimates the number of harmonics required for the four Fourier methods implemented in Momocs: elliptical Fourier analysis (see [efouier](#)), radii variation analysis (see [rfouier](#)) and tangent angle analysis (see [tfouier](#)) and discrete Fourier transform (see [dfouier](#)). It returns and can plot cumulated harmonic power whether dropping the first harmonic or not, and based and the maximum possible number of harmonics on the Coo object.

**Usage**

```
calibrate_harmonicpower()

calibrate_harmonicpower_efouier(x, id = 1:length(x), nb.h, drop = 1,
  thresh = c(90, 95, 99, 99.9), plot = TRUE)

calibrate_harmonicpower_rfouier(x, id = 1:length(x), nb.h, drop = 1,
  thresh = c(90, 95, 99, 99.9), plot = TRUE)

calibrate_harmonicpower_tfourier(x, id = 1:length(x), nb.h, drop = 1,
  thresh = c(90, 95, 99, 99.9), plot = TRUE)

calibrate_harmonicpower_sfourier(x, id = 1:length(x), nb.h, drop = 1,
```

```
thresh = c(90, 95, 99, 99.9), plot = TRUE)
```

```
calibrate_harmonicpower_dfourier(x, id = 1:length(x), nb.h, drop = 1,
  thresh = c(90, 95, 99, 99.9), plot = TRUE)
```

### Arguments

x	a Coo of Opn object
id	the shapes on which to perform calibrate_harmonicpower. All of them by default
nb.h	numeric the maximum number of harmonic, on which to base the cumsum
drop	numeric the number of harmonics to drop for the cumulative sum
thresh	vector of numeric for drawing horizontal lines, and also used for minh below
plot	logical whether to plot the result or simply return the matrix Silent message and progress bars (if any) with options("verbose"=FALSE).

### Details

The power of a given harmonic  $n$  is calculated as follows for elliptical Fourier analysis and the  $n$ -th harmonic:  $HarmonicPower_n = \frac{A_n^2 + B_n^2 + C_n^2 + D_n^2}{2}$  and as follows for radii variation and tangent angle:  $HarmonicPower_n = \frac{A_n^2 + B_n^2 + C_n^2 + D_n^2}{2}$

### Value

returns a list with component:

- gg a ggplot object, q the quantile matrix
- minh a quick summary that returns the number of harmonics required to achieve a certain proportion of the total harmonic power.

### See Also

Other calibration: [calibrate\\_deviations](#), [calibrate\\_r2](#), [calibrate\\_reconstructions](#)

### Examples

```
b5 <- bot %>% slice(1:5)
b5 %>% calibrate_harmonicpower_efourier(nb.h=12)
b5 %>% calibrate_harmonicpower_rfouier(nb.h=12)
b5 %>% calibrate_harmonicpower_tfouier(nb.h=12)
b5 %>% calibrate_harmonicpower_sfouier(nb.h=12)

# on Opn
olea %>% slice(1:5) %>%
  calibrate_harmonicpower_dfouier(nb.h=12)
## Not run:
# let customize the ggplot
library(ggplot2)
cal <- b5 %>% calibrate_harmonicpower_efourier(nb.h=12)
cal$gg + theme_minimal() +
```

```
coord_cartesian(xlim=c(3.5, 12.5), ylim=c(90, 100)) +
ggtitle("Harmonic power calibration")

## End(Not run)
```

---

calibrate\_r2

*Quantitative r2 calibration for Opn objects*


---

## Description

Estimates the r2 to calibrate the degree for [npoly](#) and [opoly](#) methods. Also returns a plot

## Usage

```
calibrate_r2()

calibrate_r2_opoly(Opn, id = 1:length(Opn), degree.range = 1:8,
  thresh = c(0.9, 0.95, 0.99, 0.999), plot = TRUE, ...)

calibrate_r2_npoly(Opn, id = 1:length(Opn), degree.range = 1:8,
  thresh = c(0.9, 0.95, 0.99, 0.999), plot = TRUE, ...)
```

## Arguments

Opn	an Opn object
id	the ids of shapes on which to calculate r2 (all by default)
degree.range	on which to calculate r2
thresh	the threshold to return diagnostic
plot	logical whether to print the plot
...	useless here

## Details

May be long, so you can estimate it on a sample either with id here, or one of [sample\\_n](#) or [sample\\_frac](#)

## Note

Silent message and progress bars (if any) with options("verbose"=FALSE).

## See Also

Other calibration: [calibrate\\_deviations](#), [calibrate\\_harmonicpower](#), [calibrate\\_reconstructions](#)

**Examples**

```

## Not run:
olea %>% slice(1:5) %>% #for the sake of speed
  calibrate_r2_opoly(degree.range=1:5, thresh=c(0.9, 0.99))

olea %>% slice(1:5) %>% #for the sake of speed
  calibrate_r2_npoly(degree.range=1:5, thresh=c(0.9, 0.99))

## End(Not run)

```

---

 calibrate\_reconstructions

*Calibrate using reconstructed shapes*

---

**Description**

Calculate and displays reconstructed shapes using a range of harmonic number. Compare them visually with the maximal fit. This explicitly demonstrates how robust efourier is compared to tfourier and rfourier.

**Usage**

```

calibrate_reconstructions()

calibrate_reconstructions_efourier(x, id, range = 1:9)

calibrate_reconstructions_rfourier(x, id, range = 1:9)

calibrate_reconstructions_tfourier(x, id, range = 1:9)

calibrate_reconstructions_sfourier(x, id, range = 1:9)

calibrate_reconstructions_npoly(x, id, range = 2:10, baseline1 = c(-1, 0),
  baseline2 = c(1, 0))

calibrate_reconstructions_opoly(x, id, range = 2:10, baseline1 = c(-1, 0),
  baseline2 = c(1, 0))

calibrate_reconstructions_dfourier(x, id, range = 2:10, baseline1 = c(-1,
  0), baseline2 = c(1, 0))

```

**Arguments**

x	the Coo object on which to calibrate_reconstructions
id	the shape on which to perform calibrate_reconstructions
range	vector of harmonics on which to perform calibrate_reconstructions

baseline1      ( $x; y$ ) coordinates for the first point of the baseline  
 baseline2      ( $x; y$ ) coordinates for the second point of the baseline  
 ...            only used for the generic

**Value**

a ggplot object and the full list of intermediate results. See examples.

**See Also**

Other calibration: [calibrate\\_deviations](#), [calibrate\\_harmonicpower](#), [calibrate\\_r2](#)

**Examples**

```
### On Out
shapes %>%
  calibrate_reconstructions_efourier(id=1, range=1:6)

# you may prefer efourier...
shapes %>%
  calibrate_reconstructions_tfourier(id=1, range=1:6)

#' you may prefer efourier...
shapes %>%
  calibrate_reconstructions_rfouier(id=1, range=1:6)

#' you may prefer efourier... # todo
#shapes %>%
#  calibrate_reconstructions_sfouier(id=5, range=1:6)

### On Opn
olea %>%
  calibrate_reconstructions_opoly(id=1)

olea %>%
  calibrate_reconstructions_npoly(id=1)

olea %>%
  calibrate_reconstructions_dfouier(id=1)
```

---

 chaff

*Data: Landmark and semilandmark coordinates on cereal glumes*

---

**Description**

Data: Landmark and semilandmark coordinates on cereal glumes



**Format**

An [Ldk](#) object with 21 configurations of landmarks and semi-landmarks (4 partitions) sampled on cereal glumes

**Source**

Research support was provided by the European Research Council (Evolutionary Origins of Agriculture (grant no. 269830-EOA) PI: Glynis Jones, Dept of Archaeology, Sheffield, UK. Data collected by Emily Forster.

**See Also**

Other datasets: [apodemus](#), [bot](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#), [wings](#)

---

charring

*Data: Outline coordinates from an experimental charring on cereal grains*

---

**Description**

Data: Outline coordinates from an experimental charring on cereal grains

**Format**

An [Out](#) object with 18 grains, 3 views on each, for 2 cereal species, charred at different temperatures for 6 hours (0C (no charring), 230C and 260C).

**Source**

Research support was provided by the European Research Council (Evolutionary Origins of Agriculture (grant no. 269830-EOA) PI: Glynis Jones, Dept of Archaeology, Sheffield, UK. Data collected by Emily Forster.

**See Also**

Other datasets: [apodemus](#), [bot](#), [chaff](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#), [wings](#)

---

 chop

*Split to several objects based on a factor*


---

### Description

Rougher slicing that accepts a classifier ie a column name from the \$fac on Momocs classes. Returns a named (after every level) list that can be lapply-ed and combined. See examples.

### Usage

```
chop(.data, fac)
```

### Arguments

.data	a Coo or Coe object
fac	a column name from the \$fac

### Value

a named list of Coo or Coe objects

### See Also

Other handling functions: [arrange](#), [at\\_least](#), [combine](#), [dissolve](#), [fac\\_dispatcher](#), [filter](#), [mutate](#), [rescale](#), [rm\\_harm](#), [rm\\_uncomplete](#), [rw\\_fac](#), [sample\\_frac](#), [sample\\_n](#), [select](#), [slice](#)

### Examples

```
olea %>%
  filter(var == "Aglan") %>% # to have a balanced nb of 'view'
  chop(~view) %>% # split into a list of 2
  lapply(npoly) %>% # separately apply npoly
  combine %>% # recombine
  PCA %>% plot # an illustration of the 2 views
  # treated separately
```

---

 classification\_metrics

*Calculate classification metrics on a confusion matrix*


---

### Description

In some cases, the class correctness or the proportion of correctly classified individuals is not enough, so here are more detailed metrics when working on classification.

**Usage**

```
classification_metrics(x)
```

**Arguments**

x a table or an [LDA](#) object

**Value**

a list with the following components is returned:

1. accuracy the fraction of instances that are correctly classified
2. macro\_prf data.frame containing precision (the fraction of correct predictions for a certain class); recall, the fraction of instances of a class that were correctly predicted; f1 the harmonic mean (or a weighted average) of precision and recall.
3. macro\_avg, just the average of the three macro\_prf indices
4. ova a list of one-vs-all confusion matrices for each class
5. ova\_sum a single of all ova matrices
6. kappa measure of agreement between the predictions and the actual labels

**See Also**

The pages below are of great interest to understand these metrics. The code used is partly derived from the Revolution Analytics blog post (with their authorization). Thanks to them!

1. [https://en.wikipedia.org/wiki/Precision\\_and\\_recall](https://en.wikipedia.org/wiki/Precision_and_recall)
2. [http://blog.revolutionanalytics.com/2016/03/com\\_class\\_eval\\_metrics\\_r.html](http://blog.revolutionanalytics.com/2016/03/com_class_eval_metrics_r.html)
3. <http://www.r-bloggers.com/is-your-classification-model-making-lucky-guesses/>

Other multivariate: [CLUST](#), [KMEANS](#), [LDA](#), [MANOVA\\_PW](#), [MANOVA](#), [PCA](#), [mshapes](#)

**Examples**

```
# some morphometrics on 'hearts'  
hearts %>% fgProcrustes(tol=1) %>%  
  coo_slide(ldk=1) %>% efourier(norm=FALSE) %>% PCA() %>%  
# now the LDA and its summary  
LDA(~aut) %>% classification_metrics()
```

CLUST

*Hierarchical clustering***Description**

Performs hierarchical clustering through [dist](#) and [hclust](#). So far it is mainly a wrapper around these two functions, plus plotting using [plot.phylo](#) from the package [ape](#).

**Usage**

```
CLUST(x, fac, type = "fan", dist_method = "euclidean",
      hclust_method = "complete", retain = 0.99, tip_labels,
      palette = col_qual, ...)
```

```
## Default S3 method:
CLUST(x, ...)
```

**Arguments**

<code>x</code>	a PCA object (Coe method deprecated so far)
<code>fac</code>	the id or column name or formula for columns to use from <code>\$fac</code> .
<code>type</code>	to pass to <code>ape::plot.phylo</code> 's <code>type</code> argument, one of "cladogram", "phylogram", "radial", "unrooted" or "fan" (by default)
<code>dist_method</code>	to feed <a href="#">dist</a> 's <code>method</code> argument, one of "euclidean", "maximum", "manhattan", "canberra", "binary" or "minkowski".
<code>hclust_method</code>	to feed <a href="#">hclust</a> 's <code>method</code> argument, one of "ward.D", "ward.D2", "single", "complete" (default), "average", "mcquitty", "median" or "centroid".
<code>retain</code>	number of axis to retain from the PCA as a range of number eg 1:5 to retain the first 5 PCs. If a number $\leq 1$ is passed, then the number of PCs retained will be enough to capture this proportion of variance.
<code>tip_labels</code>	the id or column name in <code>\$fac</code> to use as <code>tip_labels</code> rather than <code>rownames</code> . Note that you can also pass a character (or a factor) with the same number of rows of <code>x\$x</code>
<code>palette</code>	a color palette to use ( <code>col_qual</code> by default). If <code>NULL</code> , <code>par("fg")</code> is used
<code>...</code>	additional parameters to feed <code>plot.phylo</code>

**Value**

the phylo object, invisibly

**See Also**

Other multivariate: [KMEANS](#), [LDA](#), [MANOVA\\_PW](#), [MANOVA](#), [PCA](#), [classification\\_metrics](#), [mshapes](#)

## Examples

```
## Not run:

# we prepare a PCA with shorter names
olea_lite <- olea
names(olea_lite) <- as.character(olea$fac$var)
x <- olea_lite %>% opoly(5) %>% PCA()

# By default
CLUST(x)

# With a fac
CLUST(x, 1)

# plot.phylo types
CLUST(x, "var", type="cladogram")
CLUST(x, "var", type="phylogram")
CLUST(x, "var", type="radial")
CLUST(x, "var", type="unrooted")

# other dist/hclust methods
CLUST(x, "var", layout="cladogram", dist_method="minkowski", hclust_method="average")

# With another
CLUST(x, "domes", tip_labels="var", palette=col_india)

# Alternative ways to pass a factor
CLUST(x, 1)
CLUST(x, "var")
CLUST(x, ~var)
# Strict equivalent before but formula allows this:
CLUST(x, ~ domes + var, tip_labels = ~ domes + var)

# More arguments to plot.phylo
CLUST(x, cex=0.5)

## End(Not run)
```

---

Coe

*Coe "super" class*

---

## Description

Coe class is the 'parent' or 'super' class of [OutCoe](#), [OpnCoe](#), [LdkCoe](#) and [TraCoe](#) classes.

## Usage

```
Coe(...)
```

## Arguments

... anything and, anyway, this function will simply returns a message.

## Details

Useful shortcuts are described below. See `browseVignettes("Momocs")` for a detail of the design behind Momocs' classes.

Coe class is the 'parent' class of the following 'child' classes

- [OutCoe](#) for coefficients from closed **out**lines morphometrics
- [OpnCoe](#) for coefficients from **open** outlines morphometrics
- [LdkCoe](#) for coefficients from configuration of **landmarks** morphometrics.

In other words, [OutCoe](#), [OpnCoe](#) and [LdkCoe](#) classes are all, primarily, Coe objects on which we define generic *and* specific methods. See their respective help pages for more help.

You can access all the methods available for Coe objects with `methods(class=Coe)`.

## See Also

Other classes: [Coo](#), [OpnCoe](#), [Opn](#), [OutCoe](#), [Out](#), [TraCoe](#)

## Examples

```
# to see all methods for Coe objects.
methods(class='Coe')
# to see all methods for OutCoe objects.
methods(class='OutCoe') # same for OpnCoe, LdkCoe, TraCoe

bot.f<- efourier(bot, 12)
bot.f
class(bot.f)
inherits(bot.f, "Coe")

# if you want to work directly on the matrix of coefficients
bot.f$coe

#getters
bot.f[1]
bot.f[1:5]

#setters
bot.f[1] <- 1:48
bot.f[1]

bot.f[1:5] <- matrix(1:48, nrow=5, ncol=48, byrow=TRUE)
bot.f[1:5]

# An illustration of Momocs desing. See also browseVignettes("Momocs")
op <- opoly(olea, 5)
op
```

```

class(op)
op$coe # same thing

wp <- fgProcrustes(wings, tol=1e-4)
wp
class(wp) # for Ldk methods, LdkCoe objects can also be considered as Coe objects
# so you can apply all Ldk methods available.
wp$coe # Procrustes aligned coordinates

```

---

coeff_rearrange	<i>Rearrange a matrix of (typically Fourier) coefficients</i>
-----------------	---

---

### Description

Momocs uses colnamed matrices to store (typically) Fourier coefficients in [Coe](#) objects (typically [OutCoe](#)). They are arranged as rank-wise: A1, A2, ..., An, B1, ..., Bn, C1, ..., Cn, D1, ..., Dn. From other softwares they may arrive as A1, B1, C1, D1, ..., An, Bn, Cn, Dn, this functions helps to go from one to the other format. In short, this function rearranges column order. See examples.

### Usage

```
coeff_rearrange(x, by = c("name", "rank")[1])
```

### Arguments

x	matrix (with colnames)
by	character either "name" (A1, A2, ..) or "rank" (A1, B1, ...)

### Examples

```

m_name <- m_rank <- matrix(1:32, 2, 16)
# this one is ordered by name
colnames(m_name) <- paste0(rep(letters[1:4], each=4), 1:4)
# this one is ordered by rank
colnames(m_rank) <- paste0(letters[1:4], rep(1:4, each=4))

m_rank
m_rank %>% coeff_rearrange(by="name")
m_rank %>% coeff_rearrange(by="rank") #no change

m_name
m_name %>% coeff_rearrange(by="name") # no change
m_name %>% coeff_rearrange(by="rank")

```

---

coeff\_sel *Helps to select a given number of harmonics from a numerical vector.*

---

### Description

coeff\_sel helps to select a given number of harmonics by returning their indices when arranged as a numeric vector. For instance, harmonic coefficients are arranged in the \$coe slot of Coe-objects in that way:  $A_1, \dots, A_n, B_1, \dots, B_n, C_1, \dots, C_n, D_1, \dots, D - n$  after an elliptical Fourier analysis (see [efourier](#) and [efourier](#)) while  $C_n$  and  $D_n$  harmonic are absent for radii variation and tangent angle approaches (see [rfourier](#) and [tfourier](#) respectively). . This function is used internally but might be of interest elsewhere.

### Usage

```
coeff_sel(retain = 8, drop = 0, nb.h = 32, cph = 4)
```

### Arguments

retain	numeric. The number of harmonics to retain.
drop	numeric. The number of harmonics to drop
nb.h	numeric. The maximum harmonic rank.
cph	numeric. Must be set to 2 for rfourier and tfourier were used.

### Value

coeff\_sel returns indices that can be used to select columns from an harmonic coefficient matrix.  
coeff\_split returns a named list of coordinates.

### Examples

```
bot.f <- efourier(bot, 32)
coe <- bot.f$coe # the raw matrix
coe
# if you want, say the first 8 harmonics but not the first one
retain <- coeff_sel(retain=8, drop=1, nb.h=32, cph=4)
head(coe[, retain])
```



---

coeff_split	<i>Converts a numerical description of harmonic coefficients to a named list.</i>
-------------	---

---

### Description

coeff\_split returns a named list of coordinates from a vector of harmonic coefficients. For instance, harmonic coefficients are arranged in the \$coe slot of Coe-objects in that way:  $A_1, \dots, A_n, B_1, \dots, B_n, C_1, \dots, C_n, D_1, \dots, D_n$  after an elliptical Fourier analysis (see [efourier](#) and [efourier](#)) while  $C_n$  and  $D_n$  harmonic are absent for radii variation and tangent angle approaches (see [rfourier](#) and [tfourier](#) respectively). This function is used internally but might be of interest elsewhere.

### Usage

```
coeff_split(cs, nb.h = 8, cph = 4)
```

### Arguments

cs	A vector of harmonic coefficients.
nb.h	numeric. The maximum harmonic rank.
cph	numeric. Must be set to 2 for rfourier and tfourier were used.

### Value

Returns a named list of coordinates.

### Examples

```
coeff_split(1:128, nb.h=32, cph=4) # efourier
coeff_split(1:64, nb.h=32, cph=2) # t/r fourier
```

---

color_palettes	<i>Some color palettes</i>
----------------	----------------------------

---

### Description

Colors, colors, colors.

**Usage**

```
col_summer(n)
col_summer2(n)
col_spring(n)
col_autumn(n)
col_black(n)
col_solarized(n)
col_gallus(n)
col_qual(n)
col_heat(n)
col_hot(n)
col_cold(n)
col_sari(n)
col_india(n)
col_bw(n)
col_grey(n)
```

**Arguments**

n                    the number of colors to generate from the color palette

**Value**

colors (hexadecimal format)

**Note**

Among available color palettes, `col_solarized` is based on Solarized: <http://ethanschoonover.com/solarized>; `col_div`, `col_qual`, `col_heat`, `col_cold` and `col_gallus` are based on on ColorBrewer2: <http://colorbrewer2.org/>.

**Examples**

```
wheel <- function(palette, n=10){
```

```
op <- par(mar=rep(0, 4)) ; on.exit(par(op))
pie(rep(1, n), col=palette(n), labels=NA, clockwise=TRUE)}

# Qualitative
wheel(col_qual)
wheel(col_solarized)
wheel(col_summer)
wheel(col_summer2)
wheel(col_spring)
wheel(col_autumn)

# Divergent
wheel(col_gallus)
wheel(col_india)

# Sequential
wheel(col_heat)
wheel(col_hot)
wheel(col_cold)
wheel(col_sari)
wheel(col_bw)
wheel(col_grey)

# Black only for pubs
wheel(col_black)
```

---

col\_transp

*Transparency helpers and palettes*

---

## Description

To ease transparency handling.

## Usage

```
col_transp(n, col = "#000000", ceiling = 1)
```

```
col_alpha(cols, transp = 0)
```

## Arguments

n	the number of colors to generate
col	a color in hexadecimal format on which to generate levels of transparency
ceiling	the maximal opacity (from 0 to 1)
cols	on or more colors, provided as hexadecimal values
transp	numeric between 0 and 1, the value of the transparency to obtain

**Examples**

```
x <- col_transp(10, col='#000000')
x
barplot(1:10, col=x, main='a transparent black is grey')

summer10 <- col_summer(10)
summer10
summer10.transp8 <- col_alpha(summer10, 0.8)
summer10.transp8
summer10.transp2 <- col_alpha(summer10, 0.8)
summer10.transp2
x <- 1:10
barplot(x, col=summer10.transp8)
barplot(x/2, col=summer10.transp2, add=TRUE)
```

---

 combine

*Combine several objects*


---

**Description**

Combine Coo objects after a slicing, either manual or using [slice](#) or [chop](#). Note that on Coo object, it combines row-wise (ie, merges shapes as a c would do) ; but on Coe it combines column-wise (merges coefficients). In the latter case, Coe must have the same number of shapes (not necessarily the same number of coefficients). Also the \$fac of the first Coe is retrieved. A separate version may come at some point.

**Usage**

```
combine(...)
```

**Arguments**

```
...          a list of Out(Coe), Opn(Coe), Ldk objects (but of the same class)
```

**Note**

Note that the order of shapes or their coefficients is not checked, so anything with the same number of rows will be merged.

**See Also**

Other handling functions: [arrange](#), [at\\_least](#), [chop](#), [dissolve](#), [fac\\_dispatcher](#), [filter](#), [mutate](#), [rescale](#), [rm\\_harm](#), [rm\\_uncomplete](#), [rw\\_fac](#), [sample\\_frac](#), [sample\\_n](#), [select](#), [slice](#)

**Examples**

```

w <- filter(bot, type=="whisky")
b <- filter(bot, type=="beer")
combine(w, b)
# or, if you have many levels
bot_s <- chop(bot, ~type)
bot_s$whisky
# note that you can apply something (single function or a more
# complex pipe) then combine everyone, since combine also works on lists
# eg:
# bot_s2 <- lapply(bot_s, efourier, 10)
# bot_sf <- combine(bot_s2)

# pipe style
lapply(bot_s, efourier, 10) %>% combine()

```

---

 complex

---

*Convert complex to/from cartesian coordinates*


---

**Description**

Convert complex to/from cartesian coordinates

**Usage**

```

cpx2coo(Z)

coo2cpx(coo)

```

**Arguments**

Z	coordinates expressed in the complex form
coo	coordinates expressed in the cartesian form

**Value**

coordinates expressed in the cartesian/complex form

**See Also**

Other bridges functions: [as\\_df](#), [bridges](#), [export](#)

**Examples**

```

shapes[4] %>% # from cartesian
  coo_sample(24) %>%
  coo2cpx() %T>% # to complex
  cpx2coo() # and back

```

---

Coo *Coo "super" class*

---

### Description

Coo class is the 'parent' or 'super' class of [Out](#), [Opn](#) and [Ldk](#) classes.

### Usage

```
Coo(...)
```

### Arguments

... anything and, anyway, this function will simply returns a message.

### Details

Useful shortcuts are described below. See `browseVignettes("Momocs")` for a detail of the design behind Momocs' classes.

Coo class is the 'parent' class of the following 'child' classes

- [Out](#) for closed **out**lines
- [Opn](#) for **open** outlines
- [Ldk](#) for configuration of **land**marks

Since all 'child classes' of them handle  $(x; y)$  coordinates among other generic methods, but also all have their specificity, this architecture allow to recycle generic methods and to use specific methods.

In other words, [Out](#), [Opn](#) and [Ldk](#) classes are all, primarily, Coo objects on which we define generic *and* specific methods. See their respective help pages for more help.

You can access all the methods available for Coo objects with `methods(class=Coo)`.

### See Also

Other classes: [Coe](#), [OpnCoe](#), [Opn](#), [OutCoe](#), [Out](#), [TraCoe](#)

### Examples

```
## Not run:
# to see all methods for Coo objects.
methods(class='Coo')

# to see all methods for Out objects.
methods(class='Out') # same for Opn and Ldk

# Let's take an Out example. But all methods shown here
# work on Ldk (try on 'wings') and on Opn ('olea')
bot
```

```

# Primarily a 'Coo' object, but also an 'Out'
class(bot)
inherits(bot, "Coo")
panel(bot)
stack(bot)
plot(bot)

# Getters (you can also use it to set data)
bot[1] %>% coo_plot()
bot[1:5] %>% str()

# Setters
bot[1] <- shapes[4]
panel(bot)

bot[1:5] <- shapes[4:8]
panel(bot)

# access the different components
# $coo coordinates
head(bot$coo)
# $fac grouping factors
head(bot$fac)
# or if you know the name of the column of interest
bot$type
# table
table(bot$fac)
# an internal view of an Out object
str(bot)

# subsetting
# see ?filter, ?select, and their 'see also' section for the
# complete list of dplyr-like verbs implemented in Momocs

length(bot) # the number of shapes
names(bot) # access all individual names
bot2 <- bot
names(bot2) <- paste0('newnames', 1:length(bot2)) # define new names

## End(Not run)

```

---

coo\_align

*Aligns coordinates*


---

### Description

Aligns the coordinates along their longer axis using var-cov matrix and eigen values.

### Usage

```
coo_align(coo)
```

**Arguments**

coo                    matrix of (x; y) coordinates or any [Coo](#) object.

**Value**

a matrix of (x; y) coordinates, or a [Coo](#) object.

**See Also**

Other aligning functions: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#)

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
coo_plot(bot[1])
coo_plot(coo_align(bot[1]))
# on a Coo
stack(bot)
stack(coo_align(bot))
```

---

`coo_aligncalliper`            *Aligns shapes along their 'calliper length'*

---

**Description**

And returns them registered on bookstein coordinates. See [coo\\_bookstein](#).

**Usage**

```
coo_aligncalliper(coo)
```

**Arguments**

coo                    matrix of (x; y) coordinates or any [Coo](#) object.

**Value**

a matrix of (x; y) coordinates, or any [Coo](#) object.



**See Also**

Other aligning functions: [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#)

Other `coo_` utilities: [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
## Not run:
b <- bot[1]
coo_plot(b)
coo_plot(coo_aligncalliper(b))
bot.al <- coo_aligncalliper(bot)
stack(bot.al)

## End(Not run)
```

---

<code>coo_alignminradius</code>	<i>Aligns shapes using their shortest radius</i>
---------------------------------	--

---

**Description**

And returns them slided with the first coordinate on the east. May be used as an aligning strategy on shapes with a clear 'invaginate' part.

**Usage**

```
coo_alignminradius(coo)
```

**Arguments**

`coo` matrix of (x; y) coordinates or any [Coo](#) object.

**Value**

a matrix of (x; y) coordinates, or a [Coo](#) object.

**See Also**

Other aligning functions: [coo\\_aligncalliper](#), [coo\\_alignxax](#), [coo\\_align](#)

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_allyspacedradii](#)

**Examples**

```
## Not run:
stack(coo_alignminradius(hearts))

## End(Not run)
```

---

<code>coo_alignxax</code>	<i>Aligns shapes along the x-axis</i>
---------------------------	---------------------------------------

---

**Description**

Align the longest axis of a shape along the x-axis.

**Usage**

```
coo_alignxax(coo)
```

**Arguments**

`coo` matrix of (x; y) coordinates or any [Coo](#) object.

**Details**

If some shapes are upside-down (or mirror of each others), try redefining a new starting point (eg with `coo_slidedirection`) before the alignment step. This may solve your problem because `coo_calliper` orders the `$arr.ind` used by `coo_aligncalliper`.

**Value**

a matrix of (x; y) coordinates, or any [Coo](#) object.

**See Also**

Other aligning functions: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_align](#)

Other coo\_ utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
## Not run:
b <- bot[1]
coo_plot(b)
coo_plot(coo_alignxax(b))

## End(Not run)
```

---

coo\_angle\_edge1

*Calculate the angle formed by three (x; y) coordinates*


---

**Description**

Returns the angle (in radians) defined by a triplet of points either signed ('atan2') or not ('acos').

**Usage**

```
coo_angle_edge1(coo, method = c("atan2", "acos")[1])
```

```
coo_theta3(coo, method = c("atan2", "acos")[1])
```

**Arguments**

coo                    a 3x2 matrix of 3 points (rows) and (x; y) coordinates  
method                one of 'atan2' or 'acos' for a signed or not angle.

**Value**

numeric the angle in radians.

**Note**

coo\_theta3 is deprecated and will be removed in future releases.

**See Also**

Other `coo_` descriptors: `coo_angle_edges`, `coo_angle_tangent`, `coo_area`, `coo_boundingbox`, `coo_chull`, `coo_circularity`, `coo_convexity`, `coo_eccentricity`, `coo_elongation`, `coo_length`, `coo_lw`, `coo_rectangularity`, `coo_rectilinearity`, `coo_solidity`, `coo_width`

**Examples**

```
b <- coo_sample(bot[1], 64)
b <- b[c(1, 14, 24), ]
coo_plot(b)
coo_angle_edges(b)
coo_angle_edges(bot[1])
```

---

<code>coo_angle_edges</code>	<i>Calculates the angle of every edge of a shape</i>
------------------------------	--

---

**Description**

Returns the angle (in radians) of every edge of a shape,

**Usage**

```
coo_angle_edges(coo, method = c("atan2", "acos")[1])

## Default S3 method:
coo_angle_edges(coo, method = c("atan2", "acos")[1])

## S3 method for class 'Coo'
coo_angle_edges(coo, method = c("atan2", "acos")[1])

coo_thetapts(coo, method = c("atan2", "acos")[1])
```

**Arguments**

`coo` a matrix or a list of (x; y) coordinates or any `Coo`  
`method` 'atan2' (or 'acos') for a signed (or not) angle.

**Value**

numeric the angles in radians for every edge.

**Note**

`coo_thetapts` is deprecated and will be removed in future releases.

**See Also**

Other coo\_ descriptors: [coo\\_angle\\_edge1](#), [coo\\_angle\\_tangent](#), [coo\\_area](#), [coo\\_boundingbox](#), [coo\\_chull](#), [coo\\_circularity](#), [coo\\_convexity](#), [coo\\_eccentricity](#), [coo\\_elongation](#), [coo\\_length](#), [coo\\_lw](#), [coo\\_rectangularity](#), [coo\\_rectilinearity](#), [coo\\_solidity](#), [coo\\_width](#)

**Examples**

```
b <- coo_sample(bot[1], 64)
coo_angle_edges(b)
```

---

coo_angle_tangent	<i>Calculates the tangent angle along the perimeter of a shape</i>
-------------------	--

---

**Description**

Calculated using complex numbers and returned in radians minus the first one (modulo  $2\pi$ ).

**Usage**

```
coo_angle_tangent(coo)

## Default S3 method:
coo_angle_tangent(coo)

## S3 method for class 'Coo'
coo_angle_tangent(coo)

coo_tangle(coo)
```

**Arguments**

coo                    a matrix of coordinates or any Coo

**Value**

numeric, the tangent angle along the perimeter, or a list of those for Coo

**See Also**

[tfourier](#)

Other coo\_ descriptors: [coo\\_angle\\_edge1](#), [coo\\_angle\\_edges](#), [coo\\_area](#), [coo\\_boundingbox](#), [coo\\_chull](#), [coo\\_circularity](#), [coo\\_convexity](#), [coo\\_eccentricity](#), [coo\\_elongation](#), [coo\\_length](#), [coo\\_lw](#), [coo\\_rectangularity](#), [coo\\_rectilinearity](#), [coo\\_solidity](#), [coo\\_width](#)

**Examples**

```

b <- bot[1]
phi <- coo_angle_tangent(b)
phi2 <- coo_angle_tangent(coo_smooth(b, 2))
plot(phi, type='l')
plot(phi2, type='l', col='red') # ta is very sensible to noise

# on Coo
bot %>% coo_angle_tangent

```

---

coo\_area

*Calculates the area of a shape*


---

**Description**

Calculates the area for a (non-crossing) shape.

**Usage**

```
coo_area(coo)
```

**Arguments**

coo                    a matrix of (x; y) coordinates.

**Value**

numeric, the area.

**Note**

Using `area.poly` in `gpc` package is a good idea, but their licence impedes Momocs to rely on it. but here is the function to do it, once `gpc` is loaded: `area.poly(as(coo, 'gpc.poly'))`

**See Also**

Other `coo_` descriptors: [coo\\_angle\\_edge1](#), [coo\\_angle\\_edges](#), [coo\\_angle\\_tangent](#), [coo\\_boundingbox](#), [coo\\_chull](#), [coo\\_circularity](#), [coo\\_convexity](#), [coo\\_eccentricity](#), [coo\\_elongation](#), [coo\\_length](#), [coo\\_lw](#), [coo\\_rectangularity](#), [coo\\_rectilinearity](#), [coo\\_solidity](#), [coo\\_width](#)

**Examples**

```

coo_area(bot[1])
# for the distribution of the area of the bottles dataset
hist(sapply(bot$coo, coo_area), breaks=10)

```

---

coo_arrows	<i>Plots (lollipop) differences between two configurations</i>
------------	--

---

### Description

Draws 'arrows' between two configurations.

### Usage

```
coo_arrows(coo1, coo2, length = coo_centsize(coo1)/15, angle = 20, ...)
```

### Arguments

coo1	A list or a matrix of coordinates.
coo2	A list or a matrix of coordinates.
length	a length for the arrows.
angle	an angle for the arrows
...	optional parameters to feed <a href="#">arrows</a> .

### See Also

Other plotting functions: [coo\\_draw](#), [coo\\_listpanel](#), [coo\\_lolli](#), [coo\\_plot](#), [coo\\_ruban](#), [ldk\\_chull](#), [ldk\\_confell](#), [ldk\\_contour](#), [ldk\\_labels](#), [ldk\\_links](#), [plot\\_devsegments](#), [plot\\_table](#)

### Examples

```
coo_arrows(coo_sample(olea[3], 50), coo_sample(olea[6], 50))
title("Hi there !")
```

---

coo_baseline	<i>Register new baselines</i>
--------------	-------------------------------

---

### Description

A non-exact baseline registration on t1 and t2 coordinates, for the ldk1-th and ldk2-th points. By default it returns Bookstein's coordinates.

### Usage

```
coo_baseline(coo, ldk1, ldk2, t1, t2)
```

**Arguments**

coo	matrix of (x; y) coordinates or any <a href="#">Coo</a> object.
ldk1	numeric the id of the first point of the new baseline
ldk2	numeric the id of the second point of the new baseline
t1	numeric the (x; y) coordinates of the 1st point of the new baseline
t2	numeric the (x; y) coordinates of the 2nd point of the new baseline

**Value**

a matrix of (x; y) coordinates or a [Coo](#) object.

**See Also**

Other baselining functions: [coo\\_bookstein](#)

Other coo\_ utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
stack(hearts)
stack(coo_baseline(hearts, 2, 4, c(-1, 0), c(1, 1)))
```

---

coo\_bookstein

*Register Bookstein's coordinates*

---

**Description**

Registers a new baseline for the shape, with the ldk1-th and ldk2-th points being set on  $(x = -0.5; y = 0)$  and  $(x = 0.5; y = 0)$ , respectively.

**Usage**

```
coo_bookstein(coo, ldk1, ldk2)
```

**Arguments**

coo	matrix of (x; y) coordinates or any <a href="#">Coo</a> object.
ldk1	numeric the id of the first point of the new baseline (the first, by default)
ldk2	numeric the id of the second point of the new baseline (the last, by default)



**Details**

For **Out**, it tries to do it using \$1dk slot. Also the case for **Opn**, but if no landmark is defined, it will do it on the first and the last point of the shape.

For **Out** and **Opn** defines the first landmark as the first point of the new shapes with **coo\_slide**.

**Value**

a matrix of (x; y) coordinates, or a **Coo** object.

**See Also**

Other baselining functions: **coo\_baseline**

Other **coo\_** utilities: **coo\_aligncalliper**, **coo\_alignminradius**, **coo\_alignxax**, **coo\_align**, **coo\_baseline**, **coo\_boundingbox**, **coo\_calliper**, **coo\_centdist**, **coo\_center**, **coo\_centpos**, **coo\_close**, **coo\_down**, **coo\_dxy**, **coo\_extract**, **coo\_flipx**, **coo\_force2close**, **coo\_interpolate**, **coo\_is\_closed**, **coo\_jitter**, **coo\_left**, **coo\_likely\_clockwise**, **coo\_nb**, **coo\_perim**, **coo\_range**, **coo\_rev**, **coo\_right**, **coo\_rotatecenter**, **coo\_rotate**, **coo\_sample\_prop**, **coo\_samlerr**, **coo\_sample**, **coo\_scale**, **coo\_shearx**, **coo\_slice**, **coo\_slidedirection**, **coo\_slidegap**, **coo\_slide**, **coo\_smoothcurve**, **coo\_smooth**, **coo\_template**, **coo\_trans**, **coo\_trimbottom**, **coo\_trimtop**, **coo\_trim**, **coo\_up**, **is\_equallyspacedradii**

**Examples**

```
stack(hearts)
stack(coo_bookstein(hearts, 2, 4))
h <- hearts[1]
coo_plot(h)
coo_plot(coo_bookstein(h, 20, 57), border='red')
```

---

coo\_boundingbox

*Calculates coordinates of the bounding box*

---

**Description**

Calculates coordinates of the bounding box

**Usage**

```
coo_boundingbox(coo)
```

**Arguments**

**coo** matrix of (x; y) coordinates or any **Coo** object.

**Value**

data.frame with coordinates of the bounding box

**See Also**

Other coo\_ utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

Other coo\_ descriptors: [coo\\_angle\\_edge1](#), [coo\\_angle\\_edges](#), [coo\\_angle\\_tangent](#), [coo\\_area](#), [coo\\_chull](#), [coo\\_circularity](#), [coo\\_convexity](#), [coo\\_eccentricity](#), [coo\\_elongation](#), [coo\\_length](#), [coo\\_lw](#), [coo\\_rectangularity](#), [coo\\_rectilinearity](#), [coo\\_solidity](#), [coo\\_width](#)

**Examples**

```
bot[1] %>% coo_boundingbox()
bot %>% coo_boundingbox()
```

---

coo_calliper	<i>Calculates the calliper length</i>
--------------	---------------------------------------

---

**Description**

Also called the Feret's diameter, the longest distance between two points of the shape provided.

**Usage**

```
coo_calliper(coo, arr.ind = FALSE)
```

**Arguments**

coo	a matrix of (x; y) coordinates or any Coo
arr.ind	logical, see below.

**Value**

numeric, the centroid size. If arr.ind=TRUE, a data\_frame.

**See Also**

Other coo\_ utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```

b <- bot[1]
coo_calliper(b)
p <- coo_calliper(b, arr.ind=TRUE)
p
p$length
ids <- p$arr_ind[[1]]
coo_plot(b)
segments(b[ids[1], 1], b[ids[1], 2], b[ids[2], 1], b[ids[2], 2], lty=2)

# on a Coo
bot %>%
coo_sample(32) %>% # for speed sake
coo_calliper()

bot %>%
coo_sample(32) %>% # for speed sake
coo_calliper(arr.ind=TRUE)

```

---

coo\_centdist

*Returns the distance between everypoints and the centroid*


---

**Description**

For every point of the shape, returns the (centroid-points) distance.

**Usage**

```
coo_centdist(coo)
```

**Arguments**

coo                    a matrix of (x; y) coordinates.

**Value**

a matrix of (x; y) coordinates.

**See Also**

Other centroid functions: [coo\\_centpos](#), [coo\\_centsize](#)

Other coo\_ utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
b <- coo_sample(bot[1], 64)
d <- coo_centdist(b)
barplot(d, xlab="Points along the outline", ylab="Distance to the centroid (pixels)")
```

---

coo\_center

*Centers coordinates*


---

**Description**

Returns a shape centered on the origin. The two functions are strictly equivalent.

**Usage**

```
coo_center(coo)
```

```
coo_centre(coo)
```

**Arguments**

coo                    matrix of (x; y) coordinates or any [Coo](#) object.

**Value**

a matrix of (x; y) coordinates, or a [Coo](#) object.

**See Also**

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
coo_plot(bot[1])
# same as
coo_plot(coo_centre(bot[1]))
# this
coo_plot(coo_center(bot[1]))
# on Coo objects
stack(bot)
stack(coo_center(bot))
```

---

coo_centpos	<i>Calculate centroid coordinates</i>
-------------	---------------------------------------

---

### Description

Returns the (x; y) centroid coordinates of a shape.

### Usage

```
coo_centpos(coo)
```

### Arguments

coo                   matrix of (x; y) coordinates or any [Coo](#) object.

### Value

(x; y) coordinates of the centroid as a vector or a matrix.

### See Also

Other centroid functions: [coo\\_centdist](#), [coo\\_centsize](#)

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

### Examples

```
b <- bot[1]
coo_plot(b)
xy <- coo_centpos(b)
points(xy[1], xy[2], cex=2, col='blue')
# on a Coo
coo_centpos(bot)
```

---

coo_centsize	<i>Calculates centroid size</i>
--------------	---------------------------------

---

**Description**

Calculates centroid size

**Usage**

```
coo_centsize(coo)
```

**Arguments**

coo                    matrix of (x; y) coordinates or any [Coo](#) object.

**Details**

This function can be used to integrate size - if meaningful - to Coo objects. See also [coo\\_length](#) and [rescale](#).

**Value**

numeric, the centroid size.

**See Also**

Other centroid functions: [coo\\_centdist](#), [coo\\_centpos](#)

**Examples**

```
coo_centsize(bot[1])  
# on a Coo  
coo_centsize(bot)  
# add it to $fac  
mutate(bot, size=coo_centsize(bot))
```

---

coo_check	<i>Checks shapes</i>
-----------	----------------------

---

**Description**

A simple utility, used internally, mostly in the coo functions and methods. Returns a matrix of coordinates, when passed with either a list or a matrix of coordinates.

**Usage**

```
coo_check(coo)
```

**Arguments**

coo                    matrix of (x; y) coordinates or any [Coo](#) object.

**Value**

matrix of (x; y) coordinates or a [Coo](#) object.

**Examples**

```
#coo_check('Not a shape')
#coo_check(iris)
#coo_check(matrix(1:10, ncol=2))
#coo_check(list(x=1:5, y=6:10))
```

---

coo_chull	<i>Calculates the (recursive) convex hull of a shape</i>
-----------	--

---

**Description**

coo\_chull returns the ids of points that define the convex hull of a shape. A simple wrapper around [chull](#), mainly used in graphical functions.

**Usage**

```
coo_chull(coo)

## Default S3 method:
coo_chull(coo)

## S3 method for class 'Coo'
coo_chull(coo)

coo_chull_onion(coo, close = TRUE)

## Default S3 method:
coo_chull_onion(coo, close = TRUE)

## S3 method for class 'Coo'
coo_chull_onion(coo, close = TRUE)
```

**Arguments**

coo                    a matrix of (x; y) coordinates or any [Coo](#).

close                 logical whether to close onion rings (TRUE by default)

**Details**

coo\_chull\_onion recursively find their convex hull, remove them, until less than 3 points are left.

**Value**

coo\_chull returns a matrix of points defining the convex hull of the shape; a list for Coe.  
 coo\_chull\_onion returns a list of successive onions rings, and a list of lists for Coe.

**See Also**

Other coo\_ descriptors: [coo\\_angle\\_edge1](#), [coo\\_angle\\_edges](#), [coo\\_angle\\_tangent](#), [coo\\_area](#), [coo\\_boundingbox](#), [coo\\_circularity](#), [coo\\_convexity](#), [coo\\_eccentricity](#), [coo\\_elongation](#), [coo\\_length](#), [coo\\_lw](#), [coo\\_rectangularity](#), [coo\\_rectilinearity](#), [coo\\_solidity](#), [coo\\_width](#)

**Examples**

```
# coo_chull
h <- coo_sample(hearts[4], 32)
coo_plot(h)
ch <- coo_chull(h)
lines(ch, col='red', lty=2)

bot %>% coo_chull

coo_chull_onion
x <- bot %>% efourier(6) %>% PCA
all_whisky_points <- x %>% as_df() %>% filter(type=="whisky") %>% select(PC1, PC2)
plot(x, ~type, eig=FALSE)
peeling_the_whisky_onion <- all_whisky_points %>% as.matrix %>% coo_chull_onion()
# you may need to par(xpd=NA) to ensure all segments
# even those outside the graphical window are drawn
peeling_the_whisky_onion$coo %>% lapply(coo_draw)
# simulated data
xy <- replicate(2, rnorm(50))
coo_plot(xy, poly=FALSE)
xy %>% coo_chull_onion() %>% lapply(polygons, col="#00000022")
```

---

 coo\_circularity

*Calculates the Haralick's circularity of a shape*


---

**Description**

coo\_circularity calculates the 'circularity measure'. Also called 'compactness' and 'shape factor' sometimes. coo\_circularityharalick calculates Haralick's circularity which is less sensible to digitalization noise than coo\_circularity. coo\_circularitynorm calculates 'circularity', also called compactness and shape factor, but normalized to the unit circle.



**Usage**

```

coo_circularity(coo)

## Default S3 method:
coo_circularity(coo)

## S3 method for class 'Coo'
coo_circularity(coo)

coo_circularityharalick(coo)

## Default S3 method:
coo_circularityharalick(coo)

## S3 method for class 'Coo'
coo_circularityharalick(coo)

coo_circularitynorm(coo)

## Default S3 method:
coo_circularitynorm(coo)

## S3 method for class 'Coo'
coo_circularitynorm(coo)

```

**Arguments**

`coo` a matrix of (x; y) coordinates or any Coo

**Value**

numeric for single shapes, list for Coo of the corresponding circularity measurement.

**Source**

Rosin PL. 2005. Computing global shape measures. Handbook of Pattern Recognition and Computer Vision. 177-196.

**See Also**

Other coo\_ descriptors: [coo\\_angle\\_edge1](#), [coo\\_angle\\_edges](#), [coo\\_angle\\_tangent](#), [coo\\_area](#), [coo\\_boundingbox](#), [coo\\_chull](#), [coo\\_convexity](#), [coo\\_eccentricity](#), [coo\\_elongation](#), [coo\\_length](#), [coo\\_lw](#), [coo\\_rectangularity](#), [coo\\_rectilinearity](#), [coo\\_solidity](#), [coo\\_width](#)

**Examples**

```

# coo_circularity
bot[1] %>% coo_circularity()

```

```

bot %>%
  slice(1:5) %>% # for speed sake only
  coo_circularity

# coo_circularityharalick
bot[1] %>% coo_circularityharalick()
bot %>%
  slice(1:5) %>% # for speed sake only
  coo_circularityharalick

# coo_circularitynorm
bot[1] %>% coo_circularitynorm()
bot %>%
  slice(1:5) %>% # for speed sake only
  coo_circularitynorm

```

---

coo_close	<i>Closes/uncloses shapes</i>
-----------	-------------------------------

---

## Description

Returns a closed shape from (un)closed shapes. See also [coo\\_unclose](#).

Returns a unclosed shape from (un)closed shapes. See also [coo\\_close](#).

## Usage

```
coo_close(coo)
```

```
coo_unclose(coo)
```

## Arguments

`coo` matrix of (x; y) coordinates or any [Coo](#) object.

## Value

a matrix of (x; y) coordinates, or a [Coo](#) object.

a matrix of (x; y) coordinates, or a [Coo](#) object.

## See Also

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#),

coo\_smooth, coo\_template, coo\_trans, coo\_trimbottom, coo\_trimtop, coo\_trim, coo\_up, is\_equallyspacedradii

Other coo\_ utilities: coo\_aligncalliper, coo\_alignminradius, coo\_alignxax, coo\_align, coo\_baseline, coo\_bookstein, coo\_boundingbox, coo\_calliper, coo\_centdist, coo\_center, coo\_centpos, coo\_down, coo\_dxy, coo\_extract, coo\_flipx, coo\_force2close, coo\_interpolate, coo\_is\_closed, coo\_jitter, coo\_left, coo\_likely\_clockwise, coo\_nb, coo\_perim, coo\_range, coo\_rev, coo\_right, coo\_rotatecenter, coo\_rotate, coo\_sample\_prop, coo\_samplerr, coo\_sample, coo\_scale, coo\_shearx, coo\_slice, coo\_slidedirection, coo\_slidegap, coo\_slide, coo\_smoothcurve, coo\_smooth, coo\_template, coo\_trans, coo\_trimbottom, coo\_trimtop, coo\_trim, coo\_up, is\_equallyspacedradii

### Examples

```
x <- (matrix(1:10, ncol=2))
x2 <- coo_close(x)
x3 <- coo_unclose(x2)
x
coo_is_closed(x)
x2
coo_is_closed(x2)
x3
coo_is_closed(x3)
x <- (matrix(1:10, ncol=2))
x2 <- coo_close(x)
x3 <- coo_unclose(x2)
x
coo_is_closed(x)
x2
coo_is_closed(x2)
x3
coo_is_closed(x3)
```

---

coo\_convexity

*Calculates the convexity of a shape*

---

### Description

Calculated using a ratio of the eigen values (inertia axis)

### Usage

```
coo_convexity(coo)
```

### Arguments

coo                    a matrix of (x; y) coordinates.

**Value**

numeric for a single shape, list for a Coo

**Source**

Rosin PL. 2005. Computing global shape measures. Handbook of Pattern Recognition and Computer Vision. 177-196.

**See Also**

Other coo\_ descriptors: [coo\\_angle\\_edge1](#), [coo\\_angle\\_edges](#), [coo\\_angle\\_tangent](#), [coo\\_area](#), [coo\\_boundingbox](#), [coo\\_chull](#), [coo\\_circularity](#), [coo\\_eccentricity](#), [coo\\_elongation](#), [coo\\_length](#), [coo\\_lw](#), [coo\\_rectangularity](#), [coo\\_rectilinearity](#), [coo\\_solidity](#), [coo\\_width](#)

**Examples**

```
coo_convexity(bot[1])
bot %>%
  slice(1:3) %>% # for speed sake only
  coo_convexity()
```

---

coo\_down

*coo\_down Retains coordinates with negative y-coordinates*

---

**Description**

Useful when shapes are aligned along the x-axis (e.g. because of a bilateral symmetry) and when one wants to retain just the lower side.

**Usage**

```
coo_down(coo, slidegap = FALSE)
```

**Arguments**

coo                   matrix of (x; y) coordinates or any [Coo](#) object.  
slidegap           logical whether to apply [coo\\_slidegap](#) after coo\_down

**Value**

a matrix of (x; y) coordinates or a [Coo](#) object ([Out](#) are returned as [Opn](#))

**Note**

When shapes are "sliced" along the x-axis, it usually results on open curves and thus to huge/artefactual gaps between points neighboring this axis. This is usually solved with [coo\\_slidegap](#). See examples there.

Also, when apply a [coo\\_left/right/up/down](#) on an [Out](#) object, you then obtain an [Opn](#) object, which is done automatically.

**See Also**

Other opening functions: [coo\\_left](#), [coo\\_right](#), [coo\\_up](#)

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trintop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
b <- coo_alignxax(bot[1])
coo_plot(b)
coo_draw(coo_down(b), border='red')
```

---

coo\_draw

*Adds a shape to the current plot*

---

**Description**

`coo_draw` is simply a [coo\\_plot](#) with `plot.new=FALSE`, ie that adds a shape on the active plot.

**Usage**

```
coo_draw(coo, ...)
```

**Arguments**

`coo` a list or a matrix of coordinates.  
`...` optional parameters for [coo\\_plot](#)

**See Also**

Other plotting functions: [coo\\_arrows](#), [coo\\_listpanel](#), [coo\\_lolli](#), [coo\\_plot](#), [coo\\_ruban](#), [ldk\\_chull](#), [ldk\\_confell](#), [ldk\\_contour](#), [ldk\\_labels](#), [ldk\\_links](#), [plot\\_devsegments](#), [plot\\_table](#)

**Examples**

```
b1 <- bot[4]
b2 <- bot[5]
coo_plot(b1)
coo_draw(b2, border='red') # all coo_plot arguments will work for coo_draw
```

---

coo\_draw\_rads                      *Draw radii to the current plot*

---

### Description

Given a shape, all centroid-points radii are drawn using [segments](#) that can be passed with options

### Usage

```
coo_draw_rads(coo, ...)
```

### Arguments

coo	a shape
...	arguments to feed <a href="#">segments</a>

### Examples

```
shp <- shapes[4] %>% coo_sample(24) %T>% coo_plot  
coo_draw_rads(shp, col=col_summer(24))
```

---

coo\_dxy                              *Calculate abscissa and ordinate on a shape*

---

### Description

A simple wrapper to calculate dxi - dx1 and dyi - dx1.

### Usage

```
coo_dxy(coo)
```

### Arguments

coo	a matrix (or a list) of (x; y) coordinates or any Coo
-----	---

### Value

a data.frame with two components dx and dy for single shapes or a list of such data.frames for Coo

**See Also**

Other coo\_ utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
coo_dxy(coo_sample(bot[1], 12))

bot %>%
  slice(1:5) %>% coo_sample(12) %>% # for readability and speed only
  coo_dxy()
```

---

coo_eccentricity	<i>Calculates the eccentricity of a shape</i>
------------------	---

---

**Description**

`coo_eccentricityeigen` uses the ratio of the eigen values (inertia axes of coordinates). `coo_eccentricityboundingbox` uses the width/length ratio (see [coo\\_lw](#)).

**Usage**

```
coo_eccentricityeigen(coo)

## Default S3 method:
coo_eccentricityeigen(coo)

## S3 method for class 'Coo'
coo_eccentricityeigen(coo)

coo_eccentricityboundingbox(coo)

## Default S3 method:
coo_eccentricityboundingbox(coo)

## S3 method for class 'Coo'
coo_eccentricityboundingbox(coo)
```

**Arguments**

`coo` a matrix of (x; y) coordinates or any `Coo`

**Value**

numeric for single shapes, list for Coos.

**Source**

Rosin PL. 2005. Computing global shape measures. Handbook of Pattern Recognition and Computer Vision. 177-196.

**See Also**

[coo\\_eccentricityboundingbox](#)

Other coo\_ descriptors: [coo\\_angle\\_edge1](#), [coo\\_angle\\_edges](#), [coo\\_angle\\_tangent](#), [coo\\_area](#), [coo\\_boundingbox](#), [coo\\_chull](#), [coo\\_circularity](#), [coo\\_convexity](#), [coo\\_elongation](#), [coo\\_length](#), [coo\\_lw](#), [coo\\_rectangularity](#), [coo\\_rectilinearity](#), [coo\\_solidity](#), [coo\\_width](#)

**Examples**

```
# coo_eccentricityeigen
bot[1] %>% coo_eccentricityeigen()
bot %>%
  slice(1:3) %>% # for speed sake only
  coo_eccentricityeigen()

# coo_eccentricityboundingbox
bot[1] %>% coo_eccentricityboundingbox()
bot %>%
  slice(1:3) %>% # for speed sake only
  coo_eccentricityboundingbox()
```

---

coo_elongation	<i>Calculates the elongation of a shape</i>
----------------	---

---

**Description**

Calculates the elongation of a shape

**Usage**

```
coo_elongation(coo)
```

**Arguments**

coo                    a matrix of (x; y) coordinates.

**Value**

numeric, the eccentricity of the bounding box



**Source**

Rosin PL. 2005. Computing global shape measures. Handbook of Pattern Recognition and Computer Vision. 177-196.

**See Also**

Other coo\_ descriptors: [coo\\_angle\\_edge1](#), [coo\\_angle\\_edges](#), [coo\\_angle\\_tangent](#), [coo\\_area](#), [coo\\_boundingbox](#), [coo\\_chull](#), [coo\\_circularity](#), [coo\\_convexity](#), [coo\\_eccentricity](#), [coo\\_length](#), [coo\\_lw](#), [coo\\_rectangularity](#), [coo\\_rectilinearity](#), [coo\\_solidity](#), [coo\\_width](#)

**Examples**

```
coo_elongation(bot[1])
# on Coo
# for speed sake
bot %>% slice(1:3) %>% coo_elongation
```

---

coo\_extract

*Extract coordinates from a shape*


---

**Description**

Extract ids coordinates from a single shape or a Coo object.

**Usage**

```
coo_extract(coo, ids)
```

**Arguments**

coo            either a matrix of (x; y) coordinates or a [Coo](#) object.  
ids            integer, the ids of points to sample.

**Details**

It probably only make sense for Coo objects with the same number of coordinates and them being homologous, typically on Ldk.

**Value**

a matrix of (x; y) coordinates, or a [Coo](#) object.

**See Also**

Other sampling functions: [coo\\_interpolate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#)

Other coo\_ utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
b <- bot[1]
stack(bot)
stack(coo_sample(bot, 24))
coo_plot(b)
coo_plot(coo_sample(b, 24))
coo_extract(bot[1], c(3, 9, 12)) # or :
bot[1] %>% coo_extract(c(3, 9, 12))

coo_extract(bot, c(3, 5, 7))
```

---

coo\_flipx

*Flips shapes*


---

**Description**

coo\_flipx flips shapes about the x-axis; coo\_flipy about the y-axis.

**Usage**

```
coo_flipx(coo)
```

```
coo_flipy(coo)
```

**Arguments**

coo                    matrix of (x; y) coordinates or any [Coo](#) object.

**Value**

a matrix of (x; y) coordinates

**See Also**

Other transforming functions: [coo\\_shearx](#)

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
cat <- shapes[4]
cat <- coo_center(cat)
coo_plot(cat)
coo_draw(coo_flipx(cat), border="red")
coo_draw(coo_flipy(cat), border="blue")

#' # to flip an entire Coo:
shapes2 <- shapes
shapes2$coo <- lapply(shapes2$coo, coo_flipx)
```

---

coo_force2close	<i>Forces shapes to close</i>
-----------------	-------------------------------

---

**Description**

An exotic function that distribute the distance between the first and the last points of unclosed shapes, so that they become closed. May be useful (?) e.g. for `t/rfourier` methods where reconstructed shapes may not be closed.

**Usage**

```
coo_force2close(coo)
```

**Arguments**

`coo` matrix of (x; y) coordinates or any [Coo](#) object.

**Value**

a matrix of (x; y) coordinates, or a [Coo](#) object.

**See Also**

Other coo\_ utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
b <- coo_sample(bot[1], 64)
b <- b[1:40,]
coo_plot(b)
coo_draw(coo_force2close(b), border='red')
```

---

coo_interpolate	<i>Interpolates coordinates</i>
-----------------	---------------------------------

---

**Description**

Interpolates n coordinates 'among existing points' between existing points, along the perimeter of the coordinates provided and keeping the first point

**Usage**

```
coo_interpolate(coo, n)
```

**Arguments**

coo	matrix of (x; y) coordinates or any <a href="#">Coo</a> object.
n	codeinteger, the number fo points to interpolate.

**Value**

a matrix of (x; y) coordinates, or a [Coo](#) object.

**See Also**

Other sampling functions: [coo\\_extract](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#)

Other coo\_ utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```

b <- bot[1]
stack(bot)
stack(coo_scale(bot))
coo_plot(b)
coo_plot(coo_scale(b))
stack(bot)
stack(coo_interpolate(coo_sample(bot, 12), 120))
coo_plot(bot[1])
coo_plot(coo_interpolate(coo_sample(bot[1], 12), 120))

```

---

coo_intersect_angle	<i>Nearest intersection between a shape and a segment specified with an angle</i>
---------------------	---

---

**Description**

Take a shape, and segment starting on the centroid and having a particular angle, which point is the nearest where the segment intersects with the shape?

**Usage**

```

coo_intersect_angle(coo, angle = 0)

coo_intersect_direction(coo, direction = c("down", "left", "up", "right")[4])

## Default S3 method:
coo_intersect_direction(coo, direction = c("down", "left",
  "up", "right")[4])

## S3 method for class 'Coo'
coo_intersect_direction(coo, direction = c("down", "left", "up",
  "right")[4])

```

**Arguments**

coo	matrix of (x; y) coordinates or any <a href="#">Coo</a> object.
angle	numeric an angle in radians (0 by default).
direction	character one of "down", "left", "up", "right" ("right" by default)

**Value**

numeric the id of the nearest point or a list for Coo See examples.

**Note**

shapes are always centered before this operation. If you need a simple direction such as (down, left, up, right)ward, then use [coo\\_intersect\\_direction](#) which does not need to find an intersection but relies on coordinates and is about 1000.

**See Also**

Other coo\_ intersect: [coo\\_intersect\\_segment](#)

**Examples**

```

coo <- bot[1] %>% coo_center %>% coo_scale
coo_plot(coo)
coo %>% coo_intersect_angle(pi/7) %>%
  coo[., , drop=FALSE] %>% points(col="red")

# many angles
coo_plot(coo)
sapply(seq(0, pi, pi/12),
  function(x) coo %>% coo_intersect_angle(x)) -> ids
coo[ids, ] %>% points(col="blue")

coo %>%
  coo_intersect_direction("down") %>%
  coo[., , drop=FALSE] %>% points(col="orange")

```

---

coo\_intersect\_segment *Nearest intersection between a shape and a segment*

---

**Description**

Take a shape, and an intersecting segment, which point is the nearest of where the segment intersects with the shape? Most of the time, centering before makes more sense.

**Usage**

```
coo_intersect_segment(coo, seg, center = TRUE)
```

**Arguments**

coo	matrix of (x; y) coordinates or any <a href="#">Coo</a> object.
seg	a 2x2 matrix defining the starting and ending points; or a list or a numeric of length 4.
center	logical whether to center the shape (TRUE by default)

**Value**

numeric the id of the nearest point, a list for Coo. See examples.

**See Also**

Other coo\_ intersect: [coo\\_intersect\\_angle](#)

**Examples**

```

coo <- bot[1] %>% coo_center %>% coo_scale
seg <- c(0, 0, 2, 2) # passed as a numeric of length(4)
coo_plot(coo)
segments(seg[1], seg[2], seg[3], seg[4])
coo %>% coo_intersect_segment(seg) %T>% print %>%
# prints on the console and draw it
  coo[., , drop=FALSE] %>% points(col="red")

# on Coo
bot %>%
  slice(1:3) %>% # for the sake of speed
  coo_center %>%
  coo_intersect_segment(matrix(c(0, 0, 1000, 1000), ncol=2, byrow=TRUE))

```

---

coo_is_closed	<i>Test if shapes are closed</i>
---------------	----------------------------------

---

**Description**

Returns TRUE/FALSE whether the last coordinate of the shapes is the same as the first one.

**Usage**

```
coo_is_closed(coo)
```

```
is_open(coo)
```

**Arguments**

coo                    matrix of (x; y) coordinates or any [Coo](#) object.

**Value**

a single or a vector of logical.

**See Also**

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```

coo_is_closed(matrix(1:10, ncol=2))
coo_is_closed(coo_close(matrix(1:10, ncol=2)))
coo_is_closed(bot)
coo_is_closed(coo_close(bot))

```

---

coo\_jitter

*Jitters shapes*


---

**Description**

A simple wrapper around [jitter](#).

**Usage**

```
coo_jitter(coo, ...)
```

**Arguments**

```

coo          matrix of (x; y) coordinates or any Coo object.
...          additional parameter for jitter

```

**Value**

a matrix of (x; y) coordinates or a [Coo](#) object

**See Also**

[get\\_pairs](#)

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```

b <-bot[1]
coo_plot(b, zoom=0.2)
coo_draw(coo_jitter(b, amount=3), border="red")

# for a Coo example, see \link{get\_pairs}

```



---

coo_ldk	<i>Defines landmarks interactively</i>
---------	--

---

**Description**

Allows to interactively define a `nb.ldk` number of landmarks on a shape. Used in other facilities to acquire/manipulate data.

**Usage**

```
coo_ldk(coo, nb.ldk)
```

**Arguments**

coo	a matrix or a list of (x; y) coordinates.
nb.ldk	integer, the number of landmarks to define

**Value**

numeric that corresponds to the closest ids, on the shape, from clicked points.

**Examples**

```
## Not run:  
b <- bot[1]  
coo_ldk(b, 3) # run this, and click 3 times  
coo_ldk(bot, 2) # this also works on Out  
  
## End(Not run)
```

---

coo_left	<i>Retains coordinates with negative x-coordinates</i>
----------	--

---

**Description**

Useful when shapes are aligned along the y-axis (e.g. because of a bilateral symmetry) and when one wants to retain just the lower side.

**Usage**

```
coo_left(coo, slidegap = FALSE)
```

**Arguments**

coo	matrix of (x; y) coordinates or any <a href="#">Coo</a> object.
slidegap	logical whether to apply <a href="#">coo_slidegap</a> after <code>coo_left</code>

**Value**

a matrix of (x; y) coordinates or a [Coo](#) object ([Out](#) are returned as [Opn](#))

**Note**

When shapes are "sliced" along the y-axis, it usually results on open curves and thus to huge/artefactual gaps between points neighboring this axis. This is usually solved with [coo\\_slidegap](#). See examples there.

Also, when apply a [coo\\_left/right/up/down](#) on an [Out](#) object, you then obtain an [Opn](#) object, which is done automatically.

**See Also**

Other opening functions: [coo\\_down](#), [coo\\_right](#), [coo\\_up](#)

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignnax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
b <- coo_center(bot[1])
coo_plot(b)
coo_draw(coo_left(b), border='red')
```

---

coo\_length

*Calculates the length of a shape*

---

**Description**

Nothing more than `coo_lw(coo)[1]`.

**Usage**

```
coo_length(coo)
```

**Arguments**

`coo` a matrix of (x; y) coordinates or a [Coo](#) object

**Details**

This function can be used to integrate size - if meaningful - to [Coo](#) objects. See also [coo\\_centsize](#) and [rescale](#).

**Value**

the length (in pixels) of the shape

**See Also**

[coo\\_lw](#), [coo\\_width](#)

Other coo\_ descriptors: [coo\\_angle\\_edge1](#), [coo\\_angle\\_edges](#), [coo\\_angle\\_tangent](#), [coo\\_area](#), [coo\\_boundingbox](#), [coo\\_chull](#), [coo\\_circularity](#), [coo\\_convexity](#), [coo\\_eccentricity](#), [coo\\_elongation](#), [coo\\_lw](#), [coo\\_rectangularity](#), [coo\\_rectilinearity](#), [coo\\_solidity](#), [coo\\_width](#)

**Examples**

```
coo_length(bot[1])
coo_length(bot)
mutate(bot, size=coo_length(bot))
```

---

`coo_likely_clockwise` Tests if shapes are (likely) developing clockwise or anticlockwise

---

**Description**

Tests if shapes are (likely) developing clockwise or anticlockwise

**Usage**

```
coo_likely_clockwise(coo)

## Default S3 method:
coo_likely_clockwise(coo)

## S3 method for class 'Coo'
coo_likely_clockwise(coo)

coo_likely_anticlockwise(coo)
```

**Arguments**

`coo` matrix of (x; y) coordinates or any [Coo](#) object.

**Value**

a single or a vector of logical.

**See Also**

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
shapes[4] %>% coo_sample(64) %>% coo_plot() #clockwise cat
shapes[4] %>% coo_likely_clockwise()
shapes[4] %>% coo_rev() %>% coo_likely_clockwise()

# on Coo
shapes %>% coo_likely_clockwise %>% `[`(4)
```

---

 coo\_listpanel

*Plots sets of shapes.*


---

**Description**

`coo_listpanel` plots a list of shapes if passed with a list of coordinates. Mainly used by [panel.Coo](#) functions. If used outside the latter, shapes must be "templated", see [coo\\_template](#). If you want to reorder shapes according to a factor, use [arrange](#).

**Usage**

```
coo_listpanel(coo.list, dim, byrow = TRUE, fromtop = TRUE, cols, borders,
  poly = TRUE, points = FALSE, points.pch = 3, points.cex = 0.2,
  points.col = "#333333", ...)
```

**Arguments**

<code>coo.list</code>	A list of coordinates
<code>dim</code>	A vector of the form (nb.row, nb.cols) to specify the panel display. If missing, shapes are arranged in a square.
<code>byrow</code>	logical. Whether to draw successive shape by row or by col.
<code>fromtop</code>	logical. Whether to display shapes from the top of the plotting region.
<code>cols</code>	A vector of colors to fill shapes.
<code>borders</code>	A vector of colors to draw shape borders.
<code>poly</code>	logical whether to use polygon or lines to draw shapes. mainly for use for out-lines and open outlines.

points	logical if poly is set to FALSE whether to add points
points.pch	if points is TRUE, a pch for these points
points.cex	if points is TRUE, a cex for these points
points.col	if points is TRUE, a col for these points
...	additional arguments to feed generic plot

**Value**

Returns (invisibly) a data.frame with position of shapes that can be used for other sophisticated plotting design.

**See Also**

Other plotting functions: [coo\\_arrows](#), [coo\\_draw](#), [coo\\_lolli](#), [coo\\_plot](#), [coo\\_ruban](#), [ldk\\_chull](#), [ldk\\_confell](#), [ldk\\_contour](#), [ldk\\_labels](#), [ldk\\_links](#), [plot\\_devsegments](#), [plot\\_table](#)

**Examples**

```
coo_listpanel(bot$coo) # equivalent to panel(bot)
```

---

coo_lolli	<i>Plots (lollipop) differences between two configurations</i>
-----------	--

---

**Description**

Draws 'lollipops' between two configurations.

**Usage**

```
coo_lolli(coo1, coo2, pch = NA, cex = 0.5, ...)
```

**Arguments**

coo1	A list or a matrix of coordinates.
coo2	A list or a matrix of coordinates.
pch	a pch for the points (default to NA)
cex	a cex for the points
...	optional parameters to fed <a href="#">points</a> and <a href="#">segments</a> .

**See Also**

Other plotting functions: [coo\\_arrows](#), [coo\\_draw](#), [coo\\_listpanel](#), [coo\\_plot](#), [coo\\_ruban](#), [ldk\\_chull](#), [ldk\\_confell](#), [ldk\\_contour](#), [ldk\\_labels](#), [ldk\\_links](#), [plot\\_devsegments](#), [plot\\_table](#)

**Examples**

```
coo_lolli(coo_sample(olea[3], 50), coo_sample(olea[6], 50))
title("A nice title !")
```

---

coo_lw	<i>Calculates length and width of a shape</i>
--------	---

---

**Description**

Returns the length and width of a shape based on their inertia axis i.e. alignment to the x-axis. The length is defined as the range along the x-axis; the width as the range on the y-axis.

**Usage**

```
coo_lw(coo)
```

**Arguments**

coo                    a matrix of (x; y) coordinates or Coo object

**Value**

a vector of two numeric: the length and the width.

**See Also**

[coo\\_length](#), [coo\\_width](#).

Other coo\_ descriptors: [coo\\_angle\\_edge1](#), [coo\\_angle\\_edges](#), [coo\\_angle\\_tangent](#), [coo\\_area](#), [coo\\_boundingbox](#), [coo\\_chull](#), [coo\\_circularity](#), [coo\\_convexity](#), [coo\\_eccentricity](#), [coo\\_elongation](#), [coo\\_length](#), [coo\\_rectangularity](#), [coo\\_rectilinearity](#), [coo\\_solidity](#), [coo\\_width](#)

**Examples**

```
coo_lw(bot[1])
```

---

coo_nb	<i>Counts coordinates</i>
--------	---------------------------

---

**Description**

Returns the number of coordinates, for a single shape or a Coo object

**Usage**

```
coo_nb(coo)
```

**Arguments**

coo                    matrix of (x; y) coordinates or any [Coo](#) object.

**Value**

either a single numeric or a vector of numeric

**See Also**

Other coo\_ utilities: `coo_aligncalliper`, `coo_alignminradius`, `coo_alignxax`, `coo_align`, `coo_baseline`, `coo_bookstein`, `coo_boundingbox`, `coo_calliper`, `coo_centdist`, `coo_center`, `coo_centpos`, `coo_close`, `coo_down`, `coo_dxy`, `coo_extract`, `coo_flipx`, `coo_force2close`, `coo_interpolate`, `coo_is_closed`, `coo_jitter`, `coo_left`, `coo_likely_clockwise`, `coo_perim`, `coo_range`, `coo_rev`, `coo_right`, `coo_rotatecenter`, `coo_rotate`, `coo_sample_prop`, `coo_samplerr`, `coo_sample`, `coo_scale`, `coo_shearx`, `coo_slice`, `coo_slidedirection`, `coo_slidegap`, `coo_slide`, `coo_smoothcurve`, `coo_smooth`, `coo_template`, `coo_trans`, `coo_trimbottom`, `coo_trimtop`, `coo_trim`, `coo_up`, `is_equallyspacedradii`

**Examples**

```
# single shape
coo_nb(bot[1])
# Coo object
coo_nb(bot)
```

---

coo\_oscillo

*Momocs' 'oscilloscope' for Fourier-based approaches*

---

**Description**

Shape analysis deals with curve fitting, whether  $x(t)$  and  $y(t)$  positions along the curvilinear abscissa and/or radius/tangent angle variation. These functions are mainly intended for (self-)teaching of Fourier-based methods.

**Usage**

```
coo_oscillo(coo, method = c("efourier", "rfourier", "tfourier", "all")[4],
  shape = TRUE, nb.pts = 12)
```

**Arguments**

coo	A list or a matrix of coordinates.
method	character among <code>c('efourier', 'rfourier', 'tfourier', 'all')</code> . 'all' by default
shape	logical whether to plot the original shape
nb.pts	integer. The number or reference points, sampled equidistantly along the curvilinear abscissa and added on the oscillo curves.

**Value**

the plotted values

**See Also**

exemplifying functions

**Examples**

```
coo_oscillo(shapes[4])
coo_oscillo(shapes[4], 'efourier')
coo_oscillo(shapes[4], 'rfourier')
coo_oscillo(shapes[4], 'tfourier')
#tfourier is prone to high-frequency noise but smoothing can help
coo_oscillo(coo_smooth(shapes[4], 10), 'tfourier')
```

---

coo\_perim

*Calculates perimeter and variations*

---

**Description**

coo\_perim calculates the perimeter; coo\_perimpts calculates the euclidean distance between every points of a shape; coo\_perimcum does the same and calculates and cumulative sum.

**Usage**

```
coo_perimpts(coo)

## Default S3 method:
coo_perimpts(coo)

## S3 method for class 'Coo'
coo_perimpts(coo)

coo_perimcum(coo)

## Default S3 method:
coo_perimcum(coo)

## S3 method for class 'Coo'
coo_perimcum(coo)

coo_perim(coo)

## Default S3 method:
coo_perim(coo)

## S3 method for class 'Coo'
coo_perim(coo)
```



**Arguments**

coo                    matrix of (x; y) coordinates or any Coo

**Value**

numeric the distance between every point or a list of those.

**See Also**

Other coo\_ utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
# for speed sake
b1 <- coo_sample(bot[1], 12)
b5 <- bot %>% slice(1:5) %>% coo_sample(12)

# coo_perim
coo_perim(b1)
coo_perim(b5)

# coo_perimpts
coo_perimpts(b1)
b5 %>% coo_perimpts()

# coo_perimcum
b1 %>% coo_perimcum()
b5 %>% coo_perimcum()
```

---

coo\_plot

*Plots a single shape*


---

**Description**

A simple wrapper around [plot](#) for plotting shapes. Widely used in Momocs in other graphical functions, in methods, etc.

**Usage**

```

coo_plot(coo, ...)

## Default S3 method:
coo_plot(coo, xlim, ylim, border = "#333333", col = NA,
  lwd = 1, lty = 1, points = FALSE, first.point = TRUE,
  centroid = TRUE, xy.axis = TRUE, pch = 1, cex = 0.5, main = NA,
  poly = TRUE, plot.new = TRUE, plot = TRUE, zoom = 1, ...)

ldk_plot(coo, ...)

```

**Arguments**

coo	A list or a matrix of coordinates.
...	further arguments for use in coo_plot methods. See examples.
xlim	If coo_plot is called and coo is missing, then a vector of length 2 specifying the xlim of the plotting area.
ylim	If coo_plot is called and coo is missing, then a vector of length 2 specifying the ylim of the plotting area.
border	A color for the shape border.
col	A color to fill the shape polygon.
lwd	The lwd for drawing shapes.
lty	The lty for drawing shapes.
points	logical. Whether to display points. If missing and number of points is < 100, then points are plotted.
first.point	logical whether to plot or not the first point.
centroid	logical. Whether to display centroid.
xy.axis	logical. Whether to draw the xy axis.
pch	The pch for points.
cex	The cex for points.
main	character. A title for the plot.
poly	logical whether to use <a href="#">polygon</a> and <a href="#">lines</a> to draw the shape, or just <a href="#">points</a> . In other words, whether the shape should be considered as a configuration of landmarks or not (eg a closed outline).
plot.new	logical whether to plot or not a new frame.
plot	logical whether to plot something or just to create an empty plot.
zoom	a numeric to take your distances.

**Value**

No returned value.

**See Also**

Other plotting functions: [coo\\_arrows](#), [coo\\_draw](#), [coo\\_listpanel](#), [coo\\_lolli](#), [coo\\_ruban](#), [ldk\\_chull](#), [ldk\\_confell](#), [ldk\\_contour](#), [ldk\\_labels](#), [ldk\\_links](#), [plot\\_devsegments](#), [plot\\_table](#)

**Examples**

```
b <- bot[1]
coo_plot(b)
coo_plot(bot[2], plot.new=FALSE) # equivalent to coo_draw(bot[2])
coo_plot(b, zoom=2)
coo_plot(b, border='blue')
coo_plot(b, first.point=FALSE, centroid=FALSE)
coo_plot(b, points=TRUE, pch=20)
coo_plot(b, xy.axis=FALSE, lwd=2, col='#F2F2F2')
```

---

coo\_range

*Calculate coordinates range*


---

**Description**

coo\_range simply returns the range, coo\_range\_enlarge enlarges it by a k proportion. coo\_diffrange return the amplitude (ie diff after coo\_range)

**Usage**

```
coo_range(coo)

## Default S3 method:
coo_range(coo)

## S3 method for class 'Coo'
coo_range(coo)

coo_range_enlarge(coo, k)

## Default S3 method:
coo_range_enlarge(coo, k = 0)

## S3 method for class 'Coo'
coo_range_enlarge(coo, k = 0)

## S3 method for class 'list'
coo_range_enlarge(coo, k = 0)

coo_diffrange(coo)

## Default S3 method:
```

```

coo_diffrange(coo)

## S3 method for class 'Coo'
coo_diffrange(coo)

## S3 method for class 'list'
coo_diffrange(coo)

```

### Arguments

coo                    matrix of (x; y) coordinates or any **Coo** object.  
k                        numeric proportion by which to enlarge it

### Value

a matrix of range such as (min, max) x (x, y)

### See Also

Other `coo_` utilities: `coo_aligncalliper`, `coo_alignminradius`, `coo_alignxax`, `coo_align`, `coo_baseline`, `coo_bookstein`, `coo_boundingbox`, `coo_calliper`, `coo_centdist`, `coo_center`, `coo_centpos`, `coo_close`, `coo_down`, `coo_dxy`, `coo_extract`, `coo_flipx`, `coo_force2close`, `coo_interpolate`, `coo_is_closed`, `coo_jitter`, `coo_left`, `coo_likely_clockwise`, `coo_nb`, `coo_perim`, `coo_rev`, `coo_right`, `coo_rotatecenter`, `coo_rotate`, `coo_sample_prop`, `coo_samlerr`, `coo_sample`, `coo_scale`, `coo_shearx`, `coo_slice`, `coo_slidedirection`, `coo_slidegap`, `coo_slide`, `coo_smoothcurve`, `coo_smooth`, `coo_template`, `coo_trans`, `coo_trimbottom`, `coo_trimtop`, `coo_trim`, `coo_up`, `is_equallyspacedradii`

### Examples

```

bot[1] %>% coo_range # single shape
bot    %>% coo_range # Coo object

bot[1] %>% coo_range_enlarge(1/50) # single shape
bot    %>% coo_range_enlarge(1/50) # Coo object

```

---

`coo_rectangularity`      *Calculates the rectangularity of a shape*

---

### Description

Calculates the rectangularity of a shape

### Usage

```
coo_rectangularity(coo)
```

**Arguments**

coo                    a matrix of (x; y) coordinates or any Coo

**Value**

numeric for a single shape, list for Coo

**Source**

Rosin PL. 2005. Computing global shape measures. Handbook of Pattern Recognition and Computer Vision. 177-196.

**See Also**

Other coo\_ descriptors: [coo\\_angle\\_edge1](#), [coo\\_angle\\_edges](#), [coo\\_angle\\_tangent](#), [coo\\_area](#), [coo\\_boundingbox](#), [coo\\_chull](#), [coo\\_circularity](#), [coo\\_convexity](#), [coo\\_eccentricity](#), [coo\\_elongation](#), [coo\\_length](#), [coo\\_lw](#), [coo\\_rectilinearity](#), [coo\\_solidity](#), [coo\\_width](#)

**Examples**

```
coo_rectangularity(bot[1])

bot %>%
  slice(1:3) %>% # for speed sake only
  coo_rectangularity
```

---

coo\_rectilinearity      *Calculates the rectilinearity of a shape*

---

**Description**

As proposed by Zunic and Rosin (see below). May need some testing/review.

**Usage**

```
coo_rectilinearity(coo)
```

**Arguments**

coo                    a matrix of (x; y) coordinates or any Coo

**Value**

numeric for a single shape, list for Coo

**Note**

due to the laborious nature of the algorithm (in nb.pts^2), and of its implementation, it may be very long to compute.

**Source**

Zunic J, Rosin PL. 2003. Rectilinearity measurements for polygons. IEEE Transactions on Pattern Analysis and Machine Intelligence 25: 1193-1200.

**See Also**

Other coo\_ descriptors: [coo\\_angle\\_edge1](#), [coo\\_angle\\_edges](#), [coo\\_angle\\_tangent](#), [coo\\_area](#), [coo\\_boundingbox](#), [coo\\_chull](#), [coo\\_circularity](#), [coo\\_convexity](#), [coo\\_eccentricity](#), [coo\\_elongation](#), [coo\\_length](#), [coo\\_lw](#), [coo\\_rectangularity](#), [coo\\_solidity](#), [coo\\_width](#)

**Examples**

```
bot[1] %>%
  coo_sample(32) %>% # for speed sake only
  coo_rectilinearity

bot %>%
  slice(1:3) %>% coo_sample(32) %>% # for speed sake only
  coo_rectilinearity
```

---

 coo\_rev

*Reverses coordinates*


---

**Description**

Returns the reverse suite of coordinates, i.e. change shape's orientation

**Usage**

```
coo_rev(coo)
```

**Arguments**

coo                    matrix of (x; y) coordinates or any [Coo](#) object.

**Value**

a matrix of (x; y) coordinates or a [Coo](#) object

**See Also**

Other coo\_ utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerrr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_allyspacedradii](#)

**Examples**

```
b <- coo_sample(bot[1], 4)
b
coo_rev(b)
```

---

coo\_right

*Retains coordinates with positive x-coordinates*


---

**Description**

Useful when shapes are aligned along the y-axis (e.g. because of a bilateral symmetry) and when one wants to retain just the upper side.

**Usage**

```
coo_right(coo, slidegap = FALSE)
```

**Arguments**

coo                   matrix of (x; y) coordinates or any [Coo](#) object.  
slidegap              logical whether to apply [coo\\_slidegap](#) after [coo\\_right](#)

**Value**

a matrix of (x; y) coordinates or a [Coo](#) object ([Out](#) are returned as [Opn](#))

**Note**

When shapes are "sliced" along the y-axis, it usually results on open curves and thus to huge/artefactual gaps between points neighboring this axis. This is usually solved with [coo\\_slidegap](#). See examples there.

Also, when apply a [coo\\_left/right/up/down](#) on an [Out](#) object, you then obtain an [Opn](#) object, which is done automatically.

**See Also**

Other opening functions: [coo\\_down](#), [coo\\_left](#), [coo\\_up](#)

Other [coo\\_](#) utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
b <- coo_center(bot[1])
coo_plot(b)
coo_draw(coo_right(b), border='red')
```

---

coo\_rotate

*Rotates coordinates*


---

**Description**

Rotates the coordinates by a 'theta' angle (in radians) in the trigonometric direction (anti-clockwise). If not provided, assumed to be the centroid size. It involves three steps: centering from current position, dividing coordinates by 'scale', translating to the original position.

**Usage**

```
coo_rotate(coo, theta = 0)
```

**Arguments**

coo                    either a matrix of (x; y) coordinates, or any [Coo](#) object.  
theta                  numericthe angle (in radians) to rotate shapes.

**Value**

a matrix of (x; y) coordinates, or a [Coo](#) object.

**See Also**

Other coo\_ utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_allyspacedradii](#)

Other rotation functions: [coo\\_rotatecenter](#)

**Examples**

```
coo_plot(bot[1])
coo_plot(coo_rotate(bot[1], pi/2))
# on Coo
stack(bot)
stack(coo_rotate(bot, pi/2))
```



---

coo_rotatecenter	<i>Rotates shapes with a custom center</i>
------------------	--

---

### Description

rotates a shape of 'theta' angles (in radians) and with a (x; y) 'center'.

### Usage

```
coo_rotatecenter(coo, theta, center = c(0, 0))
```

### Arguments

coo	matrix of (x; y) coordinates or any <a href="#">Coo</a> object.
theta	numeric the angle (in radians) to rotate shapes.
center	numeric the (x; y) position of the center

### Value

a matrix of (x; y) coordinates, or a [Coo](#) object.

### See Also

Other rotation functions: [coo\\_rotate](#)

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

Other rotation functions: [coo\\_rotate](#)

### Examples

```
b <- bot[1]
coo_plot(b)
coo_draw(coo_rotatecenter(b, -pi/2, c(200, 200)), border='red')
```

---

coo_ruban	<i>Plots differences as (colored) segments aka a ruban</i>
-----------	--

---

### Description

Useful to display differences between shapes

### Usage

```
coo_ruban(coo, dev, palette = col_heat, normalize = TRUE, ...)
```

### Arguments

coo	a shape, typically a mean shape
dev	numeric a vector of distances or anything relevant
palette	the color palette to use or any palette
normalize	logical whether to normalize (TRUE by default) distances
...	other parameters to feed segments, eg lwd (see examples)

### Value

nothing

### See Also

Other plotting functions: [coo\\_arrows](#), [coo\\_draw](#), [coo\\_listpanel](#), [coo\\_lolli](#), [coo\\_plot](#), [ldk\\_chull](#), [ldk\\_confell](#), [ldk\\_contour](#), [ldk\\_labels](#), [ldk\\_links](#), [plot\\_devsegments](#), [plot\\_table](#)

Other plotting functions: [coo\\_arrows](#), [coo\\_draw](#), [coo\\_listpanel](#), [coo\\_lolli](#), [coo\\_plot](#), [ldk\\_chull](#), [ldk\\_confell](#), [ldk\\_contour](#), [ldk\\_labels](#), [ldk\\_links](#), [plot\\_devsegments](#), [plot\\_table](#)

### Examples

```
ms <- mshapes(efourier(bot , 10), "type")
b <- ms$shp$beer
w <- ms$shp$whisky
# we obtain the mean shape, then euclidean distances between points
m <- mshapes(list(b, w))
d <- edm(b, w)
# First plot
coo_plot(m, plot=FALSE)
coo_draw(b)
coo_draw(w)
coo_ruban(m, d, lwd=5)

#Another example
coo_plot(m, plot=FALSE)
coo_ruban(m, d, palette=col_summer2, lwd=5)
```

```
#If you want linewidth rather than color
coo_plot(m, plot=FALSE)
coo_ruban(m, d, palette=col_black)
```

---

coo_sample	<i>Sample coordinates (among points)</i>
------------	--

---

## Description

Sample n coordinates among existing points.

## Usage

```
coo_sample(coo, n)
```

## Arguments

coo	either a matrix of (x; y) coordinates or an <a href="#">Out</a> or an <a href="#">Opn</a> object.
n	integer, the number fo points to sample.

## Details

For the [Out](#) an [Opn](#) methods (pointless for [Ldk](#)), in an `$ldk` component is defined, it is changed accordingly by multiplying the ids by n over the number of coordinates.

## Value

a matrix of (x; y) coordinates, or an [Out](#) or an [Opn](#) object.

## See Also

Other sampling functions: [coo\\_extract](#), [coo\\_interpolate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#)

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

## Examples

```
b <- bot[1]
stack(bot)
stack(coo_sample(bot, 24))
coo_plot(b)
coo_plot(coo_sample(b, 24))
```

---

coo_samlerr	<i>Samples coordinates (regular radius)</i>
-------------	---

---

### Description

Samples  $n$  coordinates with a regular angle.

### Usage

```
coo_samlerr(coo, n)
```

### Arguments

coo	matrix of (x; y) coordinates or any <a href="#">Coo</a> object.
n	integer, the number of points to sample.

### Details

By design, this function samples among existing points, so using [coo\\_interpolate](#) prior to it may be useful to have more homogeneous angles. See examples.

### Value

a matrix of (x; y) coordinates or a [Coo](#) object.

### See Also

Other sampling functions: [coo\\_extract](#), [coo\\_interpolate](#), [coo\\_sample\\_prop](#), [coo\\_sample](#)

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

### Examples

```
stack(bot)
bot <- coo_center(bot)
stack(coo_samlerr(bot, 12))
coo_plot(bot[1])
coo_plot(rr <- coo_samlerr(bot[1], 12))
cpos <- coo_centpos(bot[1])
segments(cpos[1], cpos[2], rr[, 1], rr[, 2])

# Sometimes, interpolating may be useful:
```

```

shp <- hearts[1] %>% coo_center

# given a shp, draw segments from each points on it, to its centroid
draw_rads <- function(shp, ...){
  segments(shp[, 1], shp[, 2], coo_centpos(shp)[1], coo_centpos(shp)[2], ...)
}

# calculate the sd of argument difference in successive points,
# in other words a proxy for the homogeneity of angles
sd_theta_diff <- function(shp)
  shp %>% complex(real=.[, 1], imaginary=.[, 2]) %>%
  Arg %>% `\[(-1) %>% diff %>% sd

# no interpolation: all points are sampled from existing points but the
# angles are not equal
shp %>% coo_plot(points=TRUE, main="no interpolation")
shp %>% coo_samlerr(64) %T>% draw_rads(col="red") %>% sd_theta_diff
# with interpolation: much more homogeneous angles
shp %>% coo_plot(points=TRUE)
shp %>% coo_interpolate(360) %>% coo_samlerr(64) %T>% draw_rads(col="blue") %>% sd_theta_diff

```

---

coo_sample_prop	<i>Sample a proportion of coordinates (among points)</i>
-----------------	--

---

### Description

A simple wrapper around [coo\\_sample](#)

### Usage

```
coo_sample_prop(coo, prop = 1)
```

### Arguments

coo	either a matrix of (x; y) coordinates or an <a href="#">Out</a> or an <a href="#">Opn</a> object.
prop	numeric, the proportion of points to sample

### Details

As for [coo\\_sample](#) if an `$ldk` component is defined, it is changed accordingly by multiplying the `ids` by `n` over the number of coordinates.

### Value

a matrix of (x; y) coordinates, or an [Out](#) or an [Opn](#) object.

**See Also**

Other sampling functions: `coo_extract`, `coo_interpolate`, `coo_sampler`, `coo_sample`

Other `coo_` utilities: `coo_aligncalliper`, `coo_alignminradius`, `coo_alignxax`, `coo_align`, `coo_baseline`, `coo_bookstein`, `coo_boundingbox`, `coo_calliper`, `coo_centdist`, `coo_center`, `coo_centpos`, `coo_close`, `coo_down`, `coo_dxy`, `coo_extract`, `coo_flipx`, `coo_force2close`, `coo_interpolate`, `coo_is_closed`, `coo_jitter`, `coo_left`, `coo_likely_clockwise`, `coo_nb`, `coo_perim`, `coo_range`, `coo_rev`, `coo_right`, `coo_rotatecenter`, `coo_rotate`, `coo_sampler`, `coo_sample`, `coo_scale`, `coo_shearx`, `coo_slice`, `coo_slidedirection`, `coo_slidegap`, `coo_slide`, `coo_smoothcurve`, `coo_smooth`, `coo_template`, `coo_trans`, `coo_trimbottom`, `coo_trimtop`, `coo_trim`, `coo_up`, `is_equallyspacedradii`

**Examples**

```
# single shape
bot[1] %>% coo_nb()
bot[1] %>% coo_sample_prop(0.5) %>% coo_nb()
```

---

<code>coo_scale</code>	<i>Scales coordinates</i>
------------------------	---------------------------

---

**Description**

`coo_scale` scales the coordinates by a 'scale' factor. If not provided, assumed to be the centroid size. It involves three steps: centering from current position, dividing coordinates by 'scale', pushing back to the original position. `coo_scalex` applies a scaling (or shrinking) parallel to the x-axis, `coo_scaley` does the same for the y axis.

**Usage**

```
coo_scale(coo, scale)

## Default S3 method:
coo_scale(coo, scale = coo_centsize(coo))

## S3 method for class 'Coo'
coo_scale(coo, scale)

coo_scalex(coo, scale = 1)

## Default S3 method:
coo_scalex(coo, scale = 1)

## S3 method for class 'Coo'
coo_scalex(coo, scale = 1)

coo_scaley(coo, scale = 1)
```

```
## Default S3 method:
coo_scaley(coo, scale = 1)

## S3 method for class 'Coo'
coo_scaley(coo, scale = 1)
```

### Arguments

`coo` matrix of (x; y) coordinates or any [Coo](#) object.

`scale` the scaling factor, by default, the centroid size for `coo_scale`; 1 for `scalex` and `scaley`.

### Value

a single shape or a [Coo](#) object

### See Also

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

Other scaling functions: [coo\\_template](#)

### Examples

```
# on a single shape
b <- bot[1] %>% coo_center %>% coo_scale
coo_plot(b, lwd=2)
coo_draw(coo_scalex(b, 1.5), bor="blue")
coo_draw(coo_scaley(b, 0.5), bor="red")
# this also works on Coo objects:
stack(bot)
bot %>% coo_center %>% coo_scale %>% stack
bot %>% coo_center %>% coo_scaley(0.5) %>% stack
#equivalent to:
#bot %>% coo_center %>% coo_scalex(2) %>% stack
```

---

coo\_shearx

*Shears shapes*

---

### Description

`coo_shearx` applies a shear mapping on a matrix of (x; y) coordinates (or a list), parallel to the x-axis (i.e.  $x' = x + ky$ ;  $y' = y + kx$ ). `coo_sheary` does it parallel to the y-axis.

**Usage**

```
coo_shearx(coo, k)
```

```
coo_sheary(coo, k)
```

**Arguments**

coo                matrix of (x; y) coordinates or any [Coo](#) object.  
k                 numeric shear factor

**Value**

a matrix of (x; y) coordinates.

**See Also**

Other transforming functions: [coo\\_flipx](#)

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
coo <- coo_template(shapes[11])
coo_plot(coo)
coo_draw(coo_shearx(coo, 0.5), border="blue")
coo_draw(coo_sheary(coo, 0.5), border="red")
```

---

coo\_slice

*Slices shapes between successive coordinates*

---

**Description**

Takes a shape with n coordinates. When you pass this function with at least two ids ( $\leq n$ ), the shape will be open on the corresponding coordinates and slices returned as a list

**Usage**

```
coo_slice(coo, ids, ldk)
```



**Arguments**

coo	matrix of (x; y) coordinates or any <a href="#">Coo</a> object.
ids	numeric of length $\geq 2$ , where to slice the shape(s)
ldk	numeric the id of the ldk to use as ids, only on <code>Opn</code> and <code>Opn</code> . If provided, <code>ids</code> will be ignored.

**Value**

a list of shapes or a list of [Opn](#)

**See Also**

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignnax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
h <- slice(hearts, 1:5) # speed purpose only
# single shape, a list of matrices is returned
sh <- coo_slice(h[1], c(12, 24, 36, 48))
coo_plot(sh[[1]])
panel(Opn(sh))
# on a Coo, a list of Opn is returned
# makes no sense if shapes are not normalized first
sh2 <- coo_slice(h, c(12, 24, 36, 48))
panel(sh2[[1]])

# Use coo_slice with `ldk` instead:
# hearts as an example
x <- h %>% fgProcrustes(tol=1)
# 4 landmarks
stack(x)
x$ldk[1:5]

# here we slice
y <- coo_slice(x, ldk=1:4)

# plotting
stack(y[[1]])
stack(y[[2]])

# new ldks from tipping points, new ldks from angle
olea %>% slice(1:5) %>% # for the sake of speed
def_ldk_tips %>%
```

```

def_ldk_angle(0.75*pi) %>% def_ldk_angle(0.25*pi) %>%
coo_slice(ldk =1:4) -> oleas
oleas[[1]] %>% stack
oleas[[2]] %>% stack # etc.

# domestic operations
y[[3]] %>% coo_area()
# shape analysis of a slice
y[[1]] %>% coo_bookstein() %>% npoly %>% PCA %>% plot(~aut)

```

---

coo\_slide

*Slides coordinates*


---

## Description

Slides the coordinates so that the id-th point become the first one.

## Usage

```
coo_slide(coo, id, ldk)
```

## Arguments

coo	matrix of (x; y) coordinates or any <a href="#">Coo</a> object.
id	numeric the id of the point that will become the new first point. See details below for the method on <a href="#">Coo</a> objects.
ldk	numeric the id of the ldk to use as id, only on <a href="#">Out</a>

## Details

For [Coo](#) objects, and in particular for [Out](#) and [Opn](#) three different ways of `coo_sliding` are available:

- **no ldk passed and a single id is passed:** all id-th points within the shapes will become the first points. \$ldk will be slided accordingly.
- **no ldk passed and a vector of ids matching the length of the Coo:** for every shape, the id-th point will be used as the id-th point. \$ldk will be slided accordingly.
- **a single ldk is passed:** the ldk-th ldk will be used to slide every shape. If an ldk is passed, id is ignored with a message.

See examples.

## Value

a matrix of (x; y) coordinates, or a [Coo](#) object.

**See Also**

[coo\\_slice](#) and friends.

Other sliding functions: [coo\\_slidedirection](#), [coo\\_slidegap](#)

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
stack(hearts)
# set the first landmark as the starting point
stack(coo_slide(hearts, ldk=1))
# set the 50th point as the starting point (everywhere)
stack(coo_slide(hearts, id=50))
# set the id-random-th point as the starting point (everywhere)
set.seed(123) # just for the reproducibility
id_random <- sample(x=min(sapply(hearts$coo, nrow)), size=length(hearts),
replace=TRUE)
stack(coo_slide(hearts, id=id_random))
```

---

`coo_slidedirection`      *Slides coordinates in a particular direction*

---

**Description**

Shapes are centered and then, according to direction, the point northwards, southwards, eastwards or westwards the centroid, becomes the first point with [coo\\_slide](#).

**Usage**

```
coo_slidedirection(coo, direction = c("down", "left", "up", "right")[4],
center, id)
```

**Arguments**

<code>coo</code>	matrix of (x; y) coordinates or any <a href="#">Coo</a> object.
<code>direction</code>	character one of "down", "left", "up", "right" ("right" by default)
<code>center</code>	logical whether to center or not before sliding
<code>id</code>	numeric whether to return the id of the point or the slided shapes

**Value**

a matrix of (x; y) coordinates, or a [Coo](#) object.

**See Also**

Other sliding functions: [coo\\_slidegap](#), [coo\\_slide](#)

Other coo\_ utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
b <- coo_rotate(bot[1], pi/6) # dummy example just to make it obvious
coo_plot(b) # not the first point
coo_plot(coo_slidedirection(b, "up"))
coo_plot(coo_slidedirection(b, "right"))
coo_plot(coo_slidedirection(b, "left"))
coo_plot(coo_slidedirection(b, "down"))

# on Coo objects
stack(bot)
stack(coo_slidedirection(bot, "left"))
```

---

coo\_slidegap

*Slides coordinates using the widest gap*

---

**Description**

When slicing a shape using two landmarks, or functions such as [coo\\_up](#), an open curve is obtained and the rank of points make wrong/artefactual results. If the widest gap is  $> 5 * \text{median of other gaps}$ , then the couple of coordinates forming this widest gap is used as starting and ending points. This switch helps to deal with open curves. Examples are self-speaking. Use `force=TRUE` to bypass this check

**Usage**

```
coo_slidegap(coo, force)
```

**Arguments**

`coo` matrix of (x; y) coordinates or any [Coo](#) object.  
`force` logical whether to use the widest gap, with no check, as the real gap

**Value**

a matrix of (x; y) coordinates or a [Coo](#) object.

**See Also**

Other sliding functions: [coo\\_slidedirection](#), [coo\\_slide](#)

Other coo\_ utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
cat <- coo_center(shapes[4])
coo_plot(cat)

# we only retain the bottom of the cat
cat_down <- coo_down(cat, slidegap=FALSE)

# see? the segment on the x-axis coorespond to the widest gap.
coo_plot(cat_down)

# that's what we meant
coo_plot(coo_slidegap(cat_down))
```

---

coo_smooth	<i>Smooths coordinates</i>
------------	----------------------------

---

**Description**

Smooths coordinates using a simple moving average. May be useful to remove digitization noise, mainly on outlines and open outlines.

**Usage**

```
coo_smooth(coo, n)
```

**Arguments**

coo	matrix of (x; y) coordinates or any <a href="#">Coo</a> object.
n	integer the number of smoothing iterations

**Value**

a matrix of (x; y) coordinates, or a [Coo](#) object.

**See Also**

Other smoothing functions: [coo\\_smoothcurve](#)

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
b <- bot[1]
stack(bot)
stack(coo_smooth(bot, 10))
coo_plot(bot[1])
coo_plot(coo_smooth(bot[1], 30))
```

---

coo_smoothcurve	<i>Smoothes coordinates on curves</i>
-----------------	---------------------------------------

---

**Description**

Smoothes coordinates using a simple moving average but let the first and last points unchanged. May be useful to remove digitization noise on curves.

**Usage**

```
coo_smoothcurve(coo, n)
```

**Arguments**

<code>coo</code>	matrix of (x; y) coordinates or any <a href="#">Coo</a> object.
<code>n</code>	integer to specify the number of smoothing iterations

**Value**

a matrix of (x; y) coordinates, or a [Coo](#) object.

**See Also**

Other smoothing functions: [coo\\_smooth](#)

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

**Examples**

```
o <- olea[1]
coo_plot(o, border='grey50', points=FALSE)
coo_draw(coo_smooth(o, 24), border='blue', points=FALSE)
coo_draw(coo_smoothcurve(o, 24), border='red', points=FALSE)
```

---

`coo_solidity`

*Calculates the solidity of a shape*

---

**Description**

Calculated using the ratio of the shape area and the convex hull area.

**Usage**

```
coo_solidity(coo)
```

**Arguments**

`coo` a matrix of (x; y) coordinates or any `Coo`

**Value**

numeric for a single shape, list for `Coo`

**Source**

Rosin PL. 2005. Computing global shape measures. Handbook of Pattern Recognition and Computer Vision. 177-196.

**See Also**

Other `coo_` descriptors: [coo\\_angle\\_edge1](#), [coo\\_angle\\_edges](#), [coo\\_angle\\_tangent](#), [coo\\_area](#), [coo\\_boundingbox](#), [coo\\_chull](#), [coo\\_circularity](#), [coo\\_convexity](#), [coo\\_eccentricity](#), [coo\\_elongation](#), [coo\\_length](#), [coo\\_lw](#), [coo\\_rectangularity](#), [coo\\_rectilinearity](#), [coo\\_width](#)

**Examples**

```

coo_solidity(bot[1])

bot %>%
  slice(1:3) %>% # for speed sake only
  coo_solidity

```

---

coo_template	<i>'Templates' shapes</i>
--------------	---------------------------

---

**Description**

coo\_template returns shape centered on the origin and inscribed in a size-side square. coo\_template\_relatively does the same but the biggest shape (as prod(coo\_diffrange)) will be of size=size and consequently not defined on single shapes.

**Usage**

```

coo_template(coo, size)

## Default S3 method:
coo_template(coo, size = 1)

## S3 method for class 'list'
coo_template(coo, size = 1)

## S3 method for class 'Coo'
coo_template(coo, size = 1)

coo_template_relatively(coo, size = 1)

## S3 method for class 'list'
coo_template_relatively(coo, size = 1)

## S3 method for class 'Coo'
coo_template_relatively(coo, size = 1)

```

**Arguments**

coo	A list or a matrix of coordinates.
size	numeric. Indicates the length of the side 'inscribing' the shape.

**Details**

See [coo\\_listpanel](#) for an illustration of this function. The morphospaces functions also take profit of this function. May be useful to develop other graphical functions.



**Value**

Returns a matrix of (x; y)coordinates.

**See Also**

Other coo\_ utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

Other scaling functions: [coo\\_scale](#)

**Examples**

```
coo <- bot[1]
coo_plot(coo_template(coo), xlim=c(-1, 1), ylim=c(-1, 1))
rect(-0.5, -0.5, 0.5, 0.5)

s <- 0.01
coo_plot(coo_template(coo, s))
rect(-s/2, -s/2, s/2, s/2)
```

---

coo\_trans

*Translates coordinates*


---

**Description**

Translates the coordinates by a 'x' and 'y' value

**Usage**

```
coo_trans(coo, x = 0, y = 0)
```

**Arguments**

coo	matrix of (x; y) coordinates or any <a href="#">Coo</a> object.
x	numeric translation along the x-axis.
y	numeric translation along the y-axis.

**Value**

a matrix of (x; y) coordinates, or a [Coo](#) object.

**See Also**

Other coo\_ utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_allyspacedradii](#)

**Examples**

```
coo_plot(bot[1])
coo_plot(coo_trans(bot[1], 50, 100))
# on Coo
stack(bot)
stack(coo_trans(bot, 50, 100))
```

---

coo\_trim

*Trims both ends coordinates from shape*


---

**Description**

Removes trim coordinates at both ends of a shape, ie from top and bottom of the shape matrix.

**Usage**

```
coo_trim(coo, trim = 1)
```

**Arguments**

coo	matrix of (x; y) coordinates or any <a href="#">Coo</a> object.
trim	numeric, the number of coordinates to trim

**See Also**

Other coo\_ utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_up](#), [is\\_allyspacedradii](#)

Other coo\_trimming functions: [coo\\_trimbottom](#), [coo\\_trimtop](#)

**Examples**

```
olea[1] %>% coo_sample(12) %T>%
  print() %T>% ldk_plot() %>%
  coo_trim(1) %T>% print() %>% points(col="red")
```

---

coo_trimbottom	<i>Trims bottom coordinates from shape</i>
----------------	--

---

**Description**

Removes trim coordinates from the bottom of a shape.

**Usage**

```
coo_trimbottom(coo, trim = 1)
```

**Arguments**

coo	matrix of (x; y) coordinates or any <a href="#">Coo</a> object.
trim	numeric, the number of coordinates to trim

**See Also**

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

Other `coo_`trimming functions: [coo\\_trimtop](#), [coo\\_trim](#)

**Examples**

```
olea[1] %>% coo_sample(12) %T>%
  print() %T>% ldk_plot() %>%
  coo_trimbottom(4) %T>% print() %>% points(col="red")
```

---

coo_trimtop	<i>Trims top coordinates from shape</i>
-------------	---

---

**Description**

Removes trim coordinates from the top of a shape.

**Usage**

```
coo_trimtop(coo, trim = 1)
```

**Arguments**

coo	matrix of (x; y) coordinates or any <a href="#">Coo</a> object.
trim	numeric, the number of coordinates to trim

**See Also**

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trim](#), [coo\\_up](#), [is\\_equallyspacedradii](#)

Other `coo_` trimming functions: [coo\\_trimbottom](#), [coo\\_trim](#)

**Examples**

```
olea[1] %>% coo_sample(12) %T>%
  print() %T>% ldk_plot() %>%
  coo_trimtop(4) %T>% print() %>% points(col="red")
```

---

coo_truss	<i>Truss measurement</i>
-----------	--------------------------

---

**Description**

A method to calculate on shapes or on [Coo](#) truss measurements, that is all pairwise combinations of euclidean distances

**Usage**

```
coo_truss(x)
```

**Arguments**

x a shape or an Ldk object

**Value**

a named numeric or matrix

**Note**

Mainly implemented for historical/didactical reasons.

**See Also**

Other premodern: [measure](#)

**Examples**

```
# example on a single shape
cat <- coo_sample(shapes[4], 6)
coo_truss(cat)

# example on wings dataset
tx <- coo_truss(wings)
dim(tx)
# we normalize and plot an heatmap
txn <- apply(tx$coe, 2, .normalize)
# heatmap(txn)

txp <- PCA(tx, scale. = TRUE, center=TRUE, fac=wings$fac)
plot(txp, 1)
```

---

coo_up	<i>Retains coordinates with positive y-coordinates</i>
--------	--

---

**Description**

Useful when shapes are aligned along the x-axis (e.g. because of a bilateral symmetry) and when one wants to retain just the upper side.

**Usage**

```
coo_up(coo, slidegap = FALSE)
```

**Arguments**

coo matrix of (x; y) coordinates or any [Coo](#) object.  
slidegap logical whether to apply [coo\\_slidegap](#) after [coo\\_down](#)

**Value**

a matrix of (x; y) coordinates or a [Coo](#) object ([Out](#) are returned as [Opn](#))

**Note**

When shapes are "sliced" along the x-axis, it usually results on open curves and thus to huge/artefactual gaps between points neighboring this axis. This is usually solved with [coo\\_slidegap](#). See examples there.

Also, when apply a [coo\\_left/right/up/down](#) on an [Out](#) object, you then obtain an [Opn](#) object, which is done automatically.

**See Also**

Other opening functions: [coo\\_down](#), [coo\\_left](#), [coo\\_right](#)

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignnxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samplerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [is\\_equallyspacedradii](#)

**Examples**

```
b <- coo_alignnxax(bot[1])
coo_plot(b)
coo_draw(coo_up(b), border='red')
```

---

coo\_width

*Calculates the width of a shape*

---

**Description**

Nothing more than `coo_lw(coo)[2]`.

**Usage**

```
coo_width(coo)
```

**Arguments**

`coo` a matrix of (x; y) coordinates or [Coo](#) object

**Value**

the width (in pixels) of the shape

**See Also**

[coo\\_lw](#), [coo\\_length](#).

Other `coo_` descriptors: [coo\\_angle\\_edge1](#), [coo\\_angle\\_edges](#), [coo\\_angle\\_tangent](#), [coo\\_area](#), [coo\\_boundingbox](#), [coo\\_chull](#), [coo\\_circularity](#), [coo\\_convexity](#), [coo\\_eccentricity](#), [coo\\_elongation](#), [coo\\_length](#), [coo\\_lw](#), [coo\\_rectangularity](#), [coo\\_rectilinearity](#), [coo\\_solidity](#)

**Examples**

```
coo_width(bot[1])
```

---

d

*A wrapper to calculates euclidean distances between two points*

---

**Description**

The main advantage over [ed](#) is that it is a method that can be passed to different objects and used in combination with [measure](#). See examples.

**Usage**

```
d(x, id1, id2)
```

**Arguments**

x	a Ldk (typically), an Out or a matrix
id1	id of the 1st row
id2	id of the 2nd row

**Note**

On Out objects, we first [get\\_ldk](#).

**See Also**

if you want all pairwise combinations, see [coo\\_truss](#)

**Examples**

```
# single shape
d(wings[1], 1, 4)
# Ldk object
d(wings, 1, 4)
# Out object
d(hearts, 2, 4)
```

---

def_ldk	<i>Defines new landmarks on Out and Opn objects</i>
---------	---

---

### Description

Helps to define landmarks on a Coo object. The number of landmarks must be specified and rows indices that correspond to the nearest points clicked on every outlines are stored in the \$ldk slot of the Coo object.

### Usage

```
def_ldk(Coo, nb.ldk)
```

### Arguments

Coo	an Out or Opn object
nb.ldk	the number of landmarks to define on every shape

### Value

an Out or an Opn object with some landmarks defined

### See Also

Other ldk/slidings methods: [add\\_ldk](#), [def\\_slidings](#), [get\\_ldk](#), [get\\_slidings](#), [rearrange\\_ldk](#), [slidings\\_scheme](#)

### Examples

```
## Not run:
bot <- bot[1:5] # to make it shorter to try
# click on 3 points, 5 times.
# Don't forget to save the object returned by def_ldk...
bot2 <- def_ldk(bot, 3)
stack(bot2)
bot2$ldk

## End(Not run)
```



---

def_ldk_angle	<i>Add new landmarks based on angular positions</i>
---------------	---

---

**Description**

A wrapper on [coo\\_intersect\\_angle](#) and [coo\\_intersect\\_direction](#) for [Out](#) and [Opn](#) objects.

**Usage**

```
def_ldk_angle(coo, angle)

def_ldk_direction(coo, direction = c("down", "left", "up", "right")[4])

## Default S3 method:
def_ldk_direction(coo, direction = c("down", "left", "up",
  "right")[4])

## S3 method for class 'Out'
def_ldk_direction(coo, direction = c("down", "left", "up",
  "right")[4])

## S3 method for class 'Opn'
def_ldk_direction(coo, direction = c("down", "left", "up",
  "right")[4])
```

**Arguments**

coo	a codeOut or Opn object
angle	numeric an angle in radians (0 by default).
direction	character one of "down", "left", "up", "right" ("right" by default)

**Note**

any existing ldk will be preserved.

**See Also**

Typically used before [coo\\_slice](#) and [coo\\_slide](#). See [def\\_ldk\\_tips](#) as well.

**Examples**

```
# adds a new landmark towards south east
hearts %>%
  slice(1:5) %>% # for speed purpose only
  def_ldk_angle(-pi/6) %>%
  stack()
```

```
# on Out and towards NW and NE here
olea %>%
  slice(1:5) %>% #for speed purpose only
  def_ldk_angle(3*pi/4) %>%
  def_ldk_angle(pi/4) %>%
  stack
```

---

def_ldk_tips	<i>Define tips as new landmarks</i>
--------------	-------------------------------------

---

### Description

On [Opn](#) objects, this can be used before [coo\\_slice](#). See examples.

### Usage

```
def_ldk_tips(coo)
```

### Arguments

coo	Opn object
-----	------------

### Note

any existing ldk will be preserved.

### Examples

```
is_ldk(olea) # no ldk for olea
olea %>%
  slice(1:3) %>% #for the sake of speed
  def_ldk_tips %>%
  def_ldk_angle(3*pi/4) %>% def_ldk_angle(pi/4) %T>% stack %>%
  coo_slice(ldk=1:4) -> oleas
stack(oleas[[1]])
stack(oleas[[2]]) # etc.
```

---

def_links	<i>Defines links between landmarks</i>
-----------	--

---

**Description**

Works on Ldk objects, on 2-cols matrices, 3-dim arrays (mshapes turns it into a matrix).

**Usage**

```
def_links(x, nb.ldk)
```

**Arguments**

x	Ldk, matrix or array
nb.ldk	numeric the iterative procedure is stopped when the user click on the top of the graphical window.

**See Also**

Other ldk helpers: [ldk\\_check](#), [links\\_all](#), [links\\_deLaunay](#)

**Examples**

```
## Not run:  
wm <- mshapes(wings)  
links <- def_links(wm, 3) # click to define pairs of landmarks  
ldk_links(wm, links)  
  
## End(Not run)
```

---

def_slidings	<i>Defines sliding landmarks matrix</i>
--------------	---

---

**Description**

Defines sliding landmarks matrix

**Usage**

```
def_slidings(Coo, slidings)
```

**Arguments**

Coo	an <a href="#">Ldk</a> object
slidings	a matrix, a numeric or a list of numeric. See Details

**Details**

\$slidings in `Ldk` must be a 'valid' matrix: containing ids of coordinates, none of them being lower than 1 and higher the number of coordinates in \$coo.

slidings matrix contains 3 columns (before, slide, after). It is inspired by geomorph and should be compatible with it.

This matrix can be passed directly if the slidings argument is a matrix. Of course, it is strictly equivalent to `Ldk$slidings <- slidings`.

slidings can also be passed as "partition(s)", when sliding landmarks identified by their ids (which are a row number) are consecutive in the \$coo.

A single partition can be passed either as a numeric (eg 4:12), if points 5 to 11 must be considered as sliding landmarks (4 and 12 being fixed); or as a list of numeric.

See examples below.

**See Also**

Other ldk/slidings methods: [add\\_ldk](#), [def\\_ldk](#), [get\\_ldk](#), [get\\_slidings](#), [rearrange\\_ldk](#), [slidings\\_scheme](#)

**Examples**

```
#waiting for a sliding dataset...
```

---

dfourier

*Discrete cosinus transform*


---

**Description**

Calculates discrete cosine transforms, as introduced by Dommergues and colleagues, on a shape (mainly open outlines).

**Usage**

```
dfourier(coo, nb.h)
```

```
## Default S3 method:
```

```
dfourier(coo, nb.h)
```

```
## S3 method for class 'Opn'
```

```
dfourier(coo, nb.h)
```

```
## S3 method for class 'Coo'
```

```
dfourier(coo, nb.h)
```

**Arguments**

coo	a matrix (or a list) of (x; y) coordinates
nb.h	numeric the number of harmonics to calculate

**Value**

a list with the following components:

- an the A harmonic coefficients
- bn the B harmonic coefficients
- mod the modules of the points
- arg the arguments of the points

**Note**

This method has been only poorly tested in Momocs and should be considered as experimental. Yet improved by a factor 10, this method is still long to execute. It will be improved in further releases but it should not be so painful right now. It also explains the progress bar. Shapes should be aligned before performing the dct transform.

Silent message and progress bars (if any) with options("verbose"=FALSE).

**References**

- Dommergues, C. H., Dommergues, J.-L., & Verrecchia, E. P. (2007). The Discrete Cosine Transform, a Fourier-related Method for Morphometric Analysis of Open Contours. *Mathematical Geology*, 39(8), 749-763. doi:10.1007/s11004-007-9124-6
- Many thanks to Remi Laffont for the translation in R).

**See Also**

Other dfourier: [dfourier\\_i](#), [dfourier\\_shape](#)

**Examples**

```
## Not run: # because it's long
od <- dfourier(olea)
od
op <- PCA(od)
plot(op, 1)

## End(Not run)
# dfourier and inverse dfourier
o <- olea[1]
o <- coo_bookstein(o)
coo_plot(o)
o.dfourier <- dfourier(o, nb.h=12)
o.dfourier
o.i <- dfourier_i(o.dfourier)
o.i <- coo_bookstein(o.i)
```

```

coo_draw(o.i, border='red')

#future calibrate_reconstructions
o <- olea[1]
h.range <- 2:13
coo <- list()
for (i in seq(along=h.range)){
  coo[[i]] <- dfourier_i(dfourier(o, nb.h=h.range[i]))}
names(coo) <- paste0('h', h.range)
panel(Open(coo), borders=col_india(12), names=TRUE)
title('Discrete Cosine Transforms')

```

---

dfourier\_i

*Investe discrete cosinus transform*


---

### Description

Calculates inverse discrete cosine transforms (see [dfourier](#)), given a list of A and B harmonic coefficients, typically such as those produced by [dfourier](#).

### Usage

```
dfourier_i(df, nb.h, nb.pts = 60)
```

### Arguments

df	a list with \$A and \$B components, containing harmonic coefficients.
nb.h	a custom number of harmonics to use
nb.pts	numeric the number of pts for the shape reconstruction

### Value

a matrix of (x; y) coordinates

### Note

Only the core functions so far. Will be implemented as an [Open](#) method soon.

### References

- Dommergues, C. H., Dommergues, J.-L., & Verrecchia, E. P. (2007). The Discrete Cosine Transform, a Fourier-related Method for Morphometric Analysis of Open Contours. *Mathematical Geology*, 39(8), 749-763. doi:10.1007/s11004-007-9124-6
- Many thanks to Remi Laffont for the translation in R).

### See Also

Other dfourier: [dfourier\\_shape](#), [dfourier](#)

**Examples**

```

# dfourier and inverse dfourier
o <- olea[1]
o <- coo_bookstein(o)
coo_plot(o)
o.dfourier <- dfourier(o, nb.h=12)
o.dfourier
o.i <- dfourier_i(o.dfourier)
o.i <- coo_bookstein(o.i)
coo_draw(o.i, border='red')

o <- olea[1]
h.range <- 2:13
coo <- list()
for (i in seq(along=h.range)){
  coo[[i]] <- dfourier_i(dfourier(o, nb.h=h.range[i]))}
names(coo) <- paste0('h', h.range)
panel(Open(coo), borders=col_india(12), names=TRUE)
title('Discrete Cosine Transforms')

```

---

dfourier\_shape

*Calculates and draws 'dfourier' shapes*


---

**Description**

Calculates shapes based on 'Discrete cosine transforms' given harmonic coefficients (see [dfourier](#)) or can generate some random 'dfourier' shapes. Mainly intended to generate shapes and/or to understand how dfourier works.

**Usage**

```
dfourier_shape(A, B, nb.h, nb.pts = 60, alpha = 2, plot = TRUE)
```

**Arguments**

A	vector of harmonic coefficients
B	vector of harmonic coefficients
nb.h	if A and/or B are not provided, the number of harmonics to generate
nb.pts	if A and/or B are not provided, the number of points to use to reconstruct the shapes
alpha	The power coefficient associated with the (usually decreasing) amplitude of the harmonic coefficients (see <a href="#">efourier_shape</a> )
plot	logical whether to plot the shape

**See Also**

Other dfourier: [dfourier\\_i](#), [dfourier](#)

**Examples**

```
# some signatures
panel(coo_align(Opn(replicate(48, dfourier_shape(alpha=0.5, nb.h=6))))))
# some worms
panel(coo_align(Opn(replicate(48, dfourier_shape(alpha=2, nb.h=6))))))
```

dissolve

*Dissolve Coe objects***Description**

the opposite of combine, typically used after it. Note that the \$fac slot may be wrong since combine...well combines... this \$fac. See examples.

**Usage**

```
dissolve(x, retain)
```

**Arguments**

x	a Coe object
retain	the partition id to retain. Or their name if the partitions are named (see x\$method) eg after a chop

**See Also**

Other handling functions: [arrange](#), [at\\_least](#), [chop](#), [combine](#), [fac\\_dispatcher](#), [filter](#), [mutate](#), [rescale](#), [rm\\_harm](#), [rm\\_uncomplete](#), [rw\\_fac](#), [sample\\_frac](#), [sample\\_n](#), [select](#), [slice](#)

**Examples**

```
data(bot)
w <- filter(bot, type=="whisky")
b <- filter(bot, type=="beer")
wf <- efourier(w, 10)
bf <- efourier(b, 10)
wbf <- combine(wf, bf)
dissolve(wbf, 1)
dissolve(wbf, 2)

# or using chop (yet combine here makes no sense)
bw <- bot %>% chop(~type) %>% lapply(efourier, 10) %>% combine
bw %>% dissolve(1)
bw %>% dissolve(2)
```



---

drawers	<i>grindr drawers for shape plots</i>
---------	---------------------------------------

---

**Description**

Useful drawers for building custom shape plots using the *grindr* approach. See examples and vignettes.

**Usage**

```
draw_polygon(coo, f, col = par("fg"), fill = NA, lwd = 1, lty = 1,  
             transp = 0, pal = pal_qual, ...)
```

```
draw_outline(coo, f, col = par("fg"), fill = NA, lwd = 1, lty = 1,  
             transp = 0, pal = pal_qual, ...)
```

```
draw_outlines(coo, f, col = par("fg"), fill = NA, lwd = 1, lty = 1,  
              transp = 0, pal = pal_qual, ...)
```

```
draw_points(coo, f, col = par("fg"), cex = 1/2, pch = 20, transp = 0,  
            pal = pal_qual, ...)
```

```
draw_landmarks(coo, f, col = par("fg"), cex = 1/2, pch = 20, transp = 0,  
               pal = pal_qual, ...)
```

```
draw_lines(coo, f, col = par("fg"), lwd = 1, lty = 1, transp = 0,  
           pal = pal_qual, ...)
```

```
draw_centroid(coo, f, col = par("fg"), pch = 3, cex = 0.5, transp = 0,  
              pal = pal_qual, ...)
```

```
draw_curve(coo, f, col = par("fg"), lwd = 1, lty = 1, transp = 0,  
           pal = pal_qual, ...)
```

```
draw_curves(coo, f, col = par("fg"), lwd = 1, lty = 1, transp = 0,  
            pal = pal_qual, ...)
```

```
draw_firstpoint(coo, f, label = "^", col = par("fg"), cex = 3/4,  
                transp = 0, pal = pal_qual, ...)
```

```
draw_axes(coo, col = "#333333", cex = 3/4, lwd = 3/4, ...)
```

```
draw_labels(coo, labels = 1:nrow(coo), cex = 1/2, d = 1/20, ...)
```

```
draw_links(coo, f, links, col = "#99999955", lwd = 1/2, lty = 1,  
           transp = 0, pal = pal_qual, ...)
```

```
draw_title(coo, main = "", sub = "", cex = c(1, 3/4), font = c(2, 1),
           padding = 1/200, ...)
```

### Arguments

coo	matrix of 2 columns for (x, y) coordinates
f	an optionnal factor specification to feed. See examples and vignettes.
col	color (hexadecimal) to draw components
fill	color (hexadecimal) to draw components
lwd	to draw components
lty	to draw components
transp	numeric transparency (default:0, min:0, max:1)
pal	a palette to use if no col/border/etc. are provided. See [palettes]
...	additional options to feed core functions for each drawer
cex	to draw components ((c(2, 1) by default) for draw_title)
pch	to draw components
label	to indicate first point
labels	character name of labels to draw (defaut to 1:nrow(coo))
d	numeric proportion of d(centroid-each_point) to add when centrifugating landmarks
links	matrix of links to use to draw segments between landmarks. See wings\$ldk for an example
main	character title (empty by default)
sub	character subtitle (empty by default)
font	numeric to feed <code>text</code> (c(2, 1) by default)
padding	numeric a fraction of the graphical window (1/200 by default)

### Note

This approach will (soon) replace `coo_plot` and friends in further versions. All comments are welcome.

### See Also

`grindr_layers`

Other grindr: [layers](#), [mosaic\\_engine](#), [papers](#), [pile](#), [plot\\_PCA](#)

**Examples**

```
bot[1] %>% paper_grid() %>% draw_polygon()
olea %>% paper_chess %>% draw_lines(~var)

hearts[240] %>% paper_white() %>% draw_outline() %>%
  coo_sample(24) %>% draw_landmarks %>% draw_labels() %>%
  draw_links(links=replicate(2, sample(1:24, 8)))

bot %>%
  paper_grid() %>%
  draw_outlines() %>%
  draw_title("Alcohol abuse \nis dangerous for health", "Drink responsibly")
```

---

ed

*Calculates euclidean distance between two points.*

---

**Description**

ed simply calculates euclidean distance between two points defined by their (x; y) coordinates.

**Usage**

```
ed(pt1, pt2)
```

**Arguments**

pt1	(x; y) coordinates of the first point.
pt2	(x; y) coordinates of the second point.

**Value**

Returns the euclidean distance between the two points.

**See Also**

[edm](#), [edm\\_nearest](#), [dist](#).

**Examples**

```
ed(c(0,1), c(1,0))
```

---

edi *Calculates euclidean intermediate between two points.*

---

### Description

edi simply calculates coordinates of a points at the relative distance  $r$  on the  $pt1$ - $pt2$  defined by their  $(x; y)$  coordinates. This function is used internally but may be of interest for other analyses.

### Usage

```
edi(pt1, pt2, r = 0.5)
```

### Arguments

pt1  $(x; y)$  coordinates of the first point.  
 pt2  $(x; y)$  coordinates of the second point.  
 r the relative distance from pt1 to pt2.

### Value

returns the  $(x; y)$  interpolated coordinates.

### See Also

[ed](#), [edm](#).

### Examples

```
edi(c(0,1), c(1,0), r = 0.5)
```

---

edm *Calculates euclidean distance every pairs of points in two matrices.*

---

### Description

edm returns the euclidean distances between points  $1 - > n$  of two 2-col matrices of the same dimension. This function is used internally but may be of interest for other analyses.

### Usage

```
edm(m1, m2)
```

### Arguments

m1 The first matrix of coordinates.  
 m2 The second matrix of coordinates.

**Details**

If one wishes to align two (or more shapes) Procrustes surimposition may provide a better solution.

**Value**

Returns a vector of euclidean distances between pairwise coordinates in the two matrices.

**See Also**

[ed](#), [edm\\_nearest](#), [dist](#).

**Examples**

```
x <- matrix(1:10, nc=2)
edm(x, x)
edm(x, x+1)
```

---

edm\_nearest

*Calculates the shortest euclidean distance found for every point of one matrix among those of a second.*

---

**Description**

edm\_nearest calculates the shortest euclidean distance found for every point of one matrix among those of a second. In other words, if  $m_1$ ,  $m_2$  have  $n$  rows, the result will be the shortest distance for the first point of  $m_1$  to any point of  $m_2$  and so on,  $n$  times. This function is used internally but may be of interest for other analyses.

**Usage**

```
edm_nearest(m1, m2, full = FALSE)
```

**Arguments**

m1	The first list or matrix of coordinates.
m2	The second list or matrix of coordinates.
full	logical. Whether to returns a condensed version of the results.

**Details**

So far this function is quite time consuming since it performs  $n \times n$  euclidean distance computation. If one wishes to align two (or more shapes) Procrustes surimposition may provide a better solution.

**Value**

If `full` is `TRUE`, returns a list with two components: `d` which is for every point of `m1` the shortest distance found between it and any point in `m2`, and `pos` the (`m2`) row indices of these points. Otherwise returns `d` as a numeric vector of the shortest distances.

**See Also**

[ed](#), [edm](#), [dist](#).

**Examples**

```
x <- matrix(1:10, nc=2)
edm_nearest(x, x+rnorm(10))
edm_nearest(x, x+rnorm(10), full=TRUE)
```

---

efourier

*Elliptical Fourier transform (and its normalization)*

---

**Description**

`efourier` computes Elliptical Fourier Analysis (or Transforms or EFT) from a matrix (or a list) of (`x`; `y`) coordinates. `efourier_norm` normalizes Fourier coefficients. Read Details carefully.

**Usage**

```
efourier(x, ...)

## Default S3 method:
efourier(x, nb.h, smooth.it = 0, ...)

## S3 method for class 'Out'
efourier(x, nb.h, smooth.it = 0, norm = TRUE, start = FALSE,
  ...)

efourier_norm(ef, start = FALSE)
```

**Arguments**

<code>x</code>	A list or a matrix of coordinates or a <code>Out</code> object
<code>...</code>	useless here
<code>nb.h</code>	integer. The number of harmonics to use. If missing, 12 is used on shapes; 99 percent of harmonic power on <code>Out</code> objects, both with messages.
<code>smooth.it</code>	integer. The number of smoothing iterations to perform.
<code>norm</code>	whether to normalize the coefficients using <a href="#">efourier_norm</a>
<code>start</code>	logical. For <code>efourier</code> whether to consider the first point as homologous; for <code>efourier_norm</code> whether to conserve the position of the first point of the outline.
<code>ef</code>	list with <code>a_n</code> , <code>b_n</code> , <code>c_n</code> and <code>d_n</code> Fourier coefficients, typically returned by <a href="#">efourier</a>

## Details

For the maths behind see the paper in JSS.

Normalization of coefficients has long been a matter of trouble, and not only for newcomers. There are two ways of normalizing outlines: the first, and by far the most used, is to use a "numerical" alignment, directly on the matrix of coefficients. The coefficients of the first harmonic are consumed by this process but harmonics of higher rank are normalized in terms of size and rotation. This is sometimes referred as using the "first ellipse", as the harmonics define an ellipse in the plane, and the first one is the mother of all ellipses, on which all others "roll" along. This approach is really convenient as it is done easily by most software (if not the only option) and by Momocs too. It is the default option of `efourier`.

But here is the pitfall: if your shapes are prone to bad alignments among all the first ellipses, this will result in poorly (or even not at all) "homologous" coefficients. The shapes particularly prone to this are either (at least roughly) circular and/or with a strong bilateral symmetry. You can try to use `stack` on the `Coe` object returned by `efourier`. Also, and perhaps more explicitly, morphospace usually show a mirroring symmetry, typically visible when calculated in some couple of components (usually the first two).

If you see these upside-down (or 180 degrees rotated) shapes on the morphospace, you should seriously consider aligning your shapes **before** the `efourier` step, and performing the latter with `norm = FALSE`.

Such a pitfall explains the (quite annoying) message when passing `efourier` with just the `Out`.

You have several options to align your shapes, using control points (or landmarks), by far the most time consuming (and less reproducible) but possibly the best one too when alignment is too tricky to automate. You can also try Procrustes alignment (see `fgProcrustes`) through their calliper length (see `coo_aligncalliper`), etc. You should also make the first point homologous either with `coo_slide` or `coo_slidedirection` to minimize any subsequent problems.

I will dedicate (some day) a vignette or a paper to this problem.

## Value

For `efourier`, a list with components: `an`, `bn`, `cn`, `dn` harmonic coefficients, plus `ao` and `co`. The latter should have been named `a0` and `c0` in Claude (2008) but I (intentionnaly) propagated the error.

For `efourier_norm`, a list with components: `A`, `B`, `C`, `D` for harmonic coefficients, plus `size`, the magnitude of the semi-major axis of the first fitting ellipse, `theta` angle, in radians, between the starting and the semi-major axis of the first fitting ellipse, `psi` orientation of the first fitting ellipse, `ao` and `do`, same as above, and `lnef` that is the concatenation of coefficients.

## Note

Directly borrowed for Claude (2008).

Silent message and progress bars (if any) with options(`"verbose"=FALSE`).

## References

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp. Ferson S, Rohlf FJ, Koehn RK. 1985. Measuring shape variation of two-dimensional outlines. *Systematic Biology* **34**: 59-68.

**See Also**

Other efourier: [efourier\\_i](#), [efourier\\_shape](#)

**Examples**

```
# single shape
coo <- bot[1]
coo_plot(coo)
ef <- efourier(coo, 12)
ef
efi <- efourier_i(ef)
coo_draw(efi, border='red', col=NA)

# on Out
bot %>% slice(1:5) %>% efourier
```

---

 efourier\_i

*Inverse elliptical Fourier transform*


---

**Description**

efourier\_i uses the inverse elliptical Fourier transformation to calculate a shape, when given a list with Fourier coefficients, typically obtained computed with [efourier](#).

**Usage**

```
efourier_i(ef, nb.h, nb.pts = 120)
```

**Arguments**

ef	list. A list containing $a_n$ , $b_n$ , $c_n$ and $d_n$ Fourier coefficients, such as returned by <a href="#">efourier</a> .
nb.h	integer. The number of harmonics to use. If not specified, <code>length(ef\$an)</code> is used.
nb.pts	integer. The number of points to calculate.

**Details**

See [efourier](#) for the mathematical background.

**Value**

A matrix of (x; y) coordinates.

**Note**

Directly borrowed for Claude (2008), and also called `iefourier` there.



## References

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp. Ferson S, Rohlf FJ, Koehn RK. 1985. Measuring shape variation of two-dimensional outlines. *Systematic Biology* **34**: 59-68.

## See Also

Other efourier: [efourier\\_shape](#), [efourier](#)

## Examples

```
coo <- bot[1]
coo_plot(coo)
ef <- efourier(coo, 12)
ef
efi <- efourier_i(ef)
coo_draw(efi, border='red', col=NA)
```

---

efourier_shape	<i>Calculates and draw 'efourier' shapes.</i>
----------------	---

---

## Description

efourier\_shape calculates a 'Fourier elliptical shape' given Fourier coefficients (see Details) or can generate some 'efourier' shapes. Mainly intended to generate shapes and/or to understand how efourier works.

## Usage

```
efourier_shape(an, bn, cn, dn, nb.h, nb.pts = 60, alpha = 2, plot = TRUE)
```

## Arguments

an	numeric. The $a_n$ Fourier coefficients on which to calculate a shape.
bn	numeric. The $b_n$ Fourier coefficients on which to calculate a shape.
cn	numeric. The $c_n$ Fourier coefficients on which to calculate a shape.
dn	numeric. The $d_n$ Fourier coefficients on which to calculate a shape.
nb.h	integer. The number of harmonics to use.
nb.pts	integer. The number of points to calculate.
alpha	numeric. The power coefficient associated with the (usually decreasing) amplitude of the Fourier coefficients (see <b>Details</b> ).
plot	logical. Whether to plot or not the shape.

**Details**

`efourier_shape` can be used by specifying `nb.h` and `alpha`. The coefficients are then sampled in an uniform distribution  $(-\pi; \pi)$  and this amplitude is then divided by  $harmonicrank^\alpha$ . If `alpha` is lower than 1, consecutive coefficients will thus increase. See [efourier](#) for the mathematical background.

**Value**

A list with components:

- x vector of x-coordinates
- y vector of y-coordinates.

**References**

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp.

Ferson S, Rohlf FJ, Koehn RK. 1985. Measuring shape variation of two-dimensional outlines. *Systematic Biology* **34**: 59-68.

**See Also**

Other `efourier`: [efourier\\_i](#), [efourier](#)

**Examples**

```
ef <- efourier(bot[1], 24)
efourier_shape(ef$an, ef$bn, ef$cn, ef$dn) # equivalent to efourier_i(ef)
efourier_shape() # is autonomous

panel(Out(a2l(replicate(100,
efourier_shape(nb.h=6, alpha=2.5, plot=FALSE)))))) # Bubble family
```

---

export

*Exports Coe objects and shapes*

---

**Description**

Writes a `.txt` or `.xls` or whatever readable from a single shape, a [Coe](#), or a [PCA](#) object, along with individual names and `$fac`.

**Usage**

```
export(x, file, sep, dec)
```

**Arguments**

x	a Coe or PCA object
file	the filenames data.txt by default
sep	the field separator string to feed <a href="#">write.table</a> . (default to tab) tab by default
dec	the string to feed <a href="#">write.table</a> (default ".") by default.

**Note**

This is a simple wrapper around [write.table](#).

Default parameters will write a .txt file, readable by foreign programs. With default parameters, numbers will use dots as decimal points, which is considered as a character chain in Excel in many countries (locale versions). This can be solved by using `dec=','` as in the examples below.

If you are looking for your file, and did not specified file, `getwd()` will help.

I have to mention that everytime you use this function, and cowardly run from R to Excel and do 'statistics' there, an innocent and adorable kitten is probably murdered somewhere. Use R!

**See Also**

Other bridges functions: [as\\_df](#), [bridges](#), [complex](#)

**Examples**

```
## Not run:
# Will write files on your machine!
bf <- efourier(bot, 6)
# Export Coe (here Fourier coefficients)
export(bf) # data.txt which can be opened by every software including MS Excel

# If you come from a country that uses comma as decimal separator (not recommended, but...)
export(bf, dec=',')
export(bf, file='data.xls', dec=',')

# Export PCA scores
bf %>% PCA %>% export()

# for shapes (matrices)
export(bot[1], file='bot1.txt')

# remove these files from your machine
file.remove("coefficients.txt", "data.xls", "scores.txt")

## End(Not run)
```

---

fac_dispatcher	<i>Brew and serve fac from Momocs object</i>
----------------	--

---

### Description

Ease various specifications for fac specification when passed to Momocs objects. Intensively used (internally).

### Usage

```
fac_dispatcher(x, fac)
```

### Arguments

x	a Momocs object (any Coo, Coe, PCA, etc.)
fac	a specification to extract from fac

### Details

fac can be:

- a factor, passed on the fly
- a column id from \$fac
- a column name from fac
- a formula (preferred) in the form: ~column\_name (from \$fac, no quotes)

### Value

a prepared factor (or a numeric). See examples

### See Also

Other handling functions: [arrange](#), [at\\_least](#), [chop](#), [combine](#), [dissolve](#), [filter](#), [mutate](#), [rescale](#), [rm\\_harm](#), [rm\\_uncomplete](#), [rw\\_fac](#), [sample\\_frac](#), [sample\\_n](#), [select](#), [slice](#)

### Examples

```
bot <- mutate(bot, s=rnorm(40), fake=factor(rep(letters[1:4], 10)))

# factor, on the fly
fac_dispatcher(bot, factor(rep(letters[1:4], 10)))

# column id
fac_dispatcher(bot, 1)

# column name
fac_dispatcher(bot, "type")
```

```
# same, numeric case
fac_dispatcher(bot, "s")

# formula interface
fac_dispatcher(bot, ~type)

# formula interface + interaction on the fly
fac_dispatcher(bot, ~type+fake)
```

---

fgProcrustes

*Full Generalized Procrustes alignment between shapes*


---

## Description

Directly borrowed from Claude (2008), called there the fgpa2 function.

## Usage

```
fgProcrustes(x, tol, coo)
```

## Arguments

x	an array, a list of configurations, or an <a href="#">Out</a> , <a href="#">Opn</a> or <a href="#">Ldk</a> object
tol	numeric when to stop iterations
coo	logical, when working on <a href="#">Out</a> or <a href="#">Opn</a> , whether to use \$coo rather than \$ldk

## Details

If performed on an [Out](#) or an [Opn](#) object, will try to use the \$ldk slot, if landmarks have been previously defined, then (with a message) on the \$coo slot, but in that case, all shapes must have the same number of coordinates ([coo\\_sample](#) may help).

## Value

a list with components:

- rotated array of superimposed configurations
- iterationnumber number of iterations
- Q convergence criterion
- Qi full list of Q
- Qd difference between successive Q
- interproc.dist minimal sum of squared norms of pairwise differences between all shapes in the superimposed sample
- mshape mean shape configuration
- cent.size vector of centroid sizes.

or an [Out](#), [Opn](#) or an [Ldk](#) object.

**Note**

Slightly less optimized than procGPA in the shapes package (~20 Will be optimized when performance will be the last thing to improve! Silent message and progress bars (if any) with `options("verbose"=FALSE)`.

**References**

Claude, J. (2008). Morphometrics with R. Analysis (p. 316). Springer.

**See Also**

Other procrustes functions: [fProcrustes](#), [fgsProcrustes](#), [pProcrustes](#)

**Examples**

```
## Not run:
# on Ldk
stack(wings)
fgProcrustes(wings, tol=0.1) %>% stack()

# on Out
stack(hearts)
fgProcrustes(hearts) %>% stack()

## End(Not run)
```

---

fgsProcrustes	<i>Full Generalized Procrustes alignment between shapes with sliding landmarks</i>
---------------	--

---

**Description**

Directly wrapped around `geomorph::gpagen`.

**Usage**

```
fgsProcrustes(x)
```

**Arguments**

x                    Ldk object with some \$slidings

**Note**

Landmarks methods are the less tested in Momocs. Keep in mind that some features are still experimental and that your help is welcome.

**Source**

See `?gpagen` in `geomorph` package

**See Also**

Other procrustes functions: [fProcrustes](#), [fgProcrustes](#), [pProcrustes](#)

**Examples**

```
chaffp <- fgsProcrustes(chaff)
chaffp
chaffp %>% PCA() %>% plot("taxa")
```

---

 filter

*Subset based on conditions*


---

**Description**

Return shapes with matching conditions, from the \$fac. See examples and `?dplyr::filter`.

**Usage**

```
filter(.data, ...)
```

**Arguments**

.data	a Coo, Coe, PCA object
...	logical conditions

**Details**

dplyr verbs are maintained.

**Value**

a Momocs object of the same class.

**See Also**

Other handling functions: [arrange](#), [at\\_least](#), [chop](#), [combine](#), [dissolve](#), [fac\\_dispatcher](#), [mutate](#), [rescale](#), [rm\\_harm](#), [rm\\_uncomplete](#), [rw\\_fac](#), [sample\\_frac](#), [sample\\_n](#), [select](#), [slice](#)

**Examples**

```
olea
# we retain on dorsal views
filter(olea, view=="VD")
# only dorsal views and Aglan+PicMa varieties
filter(olea, view=="VD", var %in% c("Aglan", "PicMa"))
# we create an id column and retain the 120 first shapes
olea %>% mutate(id=1:length(olea)) %>% filter(id > 120)
```

---

 flip\_PCaxes

*Flips PCA axes*


---

### Description

Simply multiply by -1, corresponding scores and rotation vectors for PCA objects. PC orientation being arbitrary, this may help to have a better display.

### Usage

```
flip_PCaxes(x, axs)
```

### Arguments

x	a PCA object
axs	numeric which PC(s) to flip

### Examples

```
bp <- bot %>% efourier(6) %>% PCA
bp %>% plot
bp %>% flip_PCaxes(1) %>% plot()
```

---

 flower

*Data: Measurement of iris flowers*


---

### Description

Data: Measurement of iris flowers

### Format

A TraCoe object with 150 measurements of 4 variables (petal + sepal) x (length x width) on 3 species of iris. This dataset is the classical [iris](#) formatted for Momocs.

### Source

see [linkiris](#)

### See Also

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#), [wings](#)



---

fProcrustes	<i>Full Procrustes alignment between two shapes</i>
-------------	---

---

**Description**

Directly borrowed from Claude (2008), called there the fPsup function.

**Usage**

```
fProcrustes(coo1, coo2)
```

**Arguments**

coo1	configuration matrix to be superimposed onto the centered preshape of coo2.
coo2	reference configuration matrix.

**Value**

a list with components:

- coo1 superimposed centered preshape of coo1 onto the centered preshape of coo2
- coo2 centered preshape of coo2
- rotation rotation matrix
- scale scale parameter
- DF full Procrustes distance between coo1 and coo2.

**References**

Claude, J. (2008). Morphometrics with R. Analysis (p. 316). Springer.

**See Also**

Other procrustes functions: [fgProcrustes](#), [fgsProcrustes](#), [pProcrustes](#)

---

get_chull_area	<i>Calculates convex hull area/volume of PCA scores</i>
----------------	---

---

### Description

May be useful to compare shape diversity. Expressed in PCA units that should only be compared within the same PCA.

### Usage

```
get_chull_area(x, fac, xax = 1, yax = 2)
get_chull_volume(x, fac, xax = 1, yax = 2, zax = 3)
```

### Arguments

x	a PCA object
fac	(optionnal) column name or ID from the \$fac slot.
xax	the first PC axis to use (1 by default)
yax	the second PC axis (2 by default)
zax	the third PC axis (3 by default only for volume)

### Details

get\_chull\_area is calculated using [coo\\_chull](#) followed by [coo\\_area](#); get\_chull\_volume is calculated using `geometry::convexhulln`

### Value

If fac is not provided global area/volume is returned; otherwise a named list for every level of fac

### Examples

```
bp <- PCA(efourier(bot, 12))
get_chull_area(bp)
get_chull_area(bp, 1)

get_chull_volume(bp)
get_chull_volume(bp, 1)
```

---

get_ldk	<i>Retrieves landmarks coordinates</i>
---------	--

---

### Description

See Details for the different behaviors implemented.

### Usage

```
get_ldk(Coo)
```

### Arguments

Coo                    an Out, Opn or Ldk object

### Details

Different behaviors depending on the class of the object:

- **Ldk**: retrieves landmarks.
- **Ldk** with slidings defined: retrieves only the fixed landmarks, not the sliding ones. See also [get\\_slidings](#).
- **Out** landmarks from \$ldk and \$coo, if any.
- **Opn**: same as above.

### Value

a list of shapes

### See Also

Other ldk/slidings methods: [add\\_ldk](#), [def\\_ldk](#), [def\\_slidings](#), [get\\_slidings](#), [rearrange\\_ldk](#), [slidings\\_scheme](#)

### Examples

```
# Out example
ldk.h <- get_ldk(hearts)
stack(Ldk(ldk.h))

# on Ldk (no slidings)
get_ldk(wings) # equivalent to wings$coo

# on Ldk (slidings)
get_ldk(chaff)
get_ldk(chaff) %>% Ldk %>% fgProcrustes(tol=0.1) %>% stack
```

---

 get\_pairs

*Get paired individual on a Coe, PCA or LDA objects*


---

### Description

If you have paired individuals, i.e. before and after a treatment or for repeated measures, and if you have coded it into \$fac, this methods allows you to retrieve the corresponding PC/LD scores, or coefficients for [Coe](#) objects.

### Usage

```
get_pairs(x, fac, range)
```

### Arguments

x	any <a href="#">Coe</a> , <a href="#">PCA</a> or <a href="#">LDA</a> object.
fac	factor or column name or id corresponding to the pairing factor.
range	numeric the range of coefficients for Coe, or PC (LD) axes on which to return scores.

### Value

a list with components x1 all coefficients/scores corresponding to the first level of the fac provided; x2 same thing for the second level; fac the corresponding fac.

### Examples

```
bot2 <- bot1 <- coo_scale(coo_center(coo_sample(bot, 60)))
bot1$fac$session <- factor(rep("session1", 40))
# we simulate an measurement error
bot2 <- coo_jitter(bot1, amount=0.01)
bot2$fac$session <- factor(rep("session2", 40))
botc <- combine(bot1, bot2)
botcf <- efourier(botc, 12)

# we gonna plot the PCA with the two measurement sessions and the two types
botcp <- PCA(botcf)
plot(botcp, "type", col=col_summer(2), pch=rep(c(1, 20), each=40), eigen=FALSE)
bot.pairs <- get_pairs(botcp, fac = "session", range=1:2)
segments(bot.pairs$session1[, 1], bot.pairs$session1[, 2],
         bot.pairs$session2[, 1], bot.pairs$session2[, 2],
         col=col_summer(2)[bot.pairs$fac$type])
```

---

get_slidings	<i>Extracts sliding landmarks coordinates</i>
--------------	---

---

**Description**

From an [Ldk](#) object.

**Usage**

```
get_slidings(Coo, partition)
```

**Arguments**

Coo	an Ldk object
partition	numeric which one(s) to get.

**Value**

a list of list(s) of coordinates.

**See Also**

Other ldk/slidings methods: [add\\_ldk](#), [def\\_ldk](#), [def\\_slidings](#), [get\\_ldk](#), [rearrange\\_ldk](#), [slidings\\_scheme](#)

**Examples**

```
# for each example below a list with partition containign shapes is returned
# extracts the first partition
get_slidings(chaff, 1) %>% names()
# the first and the fourth
get_slidings(chaff, c(1, 4)) %>% names()
# all of them
get_slidings(chaff) %>% names
# here we want to see it
get_slidings(chaff, 1)[[1]] %>% Ldk %>% stack
```

---

harm_pow	<i>Calculates harmonic power given a list from e/t/rfourier</i>
----------	---

---

**Description**

Given a list with an, bn (and eventually cn and dn), returns the harmonic power.

**Usage**

```
harm_pow(xf)
```

**Arguments**

`xf` A list with `an`, `bn` (and `cn`, `dn`) components, typically from a `e/r/tfourier` passed on `coo_`

**Value**

Returns a vector of harmonic power

**Examples**

```
ef <- efourier(bot[1], 24)
rf <- rfourier(bot[1], 24)
harm_pow(ef)
harm_pow(rf)

plot(cumsum(harm_pow(ef)[-1]), type='o',
     main='Cumulated harmonic power without the first harmonic',
     ylab='Cumulated harmonic power', xlab='Harmonic rank')
```

---

hcontrib

*Harmonic contribution to shape*


---

**Description**

Calculates contribution of harmonics to shape. The amplitude of every coefficients of a given harmonic is multiplied by the coefficients provided and the resulting shapes are reconstructed and plotted. Naturally, only works on Fourier-based methods.

**Usage**

```
hcontrib(Coe, ...)
```

```
## S3 method for class 'OutCoe'
hcontrib(Coe, id, harm.r, amp.r = c(0, 0.5, 1, 2, 5, 10),
         main = "Harmonic contribution to shape", xlab = "Harmonic rank",
         ylab = "Amplification factor", ...)
```

**Arguments**

`Coe` a `Coe` object (either `OutCoe` or (soon) `OpnCoe`)

`...` additional parameter to pass to `coo_draw`

`id` the id of a particular shape, otherwise working on the `meanshape`

`harm.r` range of harmonics on which to explore contributions

`amp.r` a vector of numeric for multiplying coefficients

main	a title for the plot
xlab	a title for the x-axis
ylab	a title for the y-axis

### See Also

Other Coe\_graphics: [boxplot.OutCoe](#), [hist.OutCoe](#)

### Examples

```
data(bot)
bot.f <- efourier(bot, 12)
hcontrib(bot.f)
hcontrib(bot.f, harm.r=3:10, amp.r=1:8, col="grey20",
  main="A huge panel")
```

---

hearts

*Data: Outline coordinates of hand-drawn hearts*

---

### Description

Data: Outline coordinates of hand-drawn hearts

### Format

A **Out** object with the outline coordinates of 240 hand-drawn hearts by 8 different persons, with 4 landmarks.

### Source

We thank the fellows of the Ecology Department of the French Institute of Pondicherry that drawn the hearts, that then have been smoothed, scaled, centered, and downsampled to 80 coordinates per outline.

### See Also

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [flower](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#), [wings](#)

---

hist.OutCoe	<i>Histogram of morphometric coefficients</i>
-------------	---

---

### Description

Explores the distribution of coefficient values.

### Usage

```
## S3 method for class 'OutCoe'  
hist(x, retain = 4, drop = 0, bw = 20, ...)
```

### Arguments

x	the <a href="#">Coe</a> object
retain	numeric the number of harmonics to retain
drop	numeric the number of harmonics to drop
bw	the number of bins (range/bw) to display
...	useless here but maintain the consistency with generic hist

### Value

a `ggplot2` object

### See Also

Other `Coe_graphics`: [boxplot.OutCoe](#), [hcontrib](#)

### Examples

```
data(bot)  
bot.f <- efourier(bot, 24)  
hist(bot.f)
```

```
data(olea)  
op <- opoly(olea)  
hist(op)
```



---

img_plot	<i>Plots a .jpg image</i>
----------	---------------------------

---

**Description**

A very simple image plotter. If provided with a path, reads the .jpg and plots it. If not provided with an imagematrix, will ask you to choose interactively a . jpeg image.

**Usage**

```
img_plot(img)
```

```
img_plot0(img)
```

**Arguments**

img                    a matrix of an image, such as those obtained with [readJPEG](#).

**Details**

img\_plot is used in import functions such as [import\\_jpg1](#); img\_plot0 does the same job but preserves the par and plots axes.

---

import_Conte	<i>Extract outlines coordinates from an image silhouette</i>
--------------	--

---

**Description**

Provided with an image 'mask' (i.e. black pixels on a white background), and a point form where to start the algorithm, returns the (x; y) coordinates of its outline.

**Usage**

```
import_Conte(img, x)
```

**Arguments**

img                    a matrix of a binary image mask.

x                      numeric the (x; y) coordinates of a starting point within the shape.

**Details**

Used internally by [import\\_jpg1](#) but may be useful for other purposes.

**Value**

a matrix the (x; y) coordinates of the outline points.

**Note**

Note this function will be deprecated from Momocs when Momacs and MomiT will be fully operational.

If you have an image with more than a single shape, then you may want to try `imager::highlight` function. Momocs may use this at some point.

**References**

- The original algorithm is due to: Pavlidis, T. (1982). *Algorithms for graphics and image processing*. Computer science press.
- is detailed in: Rohlf, F. J. (1990). An overview of image processing and analysis techniques for morphometrics. In *Proceedings of the Michigan Morphometrics Workshop*. Special Publication No. 2 (pp. 47-60). University of Michigan Museum of Zoology: Ann Arbor.
- and translated in R by: Claude, J. (2008). *Morphometrics with R*. (p. 316). Springer.

**See Also**

Other import functions: [import\\_StereoMorph\\_curve1](#), [import\\_jpg1](#), [import\\_jpg](#), [import\\_tps](#), [import\\_txt](#), [pix2chc](#)

---

import\_jpg

*Extract outline coordinates from multiple .jpg files*

---

**Description**

This function is used to import outline coordinates and is built around [import\\_jpg1](#).

**Usage**

```
import_jpg(jpg.paths = .lf.auto(), auto.notcentered = TRUE,
           fun.notcentered = NULL, threshold = 0.5)
```

**Arguments**

`jpg.paths` a vector of paths corresponding to the .jpg files to import. If not provided (or NULL), switches to the automatic version. See Details below.

`auto.notcentered` logical if TRUE random locations will be used until. one of them is (assumed) to be within the shape (because of a black pixel); if FALSE a [locator](#) will be called, and you will have to click on a point within the shape.

`fun.notcentered` NULL by default. Is your shapes are not centered and if a random pick of a black pixel is not satisfactory. See [import\\_jpg1](#) help and examples.

`threshold` the threshold value use to binarize the images. Above, pixels are turned to 1, below to 0.

### Details

see [import\\_jpg1](#) for important informations about how the outlines are extracted, and [import\\_Conte](#) for the algorithm itself.

If `jpg.paths` is not provided (or NULL), you will have to select any `.jpg` file in the folder that contains all your files. All the outlines should be imported then.

### Value

a list of matrices of (x; y) coordinates that can be passed to [Out](#)

### Note

Note this function will be deprecated from Momocs when Momacs and Momit will be fully operational.

Silent message and progress bars (if any) with options(`"verbose"`=FALSE).

### See Also

Other import functions: [import\\_Conte](#), [import\\_StereoMorph\\_curve1](#), [import\\_jpg1](#), [import\\_tps](#), [import\\_txt](#), [pix2chc](#)

### Examples

```
## Not run:

lf <- list.files('/foo/jpegs', full.names=TRUE)
coo <- import_jpg(lf)
Out(coo)

coo <- import_jpg()

## End(Not run)
```

---

import\_jpg1

*Extract outline coordinates from a single .jpg file*

---

### Description

Used to import outline coordinates from `.jpg` files. This function is used for single images and is wrapped by [import\\_jpg](#). It relies itself on [import\\_Conte](#)

**Usage**

```
import_jpg1(jpg.path, auto.notcentered = TRUE, fun.notcentered = NULL,
            threshold = 0.5)
```

**Arguments**

jpg.path	vector of paths corresponding to the .jpg files to import, such as those obtained with <a href="#">list.files</a> .
auto.notcentered	logical if TRUE random locations will be used until one of them is (assumed) to be within the shape (because it corresponds to a black pixel) and only if the middle point is not black; if FALSE a <a href="#">locator</a> will be called, and you will have to click on a point within the shape.
fun.notcentered	NULL by default but can accept a function that, when passed with an image-matrix and returns a numeric of length two that corresponds to a starting point on the imagematrix for the Conte algorithm. A while instruction wraps it, so the function may be wrong in proposing this starting position. See the examples below for a quick example.
threshold	the threshold value use to binarize the images. Above, pixels are turned to 1, below to 0.
...	arguments to be passed to <a href="#">read.table</a> , eg. 'skip', 'dec', etc.

**Details**

jpegs can be provided either as RVB or as 8-bit greylevels or monochrome. The function binarizes pixels values using the 'threshold' argument. It will try to start to apply the [import\\_Conte](#) algorithm from the center of the image and 'looking' downwards for the first black/white 'frontier' in the pixels. This point will be the first of the outlines. The latter may be useful if you align manually the images and if you want to retain this information in the consequent morphometric analyses.

If the point at the center of the image is not within the shape, i.e. is 'white' you have two choices defined by the 'auto.notcentered' argument. If it's TRUE, some random starting points will be tried until on of them is 'black' and within the shape; if FALSE you will be asked to click on a point within the shape.

If some pixels on the borders are not white, this functions adds a 2-pixel border of white pixels; otherwise [import\\_Conte](#) would fail and return an error.

Finally, remember that if the images are not in your working directory, [list.files](#) must be called with the argument `full.names=TRUE`!

Note that the use of the `fun.notcentered` argument will probably leads to serious headaches and will probably imply the dissection of these functions: [import\\_Conte](#), [img\\_plot](#) and `import_jpg` itself

**Value**

a matrix of (x; y) coordinates that can be passed to Out

**Note**

Note this function will be deprecated from Momocs when Momacs and Momi t will be fully operational.

**See Also**

[import\\_jpg](#), [import\\_Conte](#), [import\\_txt](#), [lf\\_structure](#). See also Momocs' vignettes for data import.

Other import functions: [import\\_Conte](#), [import\\_StereoMorph\\_curve1](#), [import\\_jpg](#), [import\\_tps](#), [import\\_txt](#), [pix2chc](#)

---

import\_StereoMorph\_curve1

*Import files creates by StereoMorph into Momocs*

---

**Description**

Helps to read .txt files created by StereoMorph into (x; y) coordinates or Momocs objects. Can be applied to 'curves' or 'ldk' text files.

**Usage**

```
import_StereoMorph_curve1(path)
```

```
import_StereoMorph_curve(path, names)
```

```
import_StereoMorph_ldk1(path)
```

```
import_StereoMorph_ldk(path, names)
```

**Arguments**

path	toward a single file or a folder containing .txt files produced by StereoMorph
names	to feed <a href="#">lf_structure</a>

**Details**

\*1 functions import a single .txt file. Their counterpart (no '1') work when path indicates the folder, i.e. 'curves' or 'ldk'. They then return a list of [Opn](#) or [Ldk](#) objects, respectively. Please do not hesitate to contact me should you have a particular case or need something.

**Note**

Note this function will be deprecated from Momocs when Momacs and Momi t will be fully operational.

**See Also**

Other import functions: [import\\_Conte](#), [import\\_jpg1](#), [import\\_jpg](#), [import\\_tps](#), [import\\_txt](#), [pix2chc](#)

Other import functions: [import\\_Conte](#), [import\\_jpg1](#), [import\\_jpg](#), [import\\_tps](#), [import\\_txt](#), [pix2chc](#)

Other import functions: [import\\_Conte](#), [import\\_jpg1](#), [import\\_jpg](#), [import\\_tps](#), [import\\_txt](#), [pix2chc](#)

Other import functions: [import\\_Conte](#), [import\\_jpg1](#), [import\\_jpg](#), [import\\_tps](#), [import\\_txt](#), [pix2chc](#)

---

import\_tps

*Import a tps file*


---

**Description**

And returns a list of coordinates, curves, scale

**Usage**

```
import_tps(tps.path, curves = TRUE)
```

```
tps2coo(tps, curves = TRUE)
```

**Arguments**

tps.path	lines, typically from <a href="#">readLines</a> , describing a single shape in tps-like format. You will need to manually build your Coo object from it: eg <code>Out(coo=your_list\$coo)</code> .
curves	logical whether to read curves, if any
tps	lines for a single tps file tps2coo is used in <a href="#">import_tps</a> and may be useful for data import. When provided with lines (eg after <a href="#">readLines</a> ) from a tps-like description (with "LM", "CURVES", etc.) returns a list of coordinates, curves, etc.

**Value**

a list with components: coo a matrix of coordinates; cur a list of matrices; scale the scale as a numeric.

**Note**

Note this function will be deprecated from Momocs when Momacs and Momi t will be fully operational.

**See Also**

Other import functions: [import\\_Conte](#), [import\\_StereoMorph\\_curve1](#), [import\\_jpg1](#), [import\\_jpg](#), [import\\_txt](#), [pix2chc](#)

Other import functions: [import\\_Conte](#), [import\\_StereoMorph\\_curve1](#), [import\\_jpg1](#), [import\\_jpg](#), [import\\_txt](#), [pix2chc](#)

---

import\_txt

---

*Import coordinates from a .txt file*


---

**Description**

A wrapper around [read.table](#) that can be used to import outline/landmark coordinates.

**Usage**

```
import_txt(txt.paths = .lf.auto(), ...)
```

**Arguments**

`txt.paths` a vector of paths corresponding to the .txt files to import. If not provided (or NULL), switches to the automatic version, just as in [import\\_jpg](#). See Details there.

`...` arguments to be passed to [read.table](#), eg. 'skip', 'dec', etc.

**Details**

Columns are not named in the .txt files. You can tune this using the `...` argument. Define the [read.table](#) arguments that allow to import a single file, and then pass them to this function, ie if your .txt file has a header (eg ('x', 'y')), do not forget `header=TRUE`.

**Value**

a list of `matrix(ces)` of (x; y) coordinates that can be passed to [Out](#), [Opn](#) and [Ldk](#).

**Note**

Note this function will be deprecated from Momocs when Momacs and Momit will be fully operational.

Silent message and progress bars (if any) with options(`"verbose"`=FALSE).

**See Also**

Other import functions: [import\\_Conte](#), [import\\_StereoMorph\\_curve1](#), [import\\_jpg1](#), [import\\_jpg](#), [import\\_tps](#), [pix2chc](#)

---

inspect	<i>Graphical inspection of shapes</i>
---------	---------------------------------------

---

### Description

Allows to plot shapes, individually, for [Coo](#) ([Out](#), [Opn](#) or [Ldk](#)) objects.

### Usage

```
inspect(x, id, ...)
```

### Arguments

x	the <a href="#">Coo</a> object
id	the id of the shape to plot, if not provided a random shape is plotted. If passed with 'all' all shapes are plotted, one by one.
...	further arguments to be passed to <a href="#">coo_plot</a>

### See Also

Other [Coo\\_graphics](#): [panel](#), [stack](#)

### Examples

```
## Not run:
inspect(bot, 5)
inspect(bot)
inspect(bot, 5, pch=3, points=TRUE) # an example of '...' use

## End(Not run)
```

---

is	<i>Class and component testers</i>
----	------------------------------------

---

### Description

Class testers test if any of the classes of an object *is* of a given class. For instance [is\\_PCA](#) on a [PCA](#) object (of classes [PCA](#) and [prcomp](#)) will return TRUE. Component testers check if *there\_is* a particular component (eg [\\$fac](#), etc.) in an object.



**Usage**`is_Coo(x)``is_PCA(x)``is_LDA(x)``is_Out(x)``is_Opn(x)``is_Ldk(x)``is_Coe(x)``is_OutCoe(x)``is_OpnCoe(x)``is_LdkCoe(x)``is_TraCoe(x)``is_shp(x)``is_fac(x)``is_ldk(x)``is_slidings(x)``is_links(x)`**Arguments**

x                   the object to test

**Value**

logical

**Examples**

```
is_Coo(bot)
is_Out(bot)
is_Ldk(bot)
is_ldk(hearts) # mind the capitals!
```

---

is\_equallyspacedradii *Tests if coordinates likely have equally spaced radii*

---

### Description

Returns TRUE/FALSE whether the sd of angles between all successive radii is below/above thesh

### Usage

```
is_equallyspacedradii(coo, thres)
```

### Arguments

coo	matrix of (x; y) coordinates or any <a href="#">Coo</a> object.
thres	numeric a threshold (arbitrarily $\pi/90$ , eg 2 degrees, by default)

### Value

a single or a vector of logical. If NA are returned, some coordinates are likely identical, at least for x or y.

### See Also

Other `coo_` utilities: [coo\\_aligncalliper](#), [coo\\_alignminradius](#), [coo\\_alignxax](#), [coo\\_align](#), [coo\\_baseline](#), [coo\\_bookstein](#), [coo\\_boundingbox](#), [coo\\_calliper](#), [coo\\_centdist](#), [coo\\_center](#), [coo\\_centpos](#), [coo\\_close](#), [coo\\_down](#), [coo\\_dxy](#), [coo\\_extract](#), [coo\\_flipx](#), [coo\\_force2close](#), [coo\\_interpolate](#), [coo\\_is\\_closed](#), [coo\\_jitter](#), [coo\\_left](#), [coo\\_likely\\_clockwise](#), [coo\\_nb](#), [coo\\_perim](#), [coo\\_range](#), [coo\\_rev](#), [coo\\_right](#), [coo\\_rotatecenter](#), [coo\\_rotate](#), [coo\\_sample\\_prop](#), [coo\\_samlerr](#), [coo\\_sample](#), [coo\\_scale](#), [coo\\_shearx](#), [coo\\_slice](#), [coo\\_slidedirection](#), [coo\\_slidegap](#), [coo\\_slide](#), [coo\\_smoothcurve](#), [coo\\_smooth](#), [coo\\_template](#), [coo\\_trans](#), [coo\\_trimbottom](#), [coo\\_trimtop](#), [coo\\_trim](#), [coo\\_up](#)

### Examples

```
bot[1] %>% is_equallyspacedradii
bot[1] %>% coo_samlerr(36) %>% is_equallyspacedradii
# higher tolerance but wrong
bot[1] %>% coo_samlerr(36) %>% is_equallyspacedradii(thres=5*2*pi/360)
# coo_interpolate is a better option
bot[1] %>% coo_interpolate(1200) %>% coo_samlerr(36) %>% is_equallyspacedradii
# Coo method
bot %>% coo_interpolate(360) %>% coo_samlerr(36) %>% is_equallyspacedradii
```

---

KMEANS

*KMEANS on PCA objects*

---

### Description

A very basic implementation of k-means. Beware that morphospaces are calculated so far for the 1st and 2nd component.

### Usage

```
KMEANS(x, ...)
```

```
## S3 method for class 'PCA'
```

```
KMEANS(x, centers, nax = 1:2, pch = 20, cex = 0.5, ...)
```

### Arguments

x	PCA object
...	additional arguments to be passed to <a href="#">kmeans</a>
centers	numeric number of centers
nax	numeric the range of PC components to use (1:2 by default)
pch	to draw the points
cex	to draw the points

### Value

the same thing as [kmeans](#)

### See Also

Other multivariate: [CLUST](#), [LDA](#), [MANOVA\\_PW](#), [MANOVA](#), [PCA](#), [classification\\_metrics](#), [mshapes](#)

### Examples

```
data(bot)
bp <- PCA(efourier(bot, 10))
KMEANS(bp, 2)
```

---

layers	<i>grindr layers for multivariate plots</i>
--------	---

---

### Description

Useful layers for building custom mutivariate plots using the cheapbabi approach. See examples.

### Usage

```
layer_frame(x, center_origin = TRUE, zoom = 0.9)

layer_axes(x, col = "#999999", lwd = 1/2, ...)

layer_grid(x, col = "#999999", lty = 3, grid = 3, ...)

layer_box(x, border = "#e5e5e5", ...)

layer_fullframe(x, ...)

layer_points(x, pch = 20, cex = 4/log1p(nrow(x$xy)), transp = 0, ...)

layer_morphospace(x, position = c("range", "full", "circle", "xy",
  "range_axes", "full_axes")[1], nb = 12, nr = 6, nc = 5, rotate = 0,
  size = 0.9, col = "#999999", flipx = FALSE, flipy = FALSE,
  draw = TRUE, ...)

layer_ellipses(x, conf = 0.5, lwd = 1, alpha = 0, ...)

layer_ellipsesfilled(x, conf = 0.5, lwd = 1, alpha = 0, ...)

layer_ellipsesaxes(x, conf = 0.5, lwd = 1, alpha = 0, ...)

layer_chull(x, ...)

layer_chullfilled(x, alpha = 0.8, ...)

layer_stars(x, alpha = 0.5, ...)

layer_delaunay(x, ...)

layer_density(x, levels_density = 20, levels_contour = 4, alpha = 1/3,
  n = 200, density = TRUE, contour = TRUE)

layer_labelpoints(x, col = par("fg"), cex = 2/3, font = 1,
  abbreviate = FALSE, ...)

layer_labelgroups(x, col = par("fg"), cex = 3/4, font = 2, rect = TRUE,
```

```

alpha = 1/4, abbreviate = FALSE, ...)
layer_rug(x, size = 1/200, ...)
layer_title(x, title = "", cex = 3/4, ...)
layer_axesnames(x, cex = 3/4, name = "Axis", ...)
layer_eigen(x, nb_max = 5, cex = 1/2, ...)
layer_axesvar(x, cex = 3/4, ...)
layer_legend(x, probs = seq(0, 1, 0.25), cex = 3/4, ...)

```

### Arguments

x	a list, typically returned by <a href="#">plot_PCA</a>
center_origin	logical whether to center the origin (default TRUE)
zoom	numeric to change the zoom (default 0.9)
col	color (hexadecimal) to use for drawing components
lwd	linewidth for drawing components
...	additional options to feed core functions for each layer
lty	linetype for drawing components
grid	numeric number of grid to draw
border	color (hexadecimal) to use to draw border
pch	to use for drawing components
cex	to use for drawing components
transp	transparency to use (min: 0 default:0 max:1)
position	one of range, full, circle,xy, range_axes, full_axes) to feed <a href="#">morphospace_positions</a> (default range)
nb	numeric total number of shapes when position="circle" (default 12)
nr	numeric number of rows to position shapes (default 6)
nc	numeric number of columns to position shapes (default 5)
rotate	numeric angle (in radians) to rotate shapes when displayed on the morphospace (default 0)
size	numeric size to use to feed <a href="#">coo_template</a> (default 0.9)
flipx	logical whether to flip shapes against the x-axis (default FALSE)
flipy	logical whether to flip shapes against the y-axis (default FALSE)
draw	logical whether to draw shapes (default TRUE)
conf	numeric between 0 and 1 for confidence ellipses
alpha	numeric between 0 and 1 for the transparency of components
levels_density	numeric number of levels to use to feed MASS::kde2d

levels_contour	numeric number of levels to use to feed graphics::contour
n	numeric number of grid points to feed MASS::kde2d
density	logical whether to draw density estimate
contour	logical whether to draw contour lines
font	to feed <a href="#">text</a>
abbreviate	logical whether to abbreviate names
rect	logical whether to draw a rectangle below names
title	to add to the plot (default "")
name	to use on axes (default "Axis")
nb_max	numeric number of eigen values to display (default 5)
probs	numeric sequence to feed stats::quantile and to indicate where to draw ticks and legend labels

**See Also**

[grindr\\_drawers](#)

Other grindr: [drawers](#), [mosaic\\_engine](#), [papers](#), [pile](#), [plot\\_PCA](#)

LDA

*Linear Discriminant Analysis on Coe objects***Description**

Calculates a LDA on [Coe](#) on top of [MASS::lda](#).

**Usage**

```
LDA(x, fac, retain, ...)
```

```
## Default S3 method:
```

```
LDA(x, fac, retain, ...)
```

```
## S3 method for class 'PCA'
```

```
LDA(x, fac, retain = 0.99, ...)
```

**Arguments**

x	a PCA object
fac	the grouping factor (names of one of the \$fac column or column id)
retain	the proportion of the total variance to retain (if retain<1) using <a href="#">scree</a> , or the number of PC axis (if retain>1).
...	additional arguments to feed <a href="#">lda</a>

**Value**

a 'LDA' object on which to apply [plot.LDA](#), which is a list with components:

- x any [Coe](#) object (or a matrix)
- fac grouping factor used
- removed ids of columns in the original matrix that have been removed since constant (if any)
- mod the raw lda mod from [lda](#)
- mod.pred the predicted model using x and mod
- CV.fac cross-validated classification
- CV.tab cross-validation tabke
- CV.correct proportion of correctly classified individuals
- CV.ce class error
- LDs unstandardized LD scores see Claude (2008)
- mshape mean values of coefficients in the original matrix
- method inherited from the Coe object (if any)

**Note**

For LDA.PCA, retain can be passed as a vector (eg: 1:5, and retain=1, retain=2, ..., retain=5) will be tried, or as "best" (same as before but retain=1:number\_of\_pc\_axes is used).

Silent message and progress bars (if any) with options("verbose"=FALSE).

**See Also**

Other multivariate: [CLUST](#), [KMEANS](#), [MANOVA\\_PW](#), [MANOVA](#), [PCA](#), [classification\\_metrics](#), [mshapes](#)

**Examples**

```
bot.f <- efourier(bot, 24)
bot.p <- PCA(bot.f)
LDA(bot.p, 'type', retain=0.99) # retains 0.99 of the total variance
LDA(bot.p, 'type', retain=5) # retain 5 axis
bot.l <- LDA(bot.p, 'type', retain=0.99)
bot.l
plot(bot.l)
bot.f$fac$plop <- factor(rep(letters[1:4], each=10))
bot.l <- LDA(PCA(bot.f), 'plop')
bot.l
plot(bot.l)
```

Ldk

*Builds an Ldk object***Description**

In Momocs, Ldk classes objects are lists of configurations of landmarks, with optionnal components, on which generic methods such as plotting methods (e.g. [stack](#)) and specific methods (e.g. [fgProcrustes](#)). Ldk objects are primarily [Coo](#) objects. In a sense, morphometrics methods on Ldk objects preserves (x, y) coordinates and LdkCoe are also Ldk objects.

**Usage**

```
Ldk(coo, links = NULL, slidings = NULL, fac = dplyr::data_frame())
```

**Arguments**

coo	a list of matrices of (x; y) coordinates, or an array, an Ldk object.
links	(optionnal) a 2-columns matrix of 'links' between landmarks, mainly for plotting
slidings	(optionnal) a 3-columns matrix defining (if any) sliding landmarks
fac	(optionnal) a data.frame of factors and/or numerics specifying the grouping structure

**Details**

All the shapes in x must have the same number of landmarks. If you are trying to make an Ldk object from an [Out](#) or an [Opn](#) object, try [coo\\_sample](#) beforehand to homogeneize the number of coordinates among shapes.

implementation of \$slidings is inspired by geomorph

**Value**

an Ldk object

**Examples**

```
#Methods on Ldk
methods(class=Ldk)
```



---

ldk_check	<i>Checks 'ldk' shapes</i>
-----------	----------------------------

---

### Description

A simple utility, used internally, mostly by [Ldk](#) methods, in some graphical functions, and notably in [l2a](#). Returns an array of landmarks arranged as  $(nb.ldk) \times (x; y) \times (nb.shapes)$ , when passed with either a list, a matrix or an array of coordinates. If a list is provided, checks that the number of landmarks is consistent.

### Usage

```
ldk_check(ldk)
```

### Arguments

ldk                    a matrix of (x; y) coordinates, a list, or an array.

### Value

an array of (x; y) coordinates.

### See Also

Other ldk helpers: [def\\_links](#), [links\\_all](#), [links\\_delaunay](#)

### Examples

```
#coo_check('Not a shape')
#coo_check(matrix(1:10, ncol=2))
#coo_check(list(x=1:5, y=6:10))
```

---

ldk_chull	<i>Draws convex hulls around landmark positions</i>
-----------	---

---

### Description

A wrapper that uses [coo\\_chull](#)

### Usage

```
ldk_chull(ldk, col = "grey40", lty = 1)
```

**Arguments**

ldk	an array (or a list) of landmarks
col	a color for drawing the convex hull
lty	an lty for drawing the convex hulls

**See Also**

[coo\\_chull](#), [chull](#), [ldk\\_confell](#), [ldk\\_contour](#)

Other plotting functions: [coo\\_arrows](#), [coo\\_draw](#), [coo\\_listpanel](#), [coo\\_lolli](#), [coo\\_plot](#), [coo\\_ruban](#), [ldk\\_confell](#), [ldk\\_contour](#), [ldk\\_labels](#), [ldk\\_links](#), [plot\\_devsegments](#), [plot\\_table](#)

Other ldk plotters: [ldk\\_confell](#), [ldk\\_contour](#), [ldk\\_labels](#), [ldk\\_links](#)

**Examples**

```
coo_plot(mshapes(wings))
ldk_chull(wings$coo)
```

---

ldk\_confell

*Draws confidence ellipses for landmark positions*

---

**Description**

Draws confidence ellipses for landmark positions

**Usage**

```
ldk_confell(ldk, conf = 0.5, col = "grey40", ell.lty = 1, ax = TRUE,
  ax.lty = 2)
```

**Arguments**

ldk	an array (or a list) of landmarks
conf	the confidence level (normal quantile, 0.5 by default)
col	the color for the ellipse
ell.lty	an lty for the ellipse
ax	logical whether to draw ellipses axes
ax.lty	an lty for ellipses axes

**See Also**

Other plotting functions: [coo\\_arrows](#), [coo\\_draw](#), [coo\\_listpanel](#), [coo\\_lolli](#), [coo\\_plot](#), [coo\\_ruban](#), [ldk\\_chull](#), [ldk\\_contour](#), [ldk\\_labels](#), [ldk\\_links](#), [plot\\_devsegments](#), [plot\\_table](#)

Other ldk plotters: [ldk\\_chull](#), [ldk\\_contour](#), [ldk\\_labels](#), [ldk\\_links](#)

**Examples**

```
coo_plot(mshapes(wings))
ldk_confell(wings$coo)
```

---

ldk_contour	<i>Draws kernel density contours around landmark</i>
-------------	--

---

**Description**

Using [kde2d](#) in the MASS package.

**Usage**

```
ldk_contour(ldk, nlevels = 5, grid.nb = 50, col = "grey60")
```

**Arguments**

ldk	an array (or a list) of landmarks
nlevels	the number of contour lines
grid.nb	the grid.nb
col	a color for drawing the contour lines

**See Also**

[kde2d](#), [ldk\\_confell](#), [ldk\\_chull](#)

Other plotting functions: [coo\\_arrows](#), [coo\\_draw](#), [coo\\_listpanel](#), [coo\\_lolli](#), [coo\\_plot](#), [coo\\_ruban](#), [ldk\\_chull](#), [ldk\\_confell](#), [ldk\\_labels](#), [ldk\\_links](#), [plot\\_devsegments](#), [plot\\_table](#)

Other ldk plotters: [ldk\\_chull](#), [ldk\\_confell](#), [ldk\\_labels](#), [ldk\\_links](#)

**Examples**

```
coo_plot(mshapes(wings))
ldk_contour(wings$coo)
```

---

ldk_labels	<i>Add landmarks labels</i>
------------	-----------------------------

---

**Description**

Add landmarks labels

**Usage**

```
ldk_labels(ldk, d = 0.05, cex = 2/3, ...)
```

**Arguments**

ldk	a matrix of (x; y) coordinates: where to plot the labels
d	how far from the coordinates, on a (centroid-landmark) segment
cex	the cex for the label
...	additional parameters to fed <a href="#">text</a>

**See Also**

Other plotting functions: [coo\\_arrows](#), [coo\\_draw](#), [coo\\_listpanel](#), [coo\\_lolli](#), [coo\\_plot](#), [coo\\_ruban](#), [ldk\\_chull](#), [ldk\\_confell](#), [ldk\\_contour](#), [ldk\\_links](#), [plot\\_devsegments](#), [plot\\_table](#)

Other ldk plotters: [ldk\\_chull](#), [ldk\\_confell](#), [ldk\\_contour](#), [ldk\\_links](#)

**Examples**

```
coo_plot(wings[1])
ldk_labels(wings[1])
# closer and smaller
coo_plot(wings[1])
ldk_labels(wings[1], d=0.05, cex=0.5)
```

---

ldk_links	<i>Draws links between landmarks</i>
-----------	--------------------------------------

---

**Description**

Cosmetics only but useful to visualize shape variation.

**Usage**

```
ldk_links(ldk, links, ...)
```

**Arguments**

ldk	a matrix of (x; y) coordinates
links	a matrix of links. On the first column the starting-id, on the second column the ending-id (id= the number of the coordinate)
...	additional parameters to fed <a href="#">segments</a>

**See Also**

Other plotting functions: [coo\\_arrows](#), [coo\\_draw](#), [coo\\_listpanel](#), [coo\\_lolli](#), [coo\\_plot](#), [coo\\_ruban](#), [ldk\\_chull](#), [ldk\\_confell](#), [ldk\\_contour](#), [ldk\\_labels](#), [plot\\_devsegments](#), [plot\\_table](#)

Other ldk plotters: [ldk\\_chull](#), [ldk\\_confell](#), [ldk\\_contour](#), [ldk\\_labels](#)

---

lf_structure	<i>bind_db.Coe &lt;- bind_db.Coo Extracts structure from filenames</i>
--------------	--

---

**Description**

If filenames are consistently named with the same character serating factors, and with every individual including its belonging levels, e.g.:

- 001\_speciesI\_siteA\_ind1\_dorsalview
- 002\_speciesI\_siteA\_ind2\_lateralview

etc., this function returns a [data.frame](#) from it that can be passed to [Out](#), [Opn](#), [Ldk](#) objects.

**Usage**

```
lf_structure(lf, names = character(), split = "_", trim.extension = FALSE)
```

**Arguments**

lf	a list (its names are used, except if it is a list from <a href="#">import_tps</a> in this case <code>names(lf\$coo)</code> is used) of a list of filenames, as characters, typically such as those obtained with <a href="#">list.files</a> . Alternatively, a path to a folder containing the files. Actually, if lf is of length 1 (a single character), the function assumes it is a path and do a <a href="#">list.files</a> on it.
names	the names of the groups, as a vector of characters which length corresponds to the number of groups.
split	character, the splitting factor used for the file names.
trim.extension	logical. Whether to remove the last for characters in filenames, typically their extension, e.g. '.jpg'.

**Details**

The number of groups must be consistent accross filenames.

**Value**

data.frame with, for every individual, the corresponding level for every group.

**Note**

This is, to my view, a good practice to 'store' the grouping structure in filenames, but it is of course not mandatory.

Note also that you can: i) do a [import\\_jpg](#) and save is a list, say 'foo'; then ii) pass 'names(foo)' to `lf_structure`. See Momocs' vignette for an illustration.

Note this function will be deprecated from Momocs when Momacs and Momit will be fully operational.

**See Also**

[import\\_jpg1](#), [import\\_Conte](#), [import\\_txt](#), [lf\\_structure](#). See also Momocs' vignettes for data import.

Other babel functions: [tie\\_jpg\\_txt](#)

---

links\_all

*Creates links (all pairwise combinations) between landmarks*

---

**Description**

Creates links (all pairwise combinations) between landmarks

**Usage**

```
links_all(coo)
```

**Arguments**

coo                    a matrix (or a list) of (x; y) coordinates

**Value**

a matrix that can be passed to [ldk\\_links](#), etc. The columns are the row ids of the original shape.

**See Also**

Other ldk helpers: [def\\_links](#), [ldk\\_check](#), [links\\_deLaunay](#)

**Examples**

```
w <- wings[1]
coo_plot(w)
links <- links_all(w)
ldk_links(w, links)
```

---

links_delaunay	<i>Creates links (Delaunay triangulation) between landmarks</i>
----------------	---

---

**Description**

Creates links (Delaunay triangulation) between landmarks

**Usage**

```
links_delaunay(coo)
```

**Arguments**

coo                    a matrix (or a list) of (x; y) coordinates

**Details**

uses [delaunayn](#) in the geometry package.

**Value**

a matrix that can be passed to [ldk\\_links](#), etc. The columns are the row ids of the original shape.

**See Also**

Other ldk helpers: [def\\_links](#), [ldk\\_check](#), [links\\_all](#)

**Examples**

```
w <- wings[1]
coo_plot(w, poly=FALSE)
links <- links_delaunay(w)
ldk_links(w, links)
```

---

MANOVA

*Multivariate analysis of (co)variance on Coe objects*

---

**Description**

Performs multivariate analysis of variance on [PCA](#) objects.

**Usage**

```
MANOVA(x, fac, test = "Hotelling", retain, drop)

## S3 method for class 'OpnCoe'
MANOVA(x, fac, test = "Hotelling", retain, drop)

## S3 method for class 'OutCoe'
MANOVA(x, fac, test = "Hotelling", retain, drop)

## S3 method for class 'PCA'
MANOVA(x, fac, test = "Hotelling", retain = 0.99, drop)
```

**Arguments**

x	a <a href="#">Coe</a> object
fac	a name of a column in the \$fac slot, or its id, or a formula
test	a test for <a href="#">manova</a> ('Hotelling' by default)
retain	how many harmonics (or polynomials) to retain, for PCA the highest number of PC axis to retain, or the proportion of the variance to capture.
drop	how many harmonics (or polynomials) to drop

**Details**

Performs a MANOVA/MANCOVA on PC scores. Just a wrapper around [manova](#). See examples for multifactorial manova and [summary.manova](#) for more details and examples.

**Value**

a list of matrices of (x,y) coordinates.

**Note**

Needs a review and should be considered as experimental. Silent message and progress bars (if any) with options("verbose"=FALSE).

**See Also**

Other multivariate: [CLUST](#), [KMEANS](#), [LDA](#), [MANOVA\\_PW](#), [PCA](#), [classification\\_metrics](#), [mshapes](#)

**Examples**

```
# MANOVA
bot.p <- PCA(efourier(bot, 12))
MANOVA(bot.p, 'type')

op <- PCA(npoly(olea, 5))
MANOVA(op, 'domes')

m <- manova(op$x[, 1:5] ~ op$fac$domes * op$fac$var)
```



```
summary(m)
summary.aov(m)

# MANCOVA example
# we create a numeric variable, based on centroid size
bot %<>% mutate(cs=coo_centsize(.))
# same pipe
bot %>% efourier %>% PCA %>% MANOVA("cs")
```

---

MANOVA\_PW

*Pairwise Multivariate analyses of variance*


---

### Description

A wrapper for pairwise [MANOVAs](#) on [Coe](#) objects. Calculates a MANOVA for every pairwise combination of the factor provided.

### Usage

```
MANOVA_PW(x, ...)

## S3 method for class 'PCA'
MANOVA_PW(x, fac, retain = 0.99, ...)
```

### Arguments

x	a <a href="#">PCA</a> object
...	more arguments to feed <a href="#">MANOVA</a>
fac	a name (or its id) of a grouping factor in \$fac or a factor or a formula.
retain	the number of PC axis to retain (1:retain) or the proportion of variance to capture (0.99 par default).

### Value

a list with the following components is returned (invisibly because \$manovas may be very long, see examples):

- manovas a list containing all the raw manovas
- summary
- stars.tab a table with 'significance stars', discutable but largely used: '' if  $\Pr(>F) < 0.001$ ; '' of  $< 0.01$ ; '' if  $< 0.05$ ; '.' if  $< 0.10$  and '-' if above.

### Note

Needs a review and should be considered as experimental. If the fac passed has only two levels, there is only pair and it is equivalent to [MANOVA](#). MANOVA\_PW.PCA works with the regular [manova](#).

**See Also**

[MANOVA](#), [manova](#).

Other multivariate: [CLUST](#), [KMEANS](#), [LDA](#), [MANOVA](#), [PCA](#), [classification\\_metrics](#), [mshapes](#)

**Examples**

```
# we create a fake factor with 4 levels
bot$fac$fake <- factor(rep(letters[1:4], each=10))
bot.p <- PCA(efourier(bot, 8))
MANOVA_PW(bot.p, 'fake') # or MANOVA_PW(bot.p, 2)

# an example on open outlines
op <- PCA(npoly(olea))
MANOVA_PW(op, 'domes')
# to get the results
res <- MANOVA_PW(op, 'domes')
res$manovas
res$stars.tab
res$summary
```

---

measure

*Measures shape descriptors*

---

**Description**

Calculates shape descriptors on Coo and other objects. Any function that returns a scalar when fed coordinates can be passed and naturally those of Momocs (pick some there apropos("coo\_")). Functions without arguments (eg [coo\\_area](#)) have to be passed without brackets but functions with arguments (eg [d](#)) have to be passed "entirely". See examples.

**Usage**

```
measure(x, ...)
```

**Arguments**

x any Coo object, or a list of shapes, or a shape as a matrix.  
 ... a list of functions. See examples.

**Value**

a [TraCoo](#) object, or a raw data.frame

**See Also**

Other premodern: [coo\\_truss](#)

### Examples

```
bm <- measure(bot, coo_area, coo_perim)
bm
bm$coe

# how to use arguments, eg with the d() function
measure(wings, coo_area, d(1, 3), d(4, 5))

# alternatively, to get a data_frame
measure(bot$coo, coo_area, coo_perim)

# and also, to get a data_frame (one row)
measure(bot[1], coo_area, coo_perim)
```

---

molars

*Data: Outline coordinates of 360 molars*

---

### Description

Courtesy of Julien Corny and Florent Detroit.

### Format

A **Out** object containing 79 equilinearly spaced (x; y) coordinates for 360 crown outlines, of modern human molars, along with their type (`$type`) - 90 first upper molars (UM1), 90 second upper molars (UM2), 90 first lower molars (LM1), 90 second lower molars (LM2) - and the individual (`ind`) they come from (the data of the 360 molars are taken from 180 individuals).

### Source

Corny, J., & Detroit, F. (2014). Technical Note: Anatomic identification of isolated modern human molars: testing Procrustes aligned outlines as a standardization procedure for elliptic fourier analysis. *American Journal of Physical Anthropology*, 153(2), 314-22. doi:10.1002/ajpa.22428 <http://onlinelibrary.wiley.com/doi/10.1002/ajpa.22428/abstract>

### See Also

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#), [wings](#)

---

Momocs

*Momocs*

---

## Description

The goal of Momocs is to provide a complete, convenient, reproducible and open-source toolkit for 2D morphometrics. It includes most common 2D morphometrics approaches on outlines, open outlines, configurations of landmarks, traditional morphometrics, and facilities for data preparation, manipulation and visualization with a consistent grammar throughout. It allows reproducible, complex morphometric analyses and other morphometrics approaches should be easy to plug in, or develop from, on top of this canvas.

## Details

To cite Momocs in publications: `citation("Momocs")`.

## Cheers

We are very grateful to (in alphabetical order): Sean Asselin, Laurent Bouby, Matt Bulbert, Simon Cramer, Julia Cooke, April Dinwiddie, Carl Lipo, Cedric Gaucherel, Catherine Girard, QGouil (GitHub), Christian Steven Hoggard, Sarah Ivorra, Glynis Jones, Nathalie Keller, Ricardo Kriebel, Remi Laffont, Fabien Lafuma, Matthias Mace, Stas Malavin, Neus Martinez, Sabrina Renaud, Marcelo Reginato, Evan Saitta, David Siddons, Eleanor Stillman, Theodore Stammer, Norbert Telmon, Jean-Frederic Terral, Bill Venables, Daniele Ventura, Michael Wallace, Asher Wishkerman, John Wood for their helpful ideas and bug reports.

## References

- Bonhomme V, Picq S, Gaucherel C, Claude J. 2014. Momocs: Outline Analysis Using R. *Journal of Statistical Software* **56**. <http://www.jstatsoft.org/v56/i13>.
- Claude J. 2008. *Morphometrics with R*. Springer-Verlag, New-York.

## See Also

- **Homepage:** <https://github.com/MomX/Momocs>
- **Issues:** <https://github.com/MomX/Momocs/issues>
- **Tutorial:** `browseVignettes("Momocs")` or <http://momx.github.io/Momocs/>
- **Email:** `bonhomme.vincent@gmail.com` to contribute to dev, ask for something, propose collaboration, share your data, etc.

---

Momocs_help	<i>Browse Momocs online doc</i>
-------------	---------------------------------

---

**Description**

Launch a browser to an online version of the manual

**Usage**

```
Momocs_help(topic = NULL)
```

**Arguments**

topic	the function name to access. If not specified the homepage of the online manual is accessed.
-------	--

**Examples**

```
## Not run:  
Momocs_help("efourier")  
  
## End(Not run)
```

---

Momocs_version	<i>Install last version of Momocs</i>
----------------	---------------------------------------

---

**Description**

Download the last version of Momocs from its GitHub account from <http://www.github.com/MomX/Momocs>, install it and load it (`library(Momocs)`). You need devtools, but it is checked anyway.

**Usage**

```
Momocs_lastversion()  
  
Momocs_currentGitHubversion()  
  
Momocs_currentCRANversion()  
  
Momocs_installedversion()
```

**Examples**

```
## Not run:  
Momocs_currentGitHubversion()  
Momocs_currentCRANversion()  
  
## End(Not run)
```

---

morphospace\_positions *Calculates nice positions on a plane for drawing shapes*

---

### Description

Calculates nice positions on a plane for drawing shapes

### Usage

```
morphospace_positions(xy, pos.shp = c("range", "full", "circle", "xy",
  "range_axes", "full_axes")[1], nb.shp = 12, nr.shp = 6, nc.shp = 5,
  circle.r.shp)
```

### Arguments

xy	a matrix of points typically from a PCA or other multivariate method on which morphospace can be calculated
pos.shp	how shapes should be positioned: range of xy, full extent of the plane, circle as a rosewind, on xy values provided, range_axes on the range of xy but on the axes, full_axes same thing but on (0.85) range of the axes. You can also directly pass a matrix (or a data.frame) with columns named ("x", "y").
nb.shp	the total number of shapes
nr.shp	the number of rows to position shapes
nc.shp	the number of cols to position shapes
circle.r.shp	if circle, its radius

### Details

See [plot.PCA](#) for self-speaking examples

---

mosaic\_engine *Plots mosaics of shapes.*

---

### Description

Will soon replace [panel](#). See examples and vignettes.

**Usage**

```

mosaic_engine(coo_list, dim, asp = 1, byrow = TRUE, fromtop = TRUE,
  sample = 60, relatively = FALSE, template_size = 0.92)

mosaic(x, ...)

## S3 method for class 'Out'
mosaic(x, f, relatively = FALSE, pal = pal_qual,
  sample = 60, paper_fun = paper_white, draw_fun = draw_outlines,
  legend = TRUE, dim = NA, asp = 1, byrow = TRUE, fromtop = TRUE, ...)

## S3 method for class 'Opn'
mosaic(x, f, relatively = FALSE, pal = pal_qual,
  sample = 60, paper_fun = paper_white, draw_fun = draw_curves,
  legend = TRUE, dim = NA, asp = 1, byrow = TRUE, fromtop = TRUE, ...)

## S3 method for class 'Ldk'
mosaic(x, f, relatively = FALSE, pal = pal_qual,
  sample = 60, paper_fun = paper_white, draw_fun = draw_landmarks,
  legend = TRUE, dim = NA, asp = 1, byrow = TRUE, fromtop = TRUE, ...)

```

**Arguments**

coo_list	list of shapes
dim	numeric of length 2, the desired dimensions for rows and columns
asp	numeric the yx ratio used to calculate dim (1 by default).
byrow	logical whether to order shapes by rows
fromtop	logical whether to order shapes from top
sample	numeric number of points to <a href="#">coo_sample</a>
relatively	logical if TRUE use <a href="#">coo_template_relatively</a> or, if FALSE (by default) <a href="#">coo_template</a> . In other words, whether to preserve size or not.
template_size	numeric to feed <a href="#">coo_template(_relatively)</a> . Only useful to add padding around shapes when the default value (0.95) is lowered.
x	any <a href="#">Coo</a> object
...	additional arguments to feed the main drawer if the number of shapes is > 1000 (default: 64). If non-numeric (eg FALSE) do not sample.
f	factor specification to feed <a href="#">fac_dispatcher</a>
pal	one of <a href="#">palettes</a>
paper_fun	a <a href="#">papers</a> function (default: paper)
draw_fun	one of <a href="#">drawers</a> for <a href="#">pile.list</a>
legend	logical whether to draw a legend (will be improved in further versions)

**Value**

a list of templated and translated shapes

**See Also**

Other grindr: [drawers](#), [layers](#), [papers](#), [pile](#), [plot\\_PCA](#)

**Examples**

```
# On Out ---
bot %>% mosaic
bot %>% mosaic(~type)

# As with other grindr functions you can continue the pipe
bot %>% mosaic(~type, asp=0.5) %>% draw_firstpoint

# On Opn ---- same grammar
olea %>% mosaic(~view+var, paper_fun=paper_dots)

# On Ldk
mosaic(wings, ~group, pal=pal_qual_Dark2, pch=3)

# On Out with different sizes
# would work on other Coo too
shapes2 <- shapes
sizes <- runif(30, 1, 2)
shapes2 %>% mosaic(relatively=FALSE)
shapes2 %>% mosaic(relatively=TRUE) %>% draw_centroid()
```

---

mosquito

*Data: Outline coordinates of mosquito wings.*

---

**Description**

Data: Outline coordinates of mosquito wings.

**Format**

A [Out](#) object with the 126 mosquito wing outlines outlines used Rohlf and Archie (1984). Note that the links defined here are quite approximate.

**Source**

Rohlf F, Archie J. 1984. A comparison of Fourier methods for the description of wing shape in mosquitoes (Diptera: Culicidae). *Systematic Biology*: 302-317. Arranged from: <http://life.bio.sunysb.edu/morph/data/RohlfArchieWingOutlines.nts>.

**See Also**

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#), [wings](#)



---

 mouse

*Data: Outline coordinates of mouse molars*


---

**Description**

Data: Outline coordinates of mouse molars

**Format**

A [Out](#) object 64 coordinates of 30 wood molar outlines.

**Source**

Renaud S, Dufour AB, Hardouin EA, Ledevin R, Auffray JC (2015): Once upon multivariate analyses: When they tell several stories about biological evolution. *PLoS One* 10:1-18 <http://journals.plos.org/plosone/article?id=10.1371/journal.pone.0132801>

**See Also**

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#), [wings](#)

---

 mshapes

*Mean shape calculation for Coe, Coe, etc.*


---

**Description**

Quite a versatile function that calculates mean (or median, or whatever function) on list or an array of shapes, an Ldk object. It can also be used on OutCoe and OpnCoe objects. In that case, the reverse transformation (from coefficients to shapes) is calculated, (within groups defined with the fac argument if provided) and the Coe object is returned.

**Usage**

```
mshapes(x, ...)
```

```
## S3 method for class 'list'
```

```
mshapes(x, FUN = mean, ...)
```

```
## S3 method for class 'array'
```

```
mshapes(x, FUN = mean, ...)
```

```
## S3 method for class 'Ldk'
```

```
mshapes(x, FUN = mean, ...)
```

```
## S3 method for class 'OutCoe'
```

```

mshapes(x, fac, FUN = mean, nb.pts = 120, ...)

## S3 method for class 'OpnCoe'
mshapes(x, fac, FUN = mean, nb.pts = 120, ...)

## S3 method for class 'LdkCoe'
mshapes(x, fac, FUN = mean, ...)

## S3 method for class 'PCA'
mshapes(x, fac, ...)

MSHAPES(x, ...)

```

### Arguments

x	a list, array, Ldk, LdkCoe, OutCoe or OpnCoe or PCA object
...	useless here.
FUN	a function to compute the mean shape ( <a href="#">mean</a> by default, by <a href="#">median</a> can be considered)
fac	factor from the \$fac slot (only for Coe objects). See examples below.
nb.pts	numeric the number of points for calculated shapes (only Coe objects)

### Details

Note that on Coe objects, the average can be made within levels of the passed \$fac (if any); in that case, the other columns of the fac are also returned, using the first row within every level, but they may not be representative of the group. Also notice that for PCA objects, mean scores are returned within a PCA object (accessible with PCA\$x) that can be plotted directly but other slots are left unchanged.

### Value

the averaged shape; on Coe objects, a list with two components: \$Coe object of the same class, and \$shp a list of matrices of (x, y) coordinates.

### See Also

Other multivariate: [CLUST](#), [KMEANS](#), [LDA](#), [MANOVA\\_PW](#), [MANOVA](#), [PCA](#), [classification\\_metrics](#)

### Examples

```

#### on shapes
mshapes(wings)
mshapes(wings$coo)
mshapes(coo_sample(bot, 24)$coo)
stack(wings)
coo_draw(mshapes(wings))

bot.f <- efourier(bot, 12)

```

```

mshapes(bot.f) # the mean (global) shape
ms <- mshapes(bot.f, 'type')
ms$Coe
class(ms$Coe)
ms <- ms$shp
coo_plot(ms$beer)
coo_draw(ms$whisky, border='forestgreen')
tps_arr(ms$whisky, ms$beer) #etc.

op <- npoly(filter(olea, view=='VL'), 5)
ms <- mshapes(op, 'var') #etc
ms$Coe
panel(Opn(ms$shp), names=TRUE)

wp <- fgProcrustes(wings, tol=1e-4)
ms <- mshapes(wp, 1)
ms$Coe
panel(Ldk(ms$shp), names=TRUE) #etc.
panel(ms$Coe) # equivalent (except the $fac slot)

```

---

mutate

*Add new variables*


---

### Description

Add new variables to the \$fac. See examples and `?dplyr::mutate`.

### Usage

```
mutate(.data, ...)
```

### Arguments

<code>.data</code>	a Coe, Coe, PCA object
<code>...</code>	comma separated list of unquoted expressions

### Details

dplyr verbs are maintained.

### Value

a Momocs object of the same class.

### See Also

Other handling functions: [arrange](#), [at\\_least](#), [chop](#), [combine](#), [dissolve](#), [fac\\_dispatcher](#), [filter](#), [rescale](#), [rm\\_harm](#), [rm\\_uncomplete](#), [rw\\_fac](#), [sample\\_frac](#), [sample\\_n](#), [select](#), [slice](#)

**Examples**

```
olea
mutate(olea, id=factor(1:length(olea)))
```

---

npoly	<i>Calculate natural polynomial fits on open outlines</i>
-------	---

---

**Description**

Calculates natural polynomial coefficients, through a linear model fit (see [lm](#)), from a matrix of (x; y) coordinates or an [Opn](#) object

**Usage**

```
npoly(x, ...)

## Default S3 method:
npoly(x, degree, ...)

## S3 method for class 'Opn'
npoly(x, degree, baseline1 = c(-0.5, 0), baseline2 = c(0.5,
  0), nb.pts = 120, ...)
```

**Arguments**

x	a matrix (or a list) of (x; y) coordinates or an <a href="#">Opn</a> object
...	useless here
degree	polynomial degree for the fit (the Intercept is also returned)
baseline1	numeric the (x; y) coordinates of the first baseline by default ( $x = -0.5; y = 0$ )
baseline2	numeric the (x; y) coordinates of the second baseline by default ( $x = 0.5; y = 0$ )
nb.pts	number of points to sample and on which to calculate polynomials

**Value**

when applied on a single shape, a list with components:

- `coeff` the coefficients (including the intercept)
- `ortho` whether orthogonal or natural polynomials were fitted
- `degree` degree of the fit (could be retrieved through `coeff` though)
- `baseline1` the first baseline point (so far the first point)
- `baseline2` the second baseline point (so far the last point)
- `r2` the r2 from the fit
- `mod` the raw `lm` model

otherwise, an [OpnCoe](#) object.

**See Also**

Other polynomials: [opoly\\_i](#), [opoly](#)

**Examples**

```
data(olea)
o <- olea[1]
op <- opoly(o, degree=4)
op
# shape reconstruction
opi <- opoly_i(op)
coo_plot(o)
coo_draw(opi, border="red")
# R2 for degree 1 to 10
r <- numeric()
for (i in 1:10) { r[i] <- npoly(o, degree=i)$r2 }
plot(2:10, r[2:10], type='b', pch=20, col='red', main='R2 / degree')
```

---

nsfishes

*Data: Outline coordinates of North Sea fishes*

---

**Description**

Data: Outline coordinates of North Sea fishes

**Format**

A [Out](#) object containing the outlines coordinates for 218 fishes from the North Sea along with taxonomical cofactors.

**Source**

Caillon F, Frelat R, Mollmann C, Bonhomme V (submitted)

**See Also**

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [oak](#), [olea](#), [shapes](#), [trilo](#), [wings](#)

---

oak

*Data: Configuration of landmarks of oak leaves*

---

### Description

From Viscosi and Cardini (2001).

### Format

A [Ldk](#) object containing 11 (x; y) landmarks from 176 oak leaves wings, from

### Source

Viscosi, V., & Cardini, A. (2011). Leaf morphology, taxonomy and geometric morphometrics: a simplified protocol for beginners. *PLoS One*, 6(10), e25630. doi:10.1371/journal.pone.0025630

### See Also

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [olea](#), [shapes](#), [trilo](#), [wings](#)

---

olea

*Data: Outline coordinates of olive seeds open outlines.*

---

### Description

Data: Outline coordinates of olive seeds open outlines.

### Format

An [Opn](#) object with the outline coordinates of olive seeds.

### Source

We thank Jean-Frederic Terral and Sarah Ivorra (UMR CBAE, Montpellier, France) from allowing us to share the data.

You can have a look to the original paper: Terral J-F, Alonso N, Capdevila RB i, Chatti N, Fabre L, Fiorentino G, Marival P, Jorda GP, Pradat B, Rovira N, et al. 2004. Historical biogeography of olive domestication (*Olea europaea* L.) as revealed by geometrical morphometry applied to biological and archaeological material. *Journal of Biogeography* **31**: 63-77.

### See Also

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [shapes](#), [trilo](#), [wings](#)

---

Opn	<i>Builds an Opn object</i>
-----	-----------------------------

---

### Description

In Momocs, Opn classes objects are lists of **open** outlines, with optionnal components, on which generic methods such as plotting methods (e.g. [stack](#)) and specific methods (e.g. [npoly](#)) can be applied. Opn objects are primarily [Coo](#) objects.

### Usage

```
Opn(x, fac = dplyr::data_frame(), ldk = list())
```

### Arguments

x	list of matrices of (x; y) coordinates
fac	(optionnal) a data.frame of factors and/or numerics specifying the grouping structure
ldk	(optionnal) list of landmarks as row number indices

### Value

an Opn object

### See Also

Other classes: [Coe](#), [Coo](#), [OpnCoe](#), [OutCoe](#), [Out](#), [TraCoe](#)

### Examples

```
#Methods on Opn
methods(class=Opn)
# we load some open outlines. See ?olea for credits
olea
panel(olea)
# orthogonal polynomials
op <- opoly(olea, degree=5)
# we print the Coe
op
# Let's do a PCA on it
op.p <- PCA(op)
plot(op.p, 'domes')
plot(op.p, 'var')
# and now an LDA after a PCA
olda <- LDA(PCA(op), 'var')
# for CV table
olda
plot(olda)
```

---

OpnCoe

*Builds an OpnCoe object*

---

## Description

In Momocs, OpnCoe classes objects are wrapping around lists of morphometric coefficients, along with other informations, on which generic methods such as plotting methods (e.g. [boxplot](#)) and specific methods can be applied. OpnCoe objects are primarily [Coe](#) objects.

## Usage

```
OpnCoe(coe = matrix(), fac = dplyr::data_frame(), method = character(),
       baseline1 = numeric(), baseline2 = numeric(), mod = list(),
       r2 = numeric())
```

## Arguments

coe	matrix of morphometric coefficients
fac	(optionnal) a <code>data.frame</code> of factors, specifying the grouping structure
method	used to obtain these coefficients
baseline1	$(x; y)$ coordinates of the first baseline point
baseline2	$(x; y)$ coordinates of the second baseline point
mod	an R <a href="#">lm</a> object, used to reconstruct shapes
r2	numeric, the r-squared from every model

## Value

an OpnCoe object

## See Also

Other classes: [Coe](#), [Coo](#), [Opn](#), [OutCoe](#), [Out](#), [TraCoe](#)

## Examples

```
# all OpnCoe classes
methods(class='OpnCoe')
```



---

 opoly

*Calculate orthogonal polynomial fits on open outlines*


---

**Description**

Calculates orthogonal polynomial coefficients, through a linear model fit (see [lm](#)), from a matrix of (x; y) coordinates or a [Opn](#) object

**Usage**

```
opoly(x, ...)

## Default S3 method:
opoly(x, degree, ...)

## S3 method for class 'Opn'
opoly(x, degree, baseline1 = c(-0.5, 0), baseline2 = c(0.5,
  0), nb.pts = 120, ...)
```

**Arguments**

x	a matrix (or a list) of (x; y) coordinates
...	useless here
degree	polynomial degree for the fit (the Intercept is also returned)
baseline1	numeric the (x; y) coordinates of the first baseline by default ( $x = -0.5; y = 0$ )
baseline2	numeric the (x; y) coordinates of the second baseline by default ( $x = 0.5; y = 0$ )
nb.pts	number of points to sample and on which to calculate polynomials

**Value**

a list with components when applied on a single shape:

- `coeff` the coefficients (including the intercept)
- `ortho` whether orthogonal or natural polynomials were fitted
- `degree` degree of the fit (could be retrieved through `coeff` though)
- `baseline1` the first baseline point (so far the first point)
- `baseline2` the second baseline point (so far the last point)
- `r2` the  $r^2$  from the fit
- `mod` the raw `lm` model

otherwise an [OpnCoe](#) object.

**Note**

Orthogonal polynomials are sometimes called Legendre's polynomials. They are preferred over natural polynomials since adding a degree do not change lower orders coefficients.

**See Also**

Other polynomials: [npoly](#), [opoly\\_i](#)

**Examples**

```
data(olea)
o <- olea[1]
op <- opoly(o, degree=4)
op
# shape reconstruction
opi <- opoly_i(op)
coo_plot(o)
coo_draw(opi)
lines(opi, col='red')
# R2 for degree 1 to 10
r <- numeric()
for (i in 1:10) { r[i] <- opoly(o, degree=i)$r2 }
plot(2:10, r[2:10], type='b', pch=20, col='red', main='R2 / degree')
```

---

opoly\_i

*Calculates shape from a polynomial model*

---

**Description**

Returns a matrix of (x; y) coordinates when passed with a list obtained with [opoly](#) or [npoly](#).

**Usage**

```
opoly_i(pol, nb.pts = 120, reregister = TRUE)
```

```
npoly_i(pol, nb.pts = 120, reregister = TRUE)
```

**Arguments**

pol	a pol list such as created by <a href="#">npoly</a> or <a href="#">opoly</a>
nb.pts	the number of points to predict. By default (and cannot be higher) the number of points in the original shape.
reregister	logical whether to reregister the shape with the original baseline.

**Value**

a matrix of (x; y) coordinates.

**See Also**

Other polynomials: [npoly](#), [opoly](#)

**Examples**

```
data(olea)
o <- olea[5]
coo_plot(o)
for (i in 2:7){
  x <- opoly_i(opoly(o, i))
  coo_draw(x, border=col_summer(7)[i], points=FALSE) }
```

---

 Out

*Builds an Out object*


---

**Description**

In Momocs, Out-classes objects are lists of closed **outlines**, with optional components, and on which generic methods such as plotting methods (e.g. [stack](#)) and specific methods (e.g. [efourier](#)) can be applied. Out objects are primarily [Coo](#) objects.

**Usage**

```
Out(x, fac = dplyr::data_frame(), ldk = list())
```

**Arguments**

x	a list of matrices of $(x; y)$ coordinates, or an array or an Out object or an Ldk object
fac	(optional) a data.frame of factors and/or numerics specifying the grouping structure
ldk	(optional) list of landmarks as row number indices

**Value**

an Out object

**See Also**

Other classes: [Coe](#), [Coo](#), [OpnCoe](#), [Opn](#), [OutCoe](#), [TraCoe](#)

**Examples**

```
methods(class=Out)
```

---

OutCoe	<i>Builds an OutCoe object</i>
--------	--------------------------------

---

### Description

In Momocs, OutCoe classes objects are wrapping around lists of morphometric coefficients, along with other informations, on which generic methods such as plotting methods (e.g. [boxplot](#)) and specific methods can be applied. OutCoe objects are primarily [Coe](#) objects.

### Usage

```
OutCoe(coe = matrix(), fac = dplyr::data_frame(), method, norm)
```

### Arguments

coe	matrix of harmonic coefficients
fac	(optional) a data.frame of factors, specifying the grouping structure
method	used to obtain these coefficients
norm	the normalisation used to obtain these coefficients

### Details

These methods can be applied on Out objects:

### Value

an OutCoe object

### See Also

Other classes: [Coe](#), [Coo](#), [OpnCoe](#), [Opn](#), [Out](#), [TraCoe](#)

### Examples

```
# all OutCoe methods  
methods(class='OutCoe')
```

---

palettes

*Color palettes*

---

### Description

All colorblind friendly RColorBrewer palettes recreated without the number of colors limitation and with transparency support thanks to `pal_alpha` that can be used alone. Also, all viridis palettes (see the [package on CRAN](#)), yet color ramps are borrowed and Momocs does not depend on it. Also, `pal_qual_solarized` based on Solarized: <http://ethanschoonover.com/solarized> and `pal_seq_grey` only shades of grey from grey10 to grey90.

### Usage

```
pal_alpha(cols, transp = 0)
pal_manual(cols, transp = 0)
pal_qual_solarized(n, transp = 0)
pal_seq_grey(n, transp = 0)
pal_div_BrBG(n, transp = 0)
pal_div_PiYG(n, transp = 0)
pal_div_PRGn(n, transp = 0)
pal_div_PuOr(n, transp = 0)
pal_div_RdBu(n, transp = 0)
pal_div_RdYlBu(n, transp = 0)
pal_qual_Dark2(n, transp = 0)
pal_qual_Paired(n, transp = 0)
pal_qual_Set2(n, transp = 0)
pal_seq_Blues(n, transp = 0)
pal_seq_BuGn(n, transp = 0)
pal_seq_BuPu(n, transp = 0)
pal_seq_GnBu(n, transp = 0)
```

```
pal_seq_Greens(n, transp = 0)
pal_seq_Greys(n, transp = 0)
pal_seq_Oranges(n, transp = 0)
pal_seq_OrRd(n, transp = 0)
pal_seq_PuBu(n, transp = 0)
pal_seq_PuBuGn(n, transp = 0)
pal_seq_PuRd(n, transp = 0)
pal_seq_Purples(n, transp = 0)
pal_seq_RdPu(n, transp = 0)
pal_seq_Reds(n, transp = 0)
pal_seq_YlGn(n, transp = 0)
pal_seq_YlGnBu(n, transp = 0)
pal_seq_YlOrBr(n, transp = 0)
pal_seq_YlOrRd(n, transp = 0)
pal_seq_magma(n, transp = 0)
pal_seq_inferno(n, transp = 0)
pal_seq_plasma(n, transp = 0)
pal_seq_viridis(n, transp = 0)
pal_qual(n, transp = 0)
pal_seq(n, transp = 0)
pal_div(n, transp = 0)
```

**Arguments**

cols	color(s) as hexadecimal values
transp	numeric between 0 and 1 (0, eg opaque, by default)
n	numeric number of colors

**Details**

Default color palettes are currently:

- pal\_qual=pal\_qual\_Set2
- pal\_seq=pal\_seq\_viridis
- pal\_div=pal\_div\_RdBu

**Note**

RColorBrewer palettes are not happy when n is lower than 3 and above a given number for each palette. If this is the case, these functions will create a color palette with [colorRampPalette](#) and return colors even so.

**Examples**

```
pal_div_BrBG(5) %>% barplot(rep(1, 5), col=.)
pal_div_BrBG(5, 0.5) %>% barplot(rep(1, 5), col=.)
```

---

panel

*Family picture of shapes*

---

**Description**

Plots all the outlines, side by side, from a [Coo](#) ([Out](#), [Opn](#) or [Ldk](#)) objects.

**Usage**

```
panel(x, ...)

## S3 method for class 'Out'
panel(x, dim, cols, borders, fac, palette = col_summer,
      coo_sample = 120, names = NULL, cex.names = 0.6, points = TRUE,
      points.pch = 3, points.cex = 0.2, points.col, ...)

## S3 method for class 'Opn'
panel(x, cols, borders, fac, palette = col_summer,
      coo_sample = 120, names = NULL, cex.names = 0.6, points = TRUE,
      points.pch = 3, points.cex = 0.2, points.col, ...)

## S3 method for class 'Ldk'
panel(x, cols, borders, fac, palette = col_summer,
      names = NULL, cex.names = 0.6, points = TRUE, points.pch = 3,
      points.cex = 0.2, points.col = "#333333", ...)
```

**Arguments**

x	The Coo object to plot.
...	additional arguments to feed generic plot
dim	for <a href="#">coo_listpanel</a> : a numeric of length 2 specifying the dimensions of the panel
cols	A vector of colors for drawing the outlines. Either a single value or of length exactly equal to the number of coordinates.
borders	A vector of colors for drawing the borders. Either a single value or of length exactly equals to the number of coordinates.
fac	a factor within the \$fac slot for colors
palette	a color <a href="#">palette</a>
coo_sample	if not NULL the number of point per shape to display (to plot quickly)
names	whether to plot names or not. If TRUE uses shape names, or something for <a href="#">fac_dispatcher</a>
cex.names	a cex for the names
points	logical (for Ldk) whether to draw points
points.pch	(for Ldk) and a pch for these points
points.cex	(for Ldk) and a cex for these points
points.col	(for Ldk) and a col for these points

**Note**

If you want to reorder shapes according to a factor, use [arrange](#).

**See Also**

Other Coo\_graphics: [inspect](#), [stack](#)

**Examples**

```
panel(mosquito, names=TRUE, cex.names=0.5)
panel(olea)
panel(bot, c(4, 10))
# an illustration of the use of fac
panel(bot, fac='type', palette=col_spring, names=TRUE)
```



---

papers

*grindr papers for shape plots*

---

### Description

Papers on which to use [drawers](#) for building custom shape plots using the *grindr* approach. See examples and vignettes.

### Usage

```
paper(coo, ...)
```

```
paper_white(coo)
```

```
paper_grid(coo, grid = c(10, 5), cols = c("#ffa500", "#e5e5e5"), ...)
```

```
paper_chess(coo, n = 50, col = "#E5E5E5")
```

```
paper_dots(coo, pch = 20, n = 50, col = "#7F7F7F")
```

### Arguments

coo	a single shape or any <a href="#">Coo</a> object
...	more arguments to feed the plotting function within each paper function
grid	numeric of length 2 to (roughly) specify the number of majors lines, and the number of minor lines within two major ones
cols	colors (hexadecimal preferred) to use for grid drawing
n	numeric number of squares for the chessboard
col	color (hexadecimal) to use for chessboard drawing
pch	to use for dots

### Note

This approach will (soon) replace [coo\\_plot](#) and friends in further versions. All comments are welcome.

### See Also

Other *grindr*: [drawers](#), [layers](#), [mosaic\\_engine](#), [pile](#), [plot\\_PCA](#)

**Description**

Performs a PCA on [Coe](#) objects, using [prcomp](#).

**Usage**

```
PCA(x, scale., center, fac)

## S3 method for class 'OutCoe'
PCA(x, scale. = FALSE, center = TRUE, fac)

## S3 method for class 'OpnCoe'
PCA(x, scale. = FALSE, center = TRUE, fac)

## S3 method for class 'LdkCoe'
PCA(x, scale. = FALSE, center = TRUE, fac)

## S3 method for class 'TraCoe'
PCA(x, scale. = TRUE, center = TRUE, fac)

## Default S3 method:
PCA(x, scale. = TRUE, center = TRUE,
    fac = dplyr::data_frame())

as_PCA(x, fac)
```

**Arguments**

x	a <a href="#">Coe</a> object or an appropriate object (eg <a href="#">prcomp</a> ) for <code>as_PCA</code>
scale.	logical whether to scale the input data
center	logical whether to center the input data
fac	any factor or data.frame to be passed to <code>as_PCA</code> and for use with <a href="#">plot.PCA</a>

**Details**

By default, methods on [Coe](#) object do not scale the input data but center them. There is also a generic method (eg for traditional morphometrics) that centers and scales data.

**Value**

a 'PCA' object on which to apply [plot.PCA](#), among others. This list has several components, most of them inherited from the `prcomp` object:

1. sdev the standard deviations of the principal components (i.e., the square roots of the eigenvalues of the covariance/correlation matrix, though the calculation is actually done with the singular values of the data matrix)
2. eig the cumulated proportion of variance along the PC axes
3. rotation the matrix of variable loadings (i.e., a matrix whose columns contain the eigenvectors). The function princomp returns this in the element loadings.
4. center, scale the centering and scaling used
5. x PCA scores (the value of the rotated data (the centred (and scaled if requested) data multiplied by the rotation matrix))
6. other components are inherited from the Coe object passed to PCA, eg fac, mshape, method, baseline1 and baseline2, etc. They are documented in the corresponding \*Coe file.

### See Also

Other multivariate: [CLUST](#), [KMEANS](#), [LDA](#), [MANOVA\\_PW](#), [MANOVA](#), [classification\\_metrics](#), [mshapes](#)

### Examples

```

bot.f <- efourier(bot, 12)
bot.p <- PCA(bot.f)
bot.p
plot(bot.p, morpho=FALSE)
plot(bot.p, 'type')

op <- npoly(olea, 5)
op.p <- PCA(op)
op.p
plot(op.p, 1, morpho=TRUE)

wp <- fgProcrustes(wings, tol=1e-4)
wpp <- PCA(wp)
wpp
plot(wpp, 1)

# "foreign prcomp"
head(iris)
iris.p <- prcomp(iris[, 1:4])
iris.p <- as_PCA(iris.p, iris[, 5])
class(iris.p)
plot(iris.p, 1)

```

### Description

Calculates and plots shape variation along Principal Component axes.

**Usage**

```
PCcontrib(PCA, ...)

## S3 method for class 'PCA'
PCcontrib(PCA, nax, sd.r = c(-2, -1, -0.5, 0, 0.5, 1, 2),
          gap = 1, ...)
```

**Arguments**

PCA	a PCA object
...	additional parameter to pass to <code>coo_draw</code>
nax	the range of PCs to plot (1 to 99pc total variance by default)
sd.r	a single or a range of mean +/- sd values (eg: <code>c(-1, 0, 1)</code> )
gap	for combined-Coe, an adjustment variable for gap between shapes. (bug)Default to 1 (whish should never superimpose shapes), reduce it to get a more compact plot.

**Value**

(invisibly) a list with `gg` the ggplot object and `shp` the list of shapes.

**Examples**

```
bot.p <- PCA(efourier(bot, 12))
PCcontrib(bot.p)
## Not run:
library(ggplot2)
gg <- PCcontrib(bot.p, nax=1:8, sd.r=c(-5, -3, -2, -1, -0.5, 0, 0.5, 1, 2, 3, 5))
gg + geom_polygon(fill="slategrey", col="black") + ggtitle("A nice title")

## End(Not run)
```

---

perm

*Permutes and breed Coe (and others) objects*


---

**Description**

This methods applies permutations column-wise on the coe of any `Coe` object but relies on a function that can be used on any matrix. For a `Coe` object, it uses `sample` on every column (or row) with (or without) replacement.

**Usage**

```
perm(x, ...)  
  
## Default S3 method:  
perm(x, margin = 2, size, replace = TRUE, ...)  
  
## S3 method for class 'Coe'  
perm(x, size, replace = TRUE, ...)
```

**Arguments**

x	the object to permute
...	useless here
margin	numeric whether 1 or 2 (rows or columns)
size	numeric the required size for the final object, same size by default.
replace	logical, whether to use <a href="#">sample</a> with replacement

**See Also**

Other farming: [breed](#)

**Examples**

```
m <- matrix(1:12, nrow=3)  
m  
perm(m, margin=2, size=5)  
perm(m, margin=1, size=10)  
  
bot.f <- efourier(bot, 12)  
bot.m <- perm(bot.f, 80)  
bot.m
```

---

pile

*Graphical pile of shapes*

---

**Description**

Pile all shapes in the same graphical window. Useful to check their normalization in terms of size, position, rotation, first point, etc. It is, essentially, a shortcut around `paper + drawers` of the `grindr` family.

**Usage**

```

pile(coo, f, sample, subset, pal, paper_fun, draw_fun, transp, ...)

## Default S3 method:
pile(coo, f, sample, subset, pal = pal_qual,
     paper_fun = paper, draw_fun = draw_curves, transp = 0, ...)

## S3 method for class 'list'
pile(coo, f, sample = 64, subset = 1000, pal = pal_qual,
     paper_fun = paper, draw_fun = draw_curves, transp = 0, ...)

## S3 method for class 'array'
pile(coo, f, sample = 64, subset = 1000, pal = pal_qual,
     paper_fun = paper, draw_fun = draw_landmarks, transp = 0, ...)

## S3 method for class 'Out'
pile(coo, f, sample = 64, subset = 1000, pal = pal_qual,
     paper_fun = paper, draw_fun = draw_outlines, transp = 0, ...)

## S3 method for class 'Opn'
pile(coo, f, sample = 64, subset = 1000, pal = pal_qual,
     paper_fun = paper, draw_fun = draw_curves, transp = 0, ...)

## S3 method for class 'Ldk'
pile(coo, f, sample = 64, subset = 1000, pal = pal_qual,
     paper_fun = paper, draw_fun = draw_landmarks, transp = 0, ...)

```

**Arguments**

coo	a single shape or any <a href="#">Coo</a> object
f	factor specification
sample	numeric number of points to <a href="#">coo_sample</a> if the number of shapes is > 1000 (default: 64). If non-numeric (eg FALSE) do not sample.
subset	numeric only draw this number of (randomly chosen) shapes if the number of shapes is > 1000 (default: 1000) If non-numeric (eg FALSE) do not sample.
pal	palette among <a href="#">palettes</a> (default: pal_qual)
paper_fun	a <a href="#">papers</a> function (default: paper)
draw_fun	one of <a href="#">drawers</a> for <code>pile.list</code>
transp	numeric for transparency (default:adjusted, min:0, max=0)
...	more arguments to feed the core drawer, depending on the object

**Details**

Large Coo are sampled, both in terms of the number of shapes and of points to drawn.

**Note**

A variation of this plot was called `stack` before Momocs 1.2.5

**See Also**

Other `grindr`: [drawers](#), [layers](#), [mosaic\\_engine](#), [papers](#), [plot\\_PCA](#)

**Examples**

```
# all Coo are supported with sensible defaults
pile(bot) # outlines
pile(olea, ~var, pal=pal_qual_Dark2, paper_fun=paper_grid) # curves
pile(wings) # landmarks

# you can continue the pipe with compatible drawers
pile(bot, trans=0.9) %>% draw_centroid

# if you are not happy with this, build your own !
# eg see Momocs::pile.Out (no quotes)

my_pile <- function(x, col_labels="red", transp=0.5){
  x %>% paper_chess(n=100) %>%
    draw_landmarks(transp=transp) %>%
    draw_labels(col=col_labels)
}
# using it
wings %>% my_pile(transp=3/4)

# and as gridr functions propagate, you can even continue:
wings %>% my_pile() %>% draw_centroid(col="blue", cex=5)

# method on lists
bot$coo %>% pile

# it can be tuned when we have a list of landmarks with:
wings$coo %>% pile(draw_fun=draw_landmarks)

# or on arrays (turn for draw_landmarks)
wings$coo %>% l2a %>% #we now have an array
pile
```

---

pix2chc

*Convert (x; y) coordinates to chaincoded coordinates*

---

**Description**

Useful to convert (x; y) coordinates to chain-coded coordinates.

**Usage**

```
pix2chc(coo)
```

```
chc2pix(chc)
```

**Arguments**

coo (x; y) coordinates passed as a matrix

chc chain coordinates

**Note**

Note this function will be deprecated from Momocs when Momacs and Momit will be fully operational.

**References**

Kuhl, F. P., & Giardina, C. R. (1982). Elliptic Fourier features of a closed contour. *Computer Graphics and Image Processing*, 18(3), 236-258.

**See Also**

[chc2pix](#)

Other import functions: [import\\_Conte](#), [import\\_StereoMorph\\_curve1](#), [import\\_jpg1](#), [import\\_jpg](#), [import\\_tps](#), [import\\_txt](#)

Other import functions: [import\\_Conte](#), [import\\_StereoMorph\\_curve1](#), [import\\_jpg1](#), [import\\_jpg](#), [import\\_tps](#), [import\\_txt](#)

**Examples**

```
pix2chc(shapes[1]) %T>% print %>% # from pix to chc
chc2pix() # and back
```

**Description**

The Momocs' [LDA](#) plotter with many graphical options.



**Usage**

```
## S3 method for class 'LDA'
plot(x, fac = x$fac, xax = 1, yax = 2, points = TRUE,
     col = "#000000", pch = 20, cex = 0.5, palette = col_solarized,
     center.origin = FALSE, zoom = 1, xlim = NULL, ylim = NULL,
     bg = par("bg"), grid = TRUE, nb.grids = 3, morphospace = FALSE,
     pos.shp = c("range", "full", "circle", "xy", "range_axes", "full_axes")[1],
     amp.shp = 1, size.shp = 1, nb.shp = 12, nr.shp = 6, nc.shp = 5,
     rotate.shp = 0, flipx.shp = FALSE, flipy.shp = FALSE, pts.shp = 60,
     border.shp = col_alpha("#000000", 0.5), lwd.shp = 1,
     col.shp = col_alpha("#000000", 0.95), stars = FALSE, ellipses = FALSE,
     conf.ellipses = 0.5, ellipsesax = TRUE, conf.ellipsesax = c(0.5, 0.9),
     lty.ellipsesax = 1, lwd.ellipsesax = sqrt(2), chull = FALSE,
     chull.lty = 1, chull.filled = FALSE, chull.filled.alpha = 0.92,
     density = FALSE, lev.density = 20, contour = FALSE, lev.contour = 3,
     n.kde2d = 100, delaunay = FALSE, loadings = FALSE,
     labelspoints = FALSE, col.labelspoints = par("fg"),
     cex.labelspoints = 0.6, abbreviate.labelspoints = TRUE,
     labelsgroups = TRUE, cex.labelsgroups = 0.8, rect.labelsgroups = FALSE,
     abbreviate.labelsgroups = FALSE, color.legend = FALSE, axisnames = TRUE,
     axisvar = TRUE, unit = FALSE, eigen = TRUE, rug = TRUE,
     title = substitute(x), box = TRUE, old.par = TRUE, ...)
```

**Arguments**

x	an object of class "LDA", typically obtained with <a href="#">LDA</a>
fac	name or the column id from the \$fac slot, or a formula combining column names from the \$fac slot (cf. examples). A factor or a numeric of the same length can also be passed on the fly.
xax	the first PC axis
yax	the second PC axis
points	logical whether to plot points
col	a color for the points (either global, for every level of the fac or for every individual, see examples)
pch	a pch for the points (either global, for every level of the fac or for every individual, see examples)
cex	the size of the points
palette	a <a href="#">palette</a>
center.origin	logical whether to center the plot onto the origin
zoom	to keep your distances
xlim	numeric of length two ; if provided along with ylim, the x and y limits to use
ylim	numeric of length two ; if provided along with xlim, the x and y limits to use
bg	color for the background
grid	logical whether to draw a grid

nb.grids	and how many of them
morphospace	logical whether to add the morphological space
pos.shp	passed to <a href="#">morphospace_positions</a> , one of "range", "full", "circle", "xy", "range_axes", "full" Or directly a matrix of positions. See <a href="#">morphospace_positions</a>
amp.shp	amplification factor for shape deformation
size.shp	the size of the shapes
nb.shp	(pos.shp="circle") the number of shapes on the compass
nr.shp	(pos.shp="full" or "range) the number of shapes per row
nc.shp	(pos.shp="full" or "range) the number of shapes per column
rotate.shp	angle in radians to rotate shapes (if several methods, a vector of angles)
flipx.shp	same as above, whether to apply <code>coo_flipx</code>
flipy.shp	same as above, whether to apply <code>coo_flipy</code>
pts.shp	the number of points fro drawing shapes
border.shp	the border color of the shapes
lwd.shp	the line width for these shapes
col.shp	the color of the shapes
stars	logical whether to draw "stars"
ellipses	logical whether to draw confidence ellipses
conf.ellipses	numeric the quantile for the (bivariate gaussian) confidence ellipses
ellipsesax	logical whether to draw ellipse axes
conf.ellipsesax	one or more numeric, the quantiles for the (bivariate gaussian) ellipses axes
lty.ellipsesax	if yes, the lty with which to draw these axes
lwd.ellipsesax	if yes, one or more numeric for the line widths
chull	logical whether to draw a convex hull
chull.lty	if yes, its linetype
chull.filled	logical whether to add filled convex hulls
chull.filled.alpha	numeric alpha transparency
density	whether to add a 2d density kernel estimation (based on <a href="#">kde2d</a> )
lev.density	if yes, the number of levels to plot (through <a href="#">image</a> )
contour	whether to add contour lines based on 2d density kernel
lev.contour	if yes, the (approximate) number of lines to draw
n.kde2d	the number of bins for <a href="#">kde2d</a> , ie the 'smoothness' of density kernel
deLaunay	logical whether to add a delaunay 'mesh' between points
loadings	logical whether to add loadings for every variables
labelspoints	if TRUE rownames are used as labels, a colname from \$fac can also be passed
col.labelspoints	a color for these labels, otherwise inherited from fac

```

cex.labelspoints      a cex for these labels
abbreviate.labelspoints logical whether to abbreviate
labelsgroups          logical whether to add labels for groups
cex.labelsgroups      ifyes, a numeric for the size of the labels
rect.labelsgroups     logical whether to add a rectangle behind groups names
abbreviate.labelsgroups logical, whether to abbreviate group names
color.legend          logical whether to add a (cheap) color legend for numeric fac
axisnames             logical whether to add PC names
axisvar              logical whether to draw the variance they explain
unit                 logical whether to add plane unit
eigen                logical whether to draw a plot of the eigen values
rug                  logical whether to add rug to margins
title                character a name for the plot
box                  whether to draw a box around the plotting region
old.par              whether to restore the old par. Set it to FALSE if you want to reuse the graphical
                    window.
...                 useless here, just to fit the generic plot

```

### Details

Widely inspired by the "layers" philosophy behind graphical functions of the `ade4` R package.

### Note

Morphospaces are deprecated so far. 99 is shared with [plot.PCA](#) waiting for a general rewriting of a multivariate plotter. See <https://github.com/vbonhomme/Momocs/issues/121>

### See Also

[LDA](#), [plot\\_CV](#), [plot\\_CV2](#), [plot.PCA](#).

### Examples

```

bot.f <- efourier(bot, 24)
bot.l <- LDA(PCA(bot.f), "type")
plot(bot.l)

bot.f$fac$fake <- factor(rep(letters[1:4], each=10))
bot.l <- LDA(PCA(bot.f), "fake")
plot(bot.l)

```

**Description**

The Momocs' [PCA](#) plotter with morphospaces and many graphical options.

**Usage**

```
## S3 method for class 'PCA'
plot(x, fac, xax = 1, yax = 2, points = TRUE,
     col = "#000000", pch = 20, cex = 0.5, palette = col_solarized,
     center.origin = FALSE, zoom = 1, xlim = NULL, ylim = NULL,
     bg = par("bg"), grid = TRUE, nb.grids = 3, morphospace = TRUE,
     pos.shp = c("range", "full", "circle", "xy", "range_axes", "full_axes")[1],
     amp.shp = 1, size.shp = 1, nb.shp = 12, nr.shp = 6, nc.shp = 5,
     rotate.shp = 0, flipx.shp = FALSE, flipy.shp = FALSE, pts.shp = 60,
     border.shp = col_alpha("#000000", 0.5), lwd.shp = 1,
     col.shp = col_alpha("#000000", 0.95), stars = FALSE, ellipses = FALSE,
     conf.ellipses = 0.5, ellipsesax = FALSE, conf.ellipsesax = c(0.5, 0.9),
     lty.ellipsesax = 1, lwd.ellipsesax = sqrt(2), chull = FALSE,
     chull.lty = 1, chull.filled = TRUE, chull.filled.alpha = 0.92,
     density = FALSE, lev.density = 20, contour = FALSE, lev.contour = 3,
     n.kde2d = 100, delaunay = FALSE, loadings = FALSE,
     labelspoints = FALSE, col.labelspoints = par("fg"),
     cex.labelspoints = 0.6, abbreviate.labelspoints = TRUE,
     labelsgroups = TRUE, cex.labelsgroups = 0.8, rect.labelsgroups = FALSE,
     abbreviate.labelsgroups = FALSE, color.legend = FALSE, axisnames = TRUE,
     axisvar = TRUE, unit = FALSE, eigen = TRUE, rug = TRUE,
     title = substitute(x), box = TRUE, old.par = TRUE, ...)
```

**Arguments**

x	PCA, typically obtained with <a href="#">PCA</a>
fac	name or the column id from the \$fac slot, or a formula combining column names from the \$fac slot (cf. examples). A factor or a numeric of the same length can also be passed on the fly.
xax	the first PC axis
yax	the second PC axis
points	logical whether to plot points
col	a color for the points (either global, for every level of the fac or for every individual, see examples)
pch	a pch for the points (either global, for every level of the fac or for every individual, see examples)
cex	the size of the points

palette	a <a href="#">palette</a>
center.origin	logical whether to center the plot onto the origin
zoom	to keep your distances
xlim	numeric of length two ; if provided along with ylim, the x and y lims to use
ylim	numeric of length two ; if provided along with xlim, the x and y lims to use
bg	color for the background
grid	logical whether to draw a grid
nb.grids	and how many of them
morphospace	logical whether to add the morphological space
pos.shp	passed to <a href="#">morphospace_positions</a> , one of "range", "full", "circle", "xy", "range_axes", "full" Or directly a matrix of positions. See <a href="#">morphospace_positions</a>
amp.shp	amplification factor for shape deformation
size.shp	the size of the shapes
nb.shp	(pos.shp="circle") the number of shapes on the compass
nr.shp	(pos.shp="full" or "range") the number of shapes per row
nc.shp	(pos.shp="full" or "range") the number of shapes per column
rotate.shp	angle in radians to rotate shapes (if several methods, a vector of angles)
flipx.shp	same as above, whether to apply <code>coo_flipx</code>
flipy.shp	same as above, whether to apply <code>coo_flipy</code>
pts.shp	the number of points fro drawing shapes
border.shp	the border color of the shapes
lwd.shp	the line width for these shapes
col.shp	the color of the shapes
stars	logical whether to draw "stars"
ellipses	logical whether to draw confidence ellipses
conf.ellipses	numeric the quantile for the (bivariate gaussian) confidence ellipses
ellipsesax	logical whether to draw ellipse axes
conf.ellipsesax	one or more numeric, the quantiles for the (bivariate gaussian) ellipses axes
lty.ellipsesax	if yes, the lty with which to draw these axes
lwd.ellipsesax	if yes, one or more numeric for the line widths
chull	logical whether to draw a convex hull
chull.lty	if yes, its linetype
chull.filled	logical whether to add filled convex hulls
chull.filled.alpha	numeric alpha transparency
density	whether to add a 2d density kernel estimation (based on <a href="#">kde2d</a> )
lev.density	if yes, the number of levels to plot (through <a href="#">image</a> )

contour	whether to add contour lines based on 2d density kernel
lev.contour	if yes, the (approximate) number of lines to draw
n.kde2d	the number of bins for <a href="#">kde2d</a> , ie the 'smoothness' of density kernel
delaunay	logical whether to add a delaunay 'mesh' between points
loadings	logical whether to add loadings for every variables
labelspoints	if TRUE rownames are used as labels, a colname from \$fac can also be passed
col.labelspoints	a color for these labels, otherwise inherited from fac
cex.labelspoints	a cex for these labels
abbreviate.labelspoints	logical whether to abbreviate
labelsgroups	logical whether to add labels for groups
cex.labelsgroups	if yes, a numeric for the size of the labels
rect.labelsgroups	logical whether to add a rectangle behind groups names
abbreviate.labelsgroups	logical, whether to abbreviate group names
color.legend	logical whether to add a (cheap) color legend for numeric fac
axisnames	logical whether to add PC names
axisvar	logical whether to draw the variance they explain
unit	logical whether to add plane unit
eigen	logical whether to draw a plot of the eigen values
rug	logical whether to add rug to margins
title	character a name for the plot
box	whether to draw a box around the plotting region
old.par	whether to restore the old <a href="#">par</a> . Set it to FALSE if you want to reuse the graphical window.
...	useless here, just to fit the generic plot

### Details

Widely inspired by the "layers" philosophy behind graphical functions of the [ade4](#) R package.

### Note

NAs in \$fac are handled quite experimentally. More importantly, as of early 2018, I plan I complete rewrite of [plot.PCA](#) and other multivariate plotters.

### See Also

[plot.LDA](#)

**Examples**

```

## Not run:
bot.f <- efourier(bot, 12)
bot.p <- PCA(bot.f)

### Morphospace options
plot(bot.p, pos.shp="full")
plot(bot.p, pos.shp="range")
plot(bot.p, pos.shp="xy")
plot(bot.p, pos.shp="circle")
plot(bot.p, pos.shp="range_axes")
plot(bot.p, pos.shp="full_axes")

plot(bot.p, morpho=FALSE)

### Passing factors to plot.PCA
# 3 equivalent methods
plot(bot.p, "type")
plot(bot.p, 1)
plot(bot.p, ~type)

# let's create a dummy factor of the correct length
# and another added to the $fac with mutate
# and a numeric of the correct length
f <- factor(rep(letters[1:2], 20))
z <- factor(rep(LETTERS[1:2], 20))
bot %<>% mutate(cs=coo_centsize(.), z=z)
bp <- bot %>% efourier %>% PCA
# so bp contains type, cs (numeric) and z; not f
# yet f can be passed on the fly
plot(bp, f)
# numeric fac are allowed
plot(bp, "cs", cex=3, color.legend=TRUE)
# formula allows combinations of factors
plot(bp, ~type+z)

### other morphometric approaches works the same
# open curves
op <- npoly(olea, 5)
op.p <- PCA(op)
op.p
plot(op.p, ~ domes + var, morpho=TRUE) # use of formula

# landmarks
wp <- fgProcrustes(wings, tol=1e-4)
wpp <- PCA(wp)
wpp
plot(wpp, 1)

# traditional measurements
flower %>% PCA %>% plot(1)

```

```

# plot.PCA can be used after a PCA
PCA(iris[, 1:4], fac=iris$Species) %>% plot(1)

### Cosmetic options
# window
plot(bp, 1, zoom=2)
plot(bp, zoom=0.5)
plot(bp, center.origin=FALSE, grid=FALSE)

# colors
plot(bp, col="red") # globally
plot(bp, 1, col=c("#00FF00", "#0000FF")) # for every level
# a color vector of the right length
plot(bp, 1, col=rep(c("#00FF00", "#0000FF"), each=20))
# a color vector of the right length, mixign Rcolor names (not a good idea though)
plot(bp, 1, col=rep(c("#00FF00", "forestgreen"), each=20))

# ellipses
plot(bp, 1, conf.ellipsesax=2/3)
plot(bp, 1, ellipsesax=FALSE)
plot(bp, 1, ellipsesax=TRUE, ellipses=TRUE)

# stars
plot(bp, 1, stars=TRUE, ellipsesax=FALSE)

# convex hulls
plot(bp, 1, chull=TRUE)
plot(bp, 1, chull.lty=3)

# filled convex hulls
plot(bp, 1, chull.filled=TRUE)
plot(bp, 1, chull.filled.alpha = 0.8, chull.lty = 1) # you can omit chull.filled=TRUE

# density kernel
plot(bp, 1, density=TRUE, contour=TRUE, lev.contour=10)

# delaunay
plot(bp, 1, delaunay=TRUE)

# loadings
flower %>% PCA %>% plot(1, loadings=TRUE)

# point/group labelling
plot(bp, 1, labelspoint=TRUE) # see options for abbreviations
plot(bp, 1, labelsgroup=TRUE) # see options for abbreviations

# clean axes, no rug, no border, random title
plot(bp, axisvar=FALSE, axisnames=FALSE, rug=FALSE, box=FALSE, title="random")

# no eigen
plot(bp, eigen=FALSE) # eigen cause troubles to graphical window
# eigen may causes troubles to the graphical window. you can try old.par = TRUE

```



```
## End(Not run)
```

---

plot_CV	<i>Plots a cross-validation table as an heatmap</i>
---------	---

---

### Description

Either with frequencies (or percentages) plus marginal sums, and values as heatmaps. Used in Momocs for plotting cross-validation tables but may be used for any table (likely with freq=FALSE).

### Usage

```
plot_CV(x, ...)
```

## Default S3 method:

```
plot_CV(x, freq = FALSE, rm0 = TRUE, cex = 5,
        round = 2, labels = TRUE, ...)
```

## S3 method for class 'LDA'

```
plot_CV(x, freq = FALSE, rm0 = TRUE, cex = 5, round = 2,
        labels = TRUE, ...)
```

### Arguments

x	a (cross-validation table) or an LDA object
...	only used for the generic
freq	logical whether to display frequencies or counts
rm0	logical whether to remove zeros
cex	numeric to adjust labels in every cell. NA to remove them
round	numeric, when freq=TRUE how many decimals should we display
labels	logical whether to display freq or counts as text labels

### Value

a ggplot object

### See Also

[LDA](#), [plot.LDA](#), and (pretty much the same) [plot\\_table](#).

**Examples**

```
o1 <- LDA(PCA(opoly(olea, 5)), "domes")
# freq=FALSE inspired by Chitwood et al. New Phytol fig. 4
gg <- plot_CV(o1, freq=FALSE)
gg

# and you can tune the gg object wit regular ggplot2 syntax eg
gg + ggplot2::scale_color_discrete(h = c(120, 240))

# freq=TRUE
plot_CV(o1, freq=TRUE)
```

---

plot\_CV2

*Plots a cross-correlation table*


---

**Description**

Or any contingency/confusion table. A simple graphic representation based on variable width and/or color for arrows or segments, based on the relative frequencies.

**Usage**

```
plot_CV2(x, ...)

## S3 method for class 'LDA'
plot_CV2(x, ...)

## S3 method for class 'table'
plot_CV2(x, links.FUN = arrows, col = TRUE,
  col0 = "black", col.breaks = 5, palette = col_heat, lwd = TRUE,
  lwd0 = 5, gap.dots = 0.2, pch.dots = 20, gap.names = 0.25,
  cex.names = 1, legend = TRUE, ...)
```

**Arguments**

x	an <a href="#">LDA</a> object, a table or a squared matrix
...	useless here.
links.FUN	a function to draw the links: eg <a href="#">segments</a> (by default), <a href="#">arrows</a> , etc.
col	logical whether to vary the color of the links
col0	a color for the default link (when col = FALSE)
col.breaks	the number of different colors
palette	a color palette, eg <a href="#">col_summer</a> , <a href="#">col_hot</a> , etc.
lwd	logical whether to vary the width of the links
lwd0	a width for the default link (when lwd = FALSE)
gap.dots	numeric to set space between the dots and the links

pch.dots	a pch for the dots
gap.names	numeric to set the space between the dots and the group names
cex.names	a cex for the names
legend	logical whether to add a legend

**See Also**

[LDA](#), [plot.LDA](#), [plot\\_CV](#).

**Examples**

```
# Below various table that you can try. We will use the last one for the examples.
## Not run:
#pure random
a <- sample(rep(letters[1:4], each=10))
b <- sample(rep(letters[1:4], each=10))
tab <- table(a, b)

# veryhuge + some structure
a <- sample(rep(letters[1:10], each=10))
b <- sample(rep(letters[1:10], each=10))
tab <- table(a, b)
diag(tab) <- round(runif(10, 10, 20))

tab <- matrix(c(8, 3, 1, 0, 0,
               2, 7, 1, 2, 3,
               3, 5, 9, 1, 1,
               1, 1, 2, 7, 1,
               0, 9, 1, 4, 5), 5, 5, byrow=TRUE)
tab <- as.table(tab)

## End(Not run)
# good prediction
tab <- matrix(c(8, 1, 1, 0, 0,
               1, 7, 1, 0, 0,
               1, 2, 9, 1, 0,
               1, 1, 1, 7, 1,
               0, 0, 0, 1, 8), 5, 5, byrow=TRUE)
tab <- as.table(tab)

plot_CV2(tab)
plot_CV2(tab, arrows) # if you prefer arrows
plot_CV2(tab, lwd=FALSE, lwd0=1, palette=col_india) # if you like india but not lwd
plot_CV2(tab, col=FALSE, col0='pink') # only lwd
plot_CV2(tab, col=FALSE, lwd0=10, cex.names=2) # if you're getting old
plot_CV2(tab, col=FALSE, lwd=FALSE) # pretty but useless
plot_CV2(tab, col.breaks=2) # if you think it's either good or bad
plot_CV2(tab, pch=NA) # if you do not like dots
plot_CV2(tab, gap.dots=0) # if you want to 'fill the gap'
plot_CV2(tab, gap.dots=1) # or not
```

```
#trilo examples
trilo.f <- efourier(trilo, 8)
trilo.l <- LDA(PCA(trilo.f), 'onto')
trilo.l
plot_CV2(trilo.l)

# olea example
op <- opoly(olea, 5)
opl <- LDA(PCA(op), 'var')
plot_CV2(opl)
```

---

plot\_devsegments      *Draws colored segments from a matrix of coordinates.*

---

### Description

Given a matrix of (x; y) coordinates, draws segments between every points defined by the row of the matrix and uses a color to display an information.

### Usage

```
plot_devsegments(coo, cols, lwd = 1)
```

### Arguments

coo	A matrix of coordinates.
cols	A vector of color of length = nrow(coo).
lwd	The lwd to use for drawing segments.

### See Also

Other plotting functions: [coo\\_arrows](#), [coo\\_draw](#), [coo\\_listpanel](#), [coo\\_lolli](#), [coo\\_plot](#), [coo\\_ruban](#), [ldk\\_chull](#), [ldk\\_confell](#), [ldk\\_contour](#), [ldk\\_labels](#), [ldk\\_links](#), [plot\\_table](#)

### Examples

```
# we load some data
guinness <- coo_sample(bot[9], 100)

# we calculate the diff between 48 harm and one with 6 harm.
out.6 <- efourier_i(efourier(guinness, nb.h=6), nb.pts=120)

# we calculate deviations, you can also try 'edm'
dev <- edm_nearest(out.6, guinness) / coo_centsize(out.6)

# we prepare the color scale
d.cut <- cut(dev, breaks=20, labels=FALSE, include.lowest=TRUE)
```

```
cols <- paste0(col_summer(20)[d.cut], 'CC')

# we draw the results
coo_plot(guinness, main='Guinness fitted with 6 harm.', points=FALSE)
par(xpd=NA)
plot_devsegments(out.6, cols=cols, lwd=4)
coo_draw(out.6, lty=2, points=FALSE, col=NA)
par(xpd=FALSE)
```

---

plot\_mshapes

*Pairwise comparison of a list of shapes*


---

## Description

"Confusion matrix" of a list of shapes. See examples.

## Usage

```
plot_mshapes(x, size = 3/4, col2 = "#FF0000")
```

## Arguments

x	a list of shapes (eg as returned by <a href="#">mshapes</a> )
size	numeric shrinking factor for shapes (and <a href="#">coo_template</a> ; 3/4 by default)
col2	color as hexadecimal ("#FF0000", eg red, by default)

## Note

Inspired by Chitwood et al. (2016) *New Phytologist*

## Examples

```
bot %>% efourier(6) %>% mshapes("type") %>% plot_mshapes
# above, a shortcut for working with the result of mshapes
# but works on list of shapes, eg:
leaves <- shapes %>% slice(grep("leaf", names(shapes))) %$% coo
class(leaves)
leaves %>% plot_mshapes(col2="#0000FF")
```

---

 plot\_PCA

*Multivariate plots using grindr layers*


---

### Description

Quickly visualize [PCA](#) objects and friends ([LDA](#)) and build custom plots using the [layers](#). See [examples](#).

### Usage

```
plot_PCA(x, f, axes = c(1, 2), palette = pal_qual, points = TRUE,
         points_transp = 1/4, morphospace = TRUE, morphospace_position = "range",
         chull = TRUE, chullfilled = FALSE, center_origin = TRUE, zoom = 0.9,
         eigen = TRUE, box = TRUE, axesnames = TRUE, axesvar = TRUE)
```

### Arguments

x	PCA object
f	factor. A column name or number from \$fac, or a factor can directly be passed. Accept numeric as well.
axes	numeric of length two to select PCs to use (c(1, 2) by default)
palette	color palette to use col_summer by default
points	logical whether to draw this with <a href="#">layer_points</a>
points_transp	numeric to feed <a href="#">layer_points</a> (default:0.25)
morphospace	logical whether to draw this using <a href="#">layer_morphospace</a>
morphospace_position	to feed <a href="#">layer_morphospace</a> (default: "range")
chull	logical whether to draw this with <a href="#">layer_chull</a>
chullfilled	logical whether to draw this with <a href="#">layer_chullfilled</a>
center_origin	logical whether to center origin
zoom	numeric zoom level for the frame (default: 0.9)
eigen	logical whether to draw this using <a href="#">layer_eigen</a>
box	logical whether to draw this using <a href="#">layer_box</a>
axesnames	logical whether to draw this using <a href="#">layer_axesnames</a>
axesvar	logical whether to draw this using <a href="#">layer_axesvar</a>

### Note

This approach will replace [plot.PCA](#) (and `plot.lda` in further versions). This is part of `grindr` approach that may be packaged at some point. All comments are welcome.

**See Also**

Other grindr: [drawers](#), [layers](#), [mosaic\\_engine](#), [papers](#), [pile](#)

**Examples**

```
### First prepare two PCA objects.

# Some outlines with bot
bp <- bot %>% mutate(fake=sample(letters[1:5], 40, replace=TRUE)) %>%
efourier(6) %>% PCA
plot_PCA(bp)
plot_PCA(bp, ~type)
plot_PCA(bp, ~fake)

# Some curves with olea
op <- olea %>%
mutate(s=coo_area(.)) %>%
filter(var != "Cypre") %>%
chop(~view) %>% lapply(opoly, 5, nb.pts=90) %>%
combine %>% PCA
op$fac$s %<>% as.character() %>% as.numeric()

op %>% plot_PCA

### Now we can play with layers
# and for instance build a custom plot
# it should start with plot_PCA()

my_plot <- function(x, ...){
  x %>%
    plot_PCA(...) %>%
    layer_points %>%
    layer_ellipsesaxes %>%
    layer_rug
}

# and even continue after this function
op %>% my_plot(~var, axes=c(1, 3)) %>%
  layer_title("hi there!") %>%
  layer_stars()

# You get the idea.
```

---

plot\_table

*Plots confusion matrix of sample sizes within \$fac*

---

**Description**

An utility that plots a confusion matrix of sample size (or a barplot) for every object with a \$fac. Useful to visually how large are sample sizes, how (un)balanced are designs, etc.

**Usage**

```
plot_table(x, fac1, fac2 = fac1, rm0 = FALSE)
```

**Arguments**

x	any object with a \$fac slot (Coo, Coe, PCA, etc.)
fac1	the name or id of the first factor
fac2	the name of id of the second factor
rm0	logical whether to print zeros

**Value**

a ggplot2 object

**See Also**

Other plotting functions: [coo\\_arrows](#), [coo\\_draw](#), [coo\\_listpanel](#), [coo\\_lolli](#), [coo\\_plot](#), [coo\\_ruban](#), [ldk\\_chull](#), [ldk\\_confell](#), [ldk\\_contour](#), [ldk\\_labels](#), [ldk\\_links](#), [plot\\_devsegments](#)

**Examples**

```
plot_table(olea, "var")
plot_table(olea, "domes", "var")
gg <- plot_table(olea, "domes", "var", rm0 = TRUE)
gg
library(ggplot2)
gg + coord_equal()
gg + scale_fill_gradient(low="green", high = "red")
gg + coord_flip()
```

---

pProcrustes

*Partial Procrustes alignment between two shapes*

---

**Description**

Directly borrowed from Claude (2008), and called pPsup there.

**Usage**

```
pProcrustes(coo1, coo2)
```

**Arguments**

coo1	Configuration matrix to be superimposed onto the centered preshape of coo2.
coo2	Reference configuration matrix.



**Value**

a list with components

- `coo1` superimposed centered preshape of `coo1` onto the centered preshape of `coo2`
- `coo2` centered preshape of `coo2`
- `rotation` rotation matrix
- `DP` partial Procrustes distance between `coo1` and `coo2`
- `rho` trigonometric Procrustes distance.

**References**

Claude, J. (2008). Morphometrics with R. Analysis (p. 316). Springer.

**See Also**

Other procrustes functions: [fProcrustes](#), [fgProcrustes](#), [fgsProcrustes](#)

---

Ptolemy

*Ptolemaic ellipses and illustration of efourier*

---

**Description**

Calculate and display Ptolemaic ellipses which illustrates intuitively the principle behind elliptical Fourier analysis.

**Usage**

```
Ptolemy(coo, t = seq(0, 2 * pi, length = 7)[-1], nb.h = 3, nb.pts = 360,
        palette = col_heat, zoom = 5/4, legend = TRUE, ...)
```

**Arguments**

<code>coo</code>	a matrix of (x; y) coordinates
<code>t</code>	A vector of angles (in radians) on which to display ellipses
<code>nb.h</code>	integer. The number of harmonics to display
<code>nb.pts</code>	integer. The number of points to use to display shapes
<code>palette</code>	a color palette
<code>zoom</code>	numeric a zoom factor for <a href="#">coo_plot</a>
<code>legend</code>	logical. Whether to plot the legend box
<code>...</code>	additional parameters to feed <a href="#">coo_plot</a>

## References

This method has been inspired by the figures found in the followings papers. Kuhl FP, Giardina CR. 1982. Elliptic Fourier features of a closed contour. *Computer Graphics and Image Processing* **18**: 236-258. Crampton JS. 1995. Elliptical Fourier shape analysis of fossil bivalves: some practical considerations. *Lethaia* **28**: 179-186.

## See Also

An intuitive explanation of elliptic Fourier analysis can be found in the **Details** section of the [efourier](#) function.

exemplifying functions

## Examples

```
cat <- shapes[4]
Ptolemy(cat, main="An EFT cat")
```

---

rearrange_ldk	<i>Rearrange, (select and reorder) landmarks to retain</i>
---------------	--

---

## Description

Helps reorder and retain landmarks by simply changing the order in which they are recorded in the `Coo` objects. Note that for `Out` and `Opn` objects, this rearranges the `$ldk` component. For `Ldk`, it rearranges the `$coo` directly.

## Usage

```
rearrange_ldk(Coo, new_ldk_ids)
```

## Arguments

<code>Coo</code>	any appropriate <code>Coo</code> object (typically an <code>Ldk</code> ) with landmarks inside
<code>new_ldk_ids</code>	a vector of numeric with the <code>ldk</code> to retain <i>and</i> in the right order (see below)

## See Also

Other `ldk`/`slidings` methods: [add\\_ldk](#), [def\\_ldk](#), [def\\_slidings](#), [get\\_ldk](#), [get\\_slidings](#), [slidings\\_scheme](#)

## Examples

```
# Out example
hearts %>% slice(1) %T>% stack %$$ ldk
hearts %>% rearrange_ldk(c(4, 1)) %>%
  slice(1) %T>%stack %$$ ldk

# Ldk example
wings %>% slice(1) %T>% stack %$$ coo
```

```
wings %>% rearrange_ldk(c(1, 3, 12:15)) %>%
  slice(1) %T>% stack %$$ coo
```

---

reLDA	<i>"Redo" a LDA on new data</i>
-------	---------------------------------

---

## Description

Basically a wrapper around [predict.lda](#) from the package MASS. Uses a LDA model to classify new data.

## Usage

```
reLDA(newdata, LDA)

## Default S3 method:
reLDA(newdata, LDA)

## S3 method for class 'PCA'
reLDA(newdata, LDA)

## S3 method for class 'Coe'
reLDA(newdata, LDA)
```

## Arguments

newdata	to use, a <a href="#">PCA</a> or any <a href="#">Coe</a> object
LDA	a <a href="#">LDA</a> object

## Value

a list with components (from `?predict.lda`).

- class factor of classification
- posterior posterior probabilities for the classes
- x the scores of test cases
- res data.frame of the results
- CV.tab a confusion matrix of the results
- CV.correct proportion of the diagonal of CV.tab
- newdata the data used to calculate passed to predict.lda

## Note

Uses the same number of PC axis as the LDA object provided. You should probably use [rePCA](#) in conjunction with reLDA to get 'homologous' scores.

## Examples

```
# We select the first 10 individuals in bot,  
# for whisky and beer bottles. It will be our referential.  
bot1 <- slice(bot, c(1:10, 21:30))  
# Same thing for the other 10 individuals.  
# It will be our unknown dataset on which we want  
# to calculate classes.  
bot2 <- slice(bot, c(11:20, 31:40))  
  
# We calculate efourier on these two datasets  
bot1.f <- efourier(bot1, 8)  
bot2.f <- efourier(bot2, 8)  
  
# Here we obtain our LDA model: first, a PCA, then a LDA  
bot1.p <- PCA(bot1.f)  
bot1.l <- LDA(bot1.p, "type")  
  
# we redo the same PCA since we worked with scores  
bot2.p <- rePCA(bot1.p, bot2.f)  
  
# we finally "predict" with the model obtained before  
bot2.l <- reLDA(bot2.p, bot1.l)  
bot2.l
```

---

rePCA

*"Redo" a PCA on a new Coe*

---

## Description

Basically reapply rotation to a new Coe object.

## Usage

```
rePCA(PCA, Coe)
```

## Arguments

PCA	a <a href="#">PCA</a> object
Coe	a <a href="#">Coe</a> object

## Note

Quite experimental. Dimensions of the matrices and methods must match.

**Examples**

```

b <- filter(bot, type=="beer")
w <- filter(bot, type=="whisky")

bf <- efourier(b, 8)
bp <- PCA(bf)

wf <- efourier(w, 8)

# and we use the "beer" PCA on the whisky coefficients
wp <- rePCA(bp, wf)

plot(wp)

plot(bp, eig=FALSE)
points(wp$x[, 1:2], col="red", pch=4)

```

rescale

*Rescale coordinates from pixels to real length units***Description**

Most of the time, (x, y) coordinates are recorded in pixels. If we want to have them in mm, cm, etc. we need to convert them and to rescale them. This functions does the job for the two cases: i) either an homogeneous rescaling factor, e.g. if all pictures were taken using the very same magnification or ii) with various magnifications. More in the Details section

**Usage**

```
rescale(x, scaling_factor, scale_mapping, magnification_col, ...)
```

**Arguments**

x	any Coo object
scaling_factor	numeric an homogeneous scaling factor. If all you (x, y) coordinates have the same scale
scale_mapping	either a data.frame or a path to read such a data.frame. It MUST contain three columns in that order: magnification found in \$fac, column "magnification_col", pixels, real length unit. Column names do not matter but must be specified, as read.table reads with header=TRUE Every different magnification level found in \$fac, column "magnification_col" must have its row.
magnification_col	the name or id of the \$fac column to look for magnification levels for every image
...	additional arguments (besides header=TRUE) to pass to read.table if 'scale_mapping' is a path

**Details**

The i) case above is straightforward, if 1cm is 500pix long on all your pictures, just call `rescale(your_Coo, scaling_factor)` and all coordinates will be in cm.

The ii) second case is more subtle. First you need to code in your `/linkCoo` object, in the `fac` slot, a column named, say "mag", for magnification. Imagine you have 4 magnifications: 0.5, 1, 2 and 5, we have to indicate for each magnification, how many pixels stands for how many units in the real world.

This information is passed as a `data.frame`, built externally or in R, that must look like this:

```
mag  pix  cm
0.5  1304  10
1    921   10
2    816   5
5    1020  5
```

.

We have to do that because, for optical reasons, the ratio `pix/real_unit`, is not a linear function of the magnification.

All shapes will be centered to apply (the single or the different) `scaling_factor`.

**Note**

This function is simple but quite complex to detail. Feel free to contact me should you have any problem with it. You can just access its code (type `rescale`) and reply it yourself.

**See Also**

Other handling functions: [arrange](#), [at\\_least](#), [chop](#), [combine](#), [dissolve](#), [fac\\_dispatcher](#), [filter](#), [mutate](#), [rm\\_harm](#), [rm\\_uncomplete](#), [rw\\_fac](#), [sample\\_frac](#), [sample\\_n](#), [select](#), [slice](#)

---

rfourier

*Radii variation Fourier transform (equally spaced radii)*

---

**Description**

`rfourier` computes radii variation Fourier analysis from a matrix or a list of coordinates where points are equally spaced radii.

**Usage**

```
rfourier(x, ...)

## Default S3 method:
rfourier(x, nb.h, smooth.it = 0, norm = FALSE, ...)

## S3 method for class 'Out'
rfourier(x, nb.h = 40, smooth.it = 0, norm = TRUE,
         thres = pi/90, ...)
```

**Arguments**

x	A list or matrix of coordinates or an Out object
...	useless here
nb.h	integer. The number of harmonics to use. If missing, 12 is used on shapes; 99 percent of harmonic power on Out objects, both with messages.
smooth.it	integer. The number of smoothing iterations to perform.
norm	logical. Whether to scale the outlines so that the mean length of the radii used equals 1.
thres	numeric a tolerance to feed <a href="#">is_equallyspacedradii</a>

**Details**

see the JSS paper for the maths behind. The methods for Out objects tests if coordinates have equally spaced radii using [is\\_equallyspacedradii](#). A message is printed if this is not the case.

**Value**

A list with following components:

- an vector of  $a_{1 \rightarrow n}$  harmonic coefficients
- bn vector of  $b_{1 \rightarrow n}$  harmonic coefficients
- ao ao harmonic coefficient.
- r vector of radii lengths.

**Note**

Silent message and progress bars (if any) with options("verbose"=FALSE).  
Directly borrowed for Claude (2008), and called `fourier1` there.

**References**

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp.

**See Also**

Other rfourier: [rfourier\\_i](#), [rfourier\\_shape](#)

**Examples**

```
data(bot)
coo <- coo_center(bot[1]) # centering is almost mandatory for rfourier family
coo_plot(coo)
rf <- rfourier(coo, 12)
rf
rfi <- rfourier_i(rf)
coo_draw(rfi, border='red', col=NA)

# Out method
bot %>% rfourier()
```

---

`rfourier_i`*Inverse radii variation Fourier transform*

---

**Description**

`rfourier_i` uses the inverse radii variation (equally spaced radii) transformation to calculate a shape, when given a list with Fourier coefficients, typically obtained computed with [rfourier](#).

**Usage**

```
rfourier_i(rf, nb.h, nb.pts = 120)
```

**Arguments**

<code>rf</code>	A list with <code>ao</code> , <code>an</code> and <code>bn</code> components, typically as returned by <code>rfourier</code> .
<code>nb.h</code>	integer. The number of harmonics to calculate/use.
<code>nb.pts</code>	integer. The number of points to calculate.

**Details**

See the JSS paper for the maths behind.

**Value**

A list with components:

<code>x</code>	vector of x-coordinates.
<code>y</code>	vector of y-coordinates.
<code>angle</code>	vector of angles used.
<code>r</code>	vector of radii calculated.

**Note**

Directly borrowed for Claude (2008), and called `ifourier1` there.

**References**

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp.

**See Also**

Other `rfourier`: [rfourier\\_shape](#), [rfourier](#)



**Examples**

```

data(bot)
coo <- coo_center(bot[1]) # centering is almost mandatory for rfourier family
coo_plot(coo)
rf <- rfourier(coo, 12)
rf
rfi <- rfourier_i(rf)
coo_draw(rfi, border='red', col=NA)

```

---

rfourier_shape	<i>Calculates and draw 'rfourier' shapes.</i>
----------------	---

---

**Description**

rfourier\_shape calculates a 'Fourier radii variation shape' given Fourier coefficients (see [Details](#)) or can generate some 'rfourier' shapes.

**Usage**

```
rfourier_shape(an, bn, nb.h, nb.pts = 80, alpha = 2, plot = TRUE)
```

**Arguments**

an	numeric. The $a_n$ Fourier coefficients on which to calculate a shape.
bn	numeric. The $b_n$ Fourier coefficients on which to calculate a shape.
nb.h	integer. The number of harmonics to use.
nb.pts	integer. The number of points to calculate.
alpha	numeric. The power coefficient associated with the (usually decreasing) amplitude of the Fourier coefficients (see <a href="#">Details</a> ).
plot	logical. Whether to plot or not the shape.

**Details**

rfourier\_shape can be used by specifying nb.h and alpha. The coefficients are then sampled in an uniform distribution  $(-\pi; \pi)$  and this amplitude is then divided by  $harmonicrank^{alpha}$ . If alpha is lower than 1, consecutive coefficients will thus increase. See [rfourier](#) for the mathematical background.

**Value**

A matrix of (x; y) coordinates.

**References**

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp.

**See Also**

Other rfourier: [rfourier\\_i](#), [rfourier](#)

**Examples**

```
data(bot)
rf <- rfourier(bot[1], 24)
rfourier_shape(rf$an, rf$bn) # equivalent to rfourier_i(rf)
rfourier_shape() # not very interesting

rfourier_shape(nb.h=12) # better
rfourier_shape(nb.h=6, alpha=0.4, nb.pts=500)

# Butterflies of the vignette' cover
panel(Out(a2l(replicate(100,
rfourier_shape(nb.h=6, alpha=0.4, nb.pts=200, plot=FALSE))))))
```

---

rm\_asym

*Removes asymmetric and symmetric variation on OutCoe objects*

---

**Description**

Only for those obtained with [efourier](#), otherwise a message is returned. `rm_asym` sets all B and C coefficients to 0; `rm_sym` sets all A and D coefficients to 0.

**Usage**

```
rm_asym(OutCoe)

## Default S3 method:
rm_asym(OutCoe)

## S3 method for class 'OutCoe'
rm_asym(OutCoe)

rm_sym(OutCoe)

## Default S3 method:
rm_sym(OutCoe)

## S3 method for class 'OutCoe'
rm_sym(OutCoe)
```

**Arguments**

OutCoe            an OutCoe object

**Value**

an OutCoe object

**References**

Below: the first mention, and two applications.

#'

- Iwata, H., Niikura, S., Matsuura, S., Takano, Y., & Ukai, Y. (1998). Evaluation of variation of root shape of Japanese radish (*Raphanus sativus* L.) based on image analysis using elliptic Fourier descriptors. *Euphytica*, 102, 143-149.
- Iwata, H., Nesumi, H., Ninomiya, S., Takano, Y., & Ukai, Y. (2002). The Evaluation of Genotype x Environment Interactions of Citrus Leaf Morphology Using Image Analysis and Elliptic Fourier Descriptors. *Breeding Science*, 52(2), 89-94. doi:10.1270/jsbbs.52.89
- Yoshioka, Y., Iwata, H., Ohsawa, R., & Ninomiya, S. (2004). Analysis of petal shape variation of *Primula sieboldii* by elliptic fourier descriptors and principal component analysis. *Annals of Botany*, 94(5), 657-64. doi:10.1093/aob/mch190

**See Also**

[symmetry](#) and the note there.

**Examples**

```
botf <- efourier(bot, 12)
botSym <- rm_asym(botf)
boxplot(botSym)
botSymp <- PCA(botSym)
plot(botSymp)
plot(botSymp, amp.shp=5)

# Asymmetric only
botAsym <- rm_sym(botf)
boxplot(botAsym)
botAsymp <- PCA(botAsym)
plot(botAsymp)
# strange shapes because the original shape was mainly symmetric and would need its
# symmetric (eg its average) for a proper reconstruction. Should only be used like that:
plot(botAsymp, morpho=FALSE)
```

---

rm\_harm

*Removes harmonics from Coe objects*

---

**Description**

Useful to drop harmonics on Coe objects. Should only work for Fourier-based approaches since it looks for [A-D][1-drop] pattern.

**Usage**

```
rm_harm(x, drop = 1)
```

**Arguments**

x	Coe object
drop	numeric number of harmonics to drop

**See Also**

Other handling functions: [arrange](#), [at\\_least](#), [chop](#), [combine](#), [dissolve](#), [fac\\_dispatcher](#), [filter](#), [mutate](#), [rescale](#), [rm\\_uncomplete](#), [rw\\_fac](#), [sample\\_frac](#), [sample\\_n](#), [select](#), [slice](#)

**Examples**

```
data(bot)
bf <- efourier(bot)
colnames(rm_harm(bf, 1)$coe)
```

---

 rm\_uncomplete

*Remove shapes with incomplete slices*


---

**Description**

Imagine you take three views of every object you study. Then, you can [slice](#), [filter](#) or [chop](#) your entire dataset, do morphometrics on it, then want to [combine](#) it. But if you have forgotten one view, or if it was impossible to obtain, for one or more objects, combine will not work. This function helps you to remove those ugly ducklings. See examples

**Usage**

```
rm_uncomplete(x, id, by)
```

**Arguments**

x	the object on which to remove uncomplete "by"
id	of the objects, within the \$fac slot
by	which column of the \$fac should objects have complete views

**See Also**

Other handling functions: [arrange](#), [at\\_least](#), [chop](#), [combine](#), [dissolve](#), [fac\\_dispatcher](#), [filter](#), [mutate](#), [rescale](#), [rm\\_harm](#), [rw\\_fac](#), [sample\\_frac](#), [sample\\_n](#), [select](#), [slice](#)

**Examples**

```

# we load olea
data(olea)
# we select the var Aglan since it is the only one complete
ol <- filter(olea, var == "Aglan")
# everything seems fine
table(ol$view, ol$ind)
# indeed
rm_uncomplete(ol, id="ind", by="view")

# we mess the ol object by removing a single shape
ol.pb <- slice(ol, -1)
table(ol.pb$view, ol.pb$ind)
# the counterpart has been removed with a notice
ol.ok <- rm_uncomplete(ol.pb, "ind", "view")
# now you can combine them
table(ol.ok$view, ol.ok$ind)

```

---

rw\_fac

*Renames levels on Momocs objects*


---

**Description**

rw\_fac stands for 'rewriting rule'. Typically useful to correct typos at the import, or merge some levels within covariates. Drops levels silently.

**Usage**

```
rw_fac(x, fac, from, to)
```

**Arguments**

x	any Momocs object
fac	the id of the name of the \$fac column to look for ( <a href="#">fac_dispatcher</a> not yet supported)
from	which level(s) should be renamed; passed as a single or several characters
to	which name should be used to rename this/these levels

**Value**

a Momocs object of the same type

**See Also**

Other handling functions: [arrange](#), [at\\_least](#), [chop](#), [combine](#), [dissolve](#), [fac\\_dispatcher](#), [filter](#), [mutate](#), [rescale](#), [rm\\_harm](#), [rm\\_uncomplete](#), [sample\\_frac](#), [sample\\_n](#), [select](#), [slice](#)

**Examples**

```
# single renaming
rw_fac(bot, "type", "whisky", "agua_de_fuego")$type # 1 instead of "type" is fine too
# several renaming
bot2 <- mutate(bot, fake=factor(rep(letters[1:4], 10)))
rw_fac(bot2, "fake", c("a", "e"), "ae")$fake
```

---

sample_frac	<i>Sample a fraction of shapes</i>
-------------	------------------------------------

---

**Description**

Sample a fraction of shapes from a Momocs object. See examples and `?dplyr::sample_n`.

**Usage**

```
sample_frac(tbl, size, replace, fac, ...)
```

**Arguments**

tbl	a Momocs object (Coo, Coe)
size	numeric (0 < numeric <= 1) the fraction of shapes to select
replace	logical whether sample should be done with or without replacement
fac	a column name if a \$fac is defined; size is then applied within levels of this factor
...	additional arguments to <code>dplyr::sample_frac</code> and to maintain generic compatibility

**Note**

the resulting fraction is rounded with [ceiling](#).

**See Also**

Other handling functions: [arrange](#), [at\\_least](#), [chop](#), [combine](#), [dissolve](#), [fac\\_dispatcher](#), [filter](#), [mutate](#), [rescale](#), [rm\\_harm](#), [rm\\_uncomplete](#), [rw\\_fac](#), [sample\\_n](#), [select](#), [slice](#)

**Examples**

```
# samples 50% of the bottles no matter their type
sample_frac(bot, 0.5)
# 80% bottles of beer and of whisky
table(sample_frac(bot, 0.8, fac="type")$fac)
# bootstrap the same number of bottles of each type but with replacement
table(names(sample_frac(bot, 1, replace=TRUE)))
```

---

sample_n	<i>Sample n shapes</i>
----------	------------------------

---

**Description**

Sample n shapes from a Momocs object. See examples and `?dplyr::sample_n`.

**Usage**

```
sample_n(tbl, size, replace, fac, ...)
```

**Arguments**

tbl	a Momocs object (Coo, Coe)
size	numeric how many shapes should we sample
replace	logical whether sample should be done with or without replacement
fac	a column name if a <code>\$fac</code> is defined; size is then applied within levels of this factor
...	additional arguments to <code>dplyr::sample_n</code> and to maintain generic compatibility

**See Also**

Other handling functions: [arrange](#), [at\\_least](#), [chop](#), [combine](#), [dissolve](#), [fac\\_dispatcher](#), [filter](#), [mutate](#), [rescale](#), [rm\\_harm](#), [rm\\_uncomplete](#), [rw\\_fac](#), [sample\\_frac](#), [select](#), [slice](#)

**Examples**

```
# samples 5 bottles no matter their type
sample_n(bot, 5)
# 5 bottles of beer and of whisky
table(sample_n(bot, 5, fac="type")$type)
# many repetitions
table(names(sample_n(bot, 400, replace=TRUE)))
```

---

scree	<i>Methods for PCA eigen values</i>
-------	-------------------------------------

---

**Description**

A set of functions around PCA/LDA eigen/trace. `scree` calculates their proportion and cumulated proportion; `scree_min` returns the minimal number of axis to use to retain a given proportion; `scree_plot` displays a screeplot.

**Usage**

```

scree(x, nax)

## S3 method for class 'PCA'
scree(x, nax = 1:10)

## S3 method for class 'LDA'
scree(x, nax = 1:10)

scree_min(x, prop = 0.99)

scree_plot(x, nax = 1:10)

```

**Arguments**

x	a <a href="#">PCA</a> object
nax	numeric range of axis to consider
prop	numeric how many axis are enough this proportion of variance, if too high then number of axis is returned.

**Value**

scree returns a data.frame, scree\_min a numeric, scree\_plot a ggplot.

**Examples**

```

# On PCA
bp <- PCA(efourier(bot))
scree(bp)
scree_min(bp, 0.99)
scree_min(bp, 1)

scree_plot(bp)
scree_plot(bp, 1:5)

# on LDA, it uses svd
bl <- LDA(PCA(opoly(olea)), "var")
scree(bl)

```

---

select

*Select and rename columns by name*


---

**Description**

Select variables by name, from the \$fac. See examples and `?dplyr::select`.



**Usage**

```
select(.data, ...)
```

**Arguments**

```
.data      a Coe, Coe, PCA object
...        comma separated list of unquoted expressions
```

**Details**

dplyr verbs are maintained.

**Value**

a Momocs object of the same class.

**See Also**

Other handling functions: [arrange](#), [at\\_least](#), [chop](#), [combine](#), [dissolve](#), [fac\\_dispatcher](#), [filter](#), [mutate](#), [rescale](#), [rm\\_harm](#), [rm\\_uncomplete](#), [rw\\_fac](#), [sample\\_frac](#), [sample\\_n](#), [slice](#)

**Examples**

```
olea
select(olea, var, view) # drops domes and ind
select(olea, variety=var, domesticated_status=domes, view)
# combine with filter with magrittr pipes
# only dorsal views, and 'var' and 'domes' columns
filter(olea, view=="VD") %>% select(var, domes)
head(olea$fac)
# select some columns
select(olea, domes, view)
# remove some columns
select(olea, -ind)
# rename on the fly and select some columns
select(olea, foo=domes)
```

---

sfourier

*Radii variation Fourier transform (equally spaced curvilinear abscissa)*

---

**Description**

sfourier computes radii variation Fourier analysis from a matrix or a list of coordinates where points are equally spaced along the curvilinear abscissa.

**Usage**

```
sfourier(x, nb.h)

## Default S3 method:
sfourier(x, nb.h)

## S3 method for class 'Out'
sfourier(x, nb.h)
```

**Arguments**

**x** A list or matrix of coordinates or an Out object

**nb.h** integer. The number of harmonics to use. If missing, 12 is used on shapes; 99 percent of harmonic power on Out objects, both with messages.

**Value**

A list with following components:

- an vector of  $a_{1 \rightarrow n}$  harmonic coefficients
- bn vector of  $b_{1 \rightarrow n}$  harmonic coefficients
- ao ao harmonic coefficient
- r vector of radii lengths

**Note**

The implementation is still quite experimental (as of Dec. 2016)

**References**

Renaud S, Michaux JR (2003): Adaptive latitudinal trends in the mandible shape of *Apodemus* wood mice. *J Biogeogr* 30:1617-1628.

**See Also**

Other sfourier: [sfourier\\_i](#), [sfourier\\_shape](#)

**Examples**

```
molars[4] %>%
  coo_center %>% coo_scale %>% coo_interpolate(1080) %>%
  coo_slidedirection("right") %>%
  coo_sample(360) %T>% coo_plot(zoom=2) %>%
  sfourier(16) %>%
  sfourier_i() %>%
  coo_draw(bor="red", points=TRUE)
```

---

sfourier\_i                      *Inverse radii variation Fourier transform*

---

### Description

sfourier\_i uses the inverse radii variation (equally spaced curvilinear abscissa) transformation to calculate a shape, when given a list with Fourier coefficients, typically obtained computed with [sfourier](#).

### Usage

```
sfourier_i(rf, nb.h, nb.pts = 120, dtheta = FALSE)
```

### Arguments

rf	A list with ao, an and bn components, typically as returned by <a href="#">sfourier</a> .
nb.h	integer. The number of harmonics to calculate/use.
nb.pts	integer. The number of points to calculate.
dtheta	logical. Whether to use the dtheta correction method. FALSE by default. When TRUE, tries to correct the angular difference between reconstructed points; otherwise equal angles are used.

### Value

A list with components:

x	vector of x-coordinates.
y	vector of y-coordinates.
angle	vector of angles used.
r	vector of radii calculated.

### References

Renaud S, Pale JRM, Michaux JR (2003): Adaptive latitudinal trends in the mandible shape of *Apodemus* wood mice. *J Biogeogr* 30:1617-1628.

### See Also

Other sfourier: [sfourier\\_shape](#), [sfourier](#)

**Examples**

```

coo <- coo_center(bot[1]) # centering is almost mandatory for sfourier family
coo_plot(coo)
rf <- sfourier(coo, 12)
rf
rfi <- sfourier_i(rf)
coo_draw(rfi, border='red', col=NA)

```

---

sfourier\_shape                      *Calculates and draw 'sfourier' shapes.*

---

**Description**

sfourier\_shape calculates a 'Fourier radii variation shape' given Fourier coefficients (see [Details](#)) or can generate some 'sfourier' shapes.

**Usage**

```
sfourier_shape(an, bn, nb.h, nb.pts = 80, alpha = 2, plot = TRUE)
```

**Arguments**

an	numeric. The $a_n$ Fourier coefficients on which to calculate a shape.
bn	numeric. The $b_n$ Fourier coefficients on which to calculate a shape.
nb.h	integer. The number of harmonics to use.
nb.pts	integer. The number of points to calculate.
alpha	numeric. The power coefficient associated with the (usually decreasing) amplitude of the Fourier coefficients (see <a href="#">Details</a> ).
plot	logical. Whether to plot or not the shape.

**Details**

sfourier\_shape can be used by specifying nb.h and alpha. The coefficients are then sampled in an uniform distribution  $(-\pi; \pi)$  and this amplitude is then divided by  $harmonicrank^{alpha}$ . If alpha is lower than 1, consecutive coefficients will thus increase. See [sfourier](#) for the mathematical background.

**Value**

A matrix of (x; y) coordinates.

**References**

Renaud S, Pale JRM, Michaux JR (2003): Adaptive latitudinal trends in the mandible shape of *Apodemus* wood mice. *J Biogeogr* 30:1617-1628.

**See Also**

Other sfourier: [sfourier\\_i](#), [sfourier](#)

**Examples**

```
rf <- sfourier(bot[1], 24)
sfourier_shape(rf$an, rf$bn) # equivalent to sfourier_i(rf)
sfourier_shape() # not very interesting

sfourier_shape(nb.h=12) # better
sfourier_shape(nb.h=6, alpha=0.4, nb.pts=500)

# Butterflies of the vignette' cover
panel(Out(a2l(replicate(100,
sfourier_shape(nb.h=6, alpha=0.4, nb.pts=200, plot=FALSE))))))
```

---

shapes

*Data: Outline coordinates of various shapes*

---

**Description**

Data: Outline coordinates of various shapes

**Format**

An [Out](#) object with the outline coordinates of some various shapes.

**Source**

Borrowed default shapes from (c) Adobe Photoshop. Do not send me to jail.

**See Also**

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [trilo](#), [wings](#)

---

slice

*Subset based on positions*

---

**Description**

Select rows by position, based on \$fac. See examples and `?dplyr::slice`.

**Usage**

```
slice(.data, ...)
```

**Arguments**

.data            a Coo, Coe, PCA object  
 ...            logical conditions

**Details**

dplyr verbs are maintained.

**Value**

a Momocs object of the same class.

**See Also**

Other handling functions: [arrange](#), [at\\_least](#), [chop](#), [combine](#), [dissolve](#), [fac\\_dispatcher](#), [filter](#), [mutate](#), [rescale](#), [rm\\_harm](#), [rm\\_uncomplete](#), [rw\\_fac](#), [sample\\_frac](#), [sample\\_n](#), [select](#)

**Examples**

```
olea
slice(olea, 1) # if you only want the coordinates, try bot[1]
slice(olea, 1:20)
slice(olea, 21:30)
```

---

slidings\_scheme            *Extracts partitions of sliding coordinates*

---

**Description**

Helper function that deduces (likely to be a reminder) partition scheme from \$slidings of Ldk objects.

**Usage**

```
slidings_scheme(Coo)
```

**Arguments**

Coo            an Ldk object

**Value**

a list with two components: n the number of partition; id their position. Or a NULL if no slidings are defined

**See Also**

Other ldk/slidings methods: [add\\_ldk](#), [def\\_ldk](#), [def\\_slidings](#), [get\\_ldk](#), [get\\_slidings](#), [rearrange\\_ldk](#)

**Examples**

```
# no slidings defined a NULL is returned with a message
slidings_scheme(wings)

# slidings defined
slidings_scheme(chaff)
```

---

stack

*Family picture of shapes*


---

**Description**

Plots all the outlines, on the same graph, from a **Coo** (**Out**, **Opn** or **Ldk**) object.

**Usage**

```
## S3 method for class 'Coo'
stack(x, cols, borders, fac, palette = col_summer,
      coo_sample = 120, points = FALSE, first.point = TRUE, centroid = TRUE,
      ldk = TRUE, ldk_pch = 3, ldk_col = "#FF000055", ldk_cex = 0.5,
      ldk_links = FALSE, ldk_confell = FALSE, ldk_contour = FALSE,
      ldk_chull = FALSE, ldk_labels = FALSE, xy.axis = TRUE,
      title = substitute(x), ...)

## S3 method for class 'Ldk'
stack(x, cols, borders, first.point = TRUE, centroid = TRUE,
      ldk = TRUE, ldk_pch = 20, ldk_col = col_alpha("#000000", 0.5),
      ldk_cex = 0.3, meanshape = FALSE, meanshape_col = "#FF0000",
      ldk_links = FALSE, ldk_confell = FALSE, ldk_contour = FALSE,
      ldk_chull = FALSE, ldk_labels = FALSE, slidings = TRUE,
      slidings_pch = "", xy.axis = TRUE, title = substitute(x), ...)
```

**Arguments**

<code>x</code>	The Coo object to plot.
<code>cols</code>	A vector of colors for drawing the outlines. Either a single value or of length exactly equals to the number of coordinates.
<code>borders</code>	A vector of colors for drawing the borders. Either a single value or of length exactly equals to the number of coordinates.
<code>fac</code>	a factor within the \$fac slot for colors
<code>palette</code>	a color palette to use when fac is provided
<code>coo_sample</code>	if not NULL the number of point per shape to display (to plot quickly)
<code>points</code>	logical whether to draw or not points
<code>first.point</code>	logical whether to draw or not the first point

centroid	logical whether to draw or not the centroid
ldk	logical. Whether to display landmarks (if any).
ldk_pch	pch for these landmarks
ldk_col	color for these landmarks
ldk_cex	cex for these landmarks
ldk_links	logical whether to draw links (of the mean shape)
ldk_confell	logical whether to draw conf ellipses
ldk_contour	logical whether to draw contour lines
ldk_chull	logical whether to draw convex hull
ldk_labels	logical whether to draw landmark labels
xy.axis	whether to draw or not the x and y axes
title	a title for the plot. The name of the Coo by default
...	further arguments to be passed to <a href="#">coo_plot</a>
meanshape	logical whether to add meanshape related stuff (below)
meanshape_col	a color for everything meanshape
slidings	logical whether to draw slidings semi landmarks
slidings_pch	pch for semi landmarks

### See Also

Other Coo\_graphics: [inspect](#), [panel](#)

### Examples

```
## Not run:
stack(bot)
bot.f <- efourier(bot, 12)
stack(bot.f)
stack(mosquito, borders='#1A1A1A22', first.point=FALSE)
stack(hearts)
stack(hearts, ldk=FALSE)
stack(hearts, borders='#1A1A1A22', ldk=TRUE, ldk_col=col_summer(4), ldk_pch=20)
stack(hearts, fac="aut", palette=col_sari)

chaffal <- fgProcrustes(chaff)
stack(chaffal, slidings=FALSE)
stack(chaffal, meanshape=TRUE, meanshape_col="blue")

## End(Not run)
```



---

symmetry

*Calculates symmetry indices on OutCoe objects*

---

### Description

For [OutCoe](#) objects obtained with [efourier](#), calculates several indices on the matrix of coefficients: AD, the sum of absolute values of harmonic coefficients A and D; BC same thing for B and C; amp the sum of the absolute value of all harmonic coefficients and sym which is the ratio of AD over amp. See references below for more details.

### Usage

```
symmetry(OutCoe)
```

### Arguments

OutCoe            [efourier](#) objects

### Value

a matrix with 4 columns described above.

### Note

What we call symmetry here is bilateral symmetry. By comparing coefficients resulting from [efourier](#), with AD responsible for amplitude of the Fourier functions, and BC for their phase, it results in the plane and for fitted/reconstructed shapes that symmetry. As long as your shapes are aligned along their bilateral symmetry axis, you can use the approach coined by Iwata et al., and here implemented in Momocs.

### References

Below: the first mention, and two applications.

#'

- Iwata, H., Niikura, S., Matsuura, S., Takano, Y., & Ukai, Y. (1998). Evaluation of variation of root shape of Japanese radish (*Raphanus sativus* L.) based on image analysis using elliptic Fourier descriptors. *Euphytica*, 102, 143-149.
- Iwata, H., Nesumi, H., Ninomiya, S., Takano, Y., & Ukai, Y. (2002). The Evaluation of Genotype x Environment Interactions of Citrus Leaf Morphology Using Image Analysis and Elliptic Fourier Descriptors. *Breeding Science*, 52(2), 89-94. doi:10.1270/jsbbs.52.89
- Yoshioka, Y., Iwata, H., Ohsawa, R., & Ninomiya, S. (2004). Analysis of petal shape variation of *Primula sieboldii* by elliptic fourier descriptors and principal component analysis. *Annals of Botany*, 94(5), 657-64. doi:10.1093/aob/mch190

### See Also

[rm\\_asym](#) and [rm\\_sym](#).

**Examples**

```
bot.f <- efourier(bot, 12)
res <- symmetry(bot.f)
hist(res[, 'sym'])
```

---

 tfourier

*Tangent angle Fourier transform*


---

**Description**

tfourier computes tangent angle Fourier analysis from a matrix or a list of coordinates.

**Usage**

```
tfourier(x, ...)

## Default S3 method:
tfourier(x, nb.h, smooth.it = 0, norm = FALSE, ...)

## S3 method for class 'Out'
tfourier(x, nb.h = 40, smooth.it = 0, norm = TRUE, ...)
```

**Arguments**

x	A list or matrix of coordinates or an Out
...	useless here
nb.h	integer. The number of harmonics to use. If missing, 12 is used on shapes; 99 percent of harmonic power on Out objects, both with messages.
smooth.it	integer. The number of smoothing iterations to perform
norm	logical. Whether to scale and register new coordinates so that the first point used is sent on the origin.

**Value**

A list with the following components:

- ao ao harmonic coefficient
- an vector of  $a_{1 \rightarrow n}$  harmonic coefficients
- bn vector of  $b_{1 \rightarrow n}$  harmonic coefficients
- phi vector of variation of the tangent angle
- t vector of distance along the perimeter expressed in radians
- perimeter numeric. The perimeter of the outline
- thetao numeric. The first tangent angle
- x1 The x-coordinate of the first point
- y1 The y-coordinate of the first point.

**Note**

Silent message and progress bars (if any) with options("verbose"=FALSE).  
 Directly borrowed for Claude (2008), and called `fourier2` there.

**References**

Zahn CT, Roskies RZ. 1972. Fourier Descriptors for Plane Closed Curves. *IEEE Transactions on Computers* **C-21**: 269-281.  
 Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp.

**See Also**

Other tfourier: [tfourier\\_i](#), [tfourier\\_shape](#)

**Examples**

```

coo <- bot[1]
coo_plot(coo)
tf <- tfourier(coo, 12)
tf
tfi <- tfourier_i(tf)
coo_draw(tfi, border='red', col=NA) # the outline is not closed...
coo_draw(tfourier_i(tf, force2close=TRUE), border='blue', col=NA) # we force it to close.
```

---

 tfourier\_i

*Inverse tangent angle Fourier transform*


---

**Description**

`tfourier_i` uses the inverse tangent angle Fourier transformation to calculate a shape, when given a list with Fourier coefficients, typically obtained computed with [tfourier](#).

**Usage**

```
tfourier_i(tf, nb.h, nb.pts = 120, force2close = FALSE, rescale = TRUE,
  perim = 2 * pi, thetao = 0)
```

**Arguments**

<code>tf</code>	a list with <code>ao</code> , <code>an</code> and <code>bn</code> components, typically as returned by <code>tfourier</code>
<code>nb.h</code>	integer. The number of harmonics to calculate/use
<code>nb.pts</code>	integer. The number of points to calculate
<code>force2close</code>	logical. Whether to force the outlines calculated to close (see <a href="#">coo_force2close</a> ).
<code>rescale</code>	logical. Whether to rescale the points calculated so that their perimeter equals <code>perim</code> .
<code>perim</code>	The perimeter length to rescale shapes.
<code>thetao</code>	numeric. Radius angle to the reference (in radians)

**Details**

See [tfourier](#) for the mathematical background.

**Value**

A list with components:

x	vector of x-coordinates.
y	vector of y-coordinates.
phi	vector of interpolated changes on the tangent angle.
angle	vector of position on the perimeter (in radians).

**Note**

Directly borrowed for Claude (2008), and called `ifourier2` there.

**References**

Zahn CT, Roskies RZ. 1972. Fourier Descriptors for Plane Closed Curves. *IEEE Transactions on Computers* **C-21**: 269-281.

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp.

**See Also**

Other tfourier: [tfourier\\_shape](#), [tfourier](#)

**Examples**

```
tfourier(bot[1], 24)
tfourier_shape()
```

---

tfourier_shape	<i>Calculates and draws 'tfourier' shapes.</i>
----------------	--

---

**Description**

`tfourier_shape` calculates a 'Fourier tangent angle shape' given Fourier coefficients (see Details) or can generate some 'tfourier' shapes.

**Usage**

```
tfourier_shape(an, bn, ao = 0, nb.h, nb.pts = 80, alpha = 2,
  plot = TRUE)
```

**Arguments**

an	numeric. The $a_n$ Fourier coefficients on which to calculate a shape.
bn	numeric. The $b_n$ Fourier coefficients on which to calculate a shape.
ao	ao Harmonic coefficient.
nb.h	integer. The number of harmonics to use.
nb.pts	integer. The number of points to calculate.
alpha	numeric. The power coefficient associated with the (usually decreasing) amplitude of the Fourier coefficients (see <b>Details</b> ).
plot	logical. Whether to plot or not the shape.

**Value**

A matrix of (x; y) coordinates.

**References**

Claude, J. (2008) *Morphometrics with R*, Use R! series, Springer 316 pp.

**See Also**

Other tfourier: [tfourier\\_i](#), [tfourier](#)

**Examples**

```
tf <- tfourier(bot[1], 24)
tfourier_shape(tf$an, tf$bn) # equivalent to rfourier_i(rf)
tfourier_shape()
tfourier_shape(nb.h=6, alpha=0.4, nb.pts=500)
panel(Out(a2l(replicate(100,
  coo_force2close(tfourier_shape(nb.h=6, alpha=2, nb.pts=200, plot=FALSE)))))) # biological shapes
```

---

tie\_jpg\_txt

*Binds .jpg outlines from .txt landmarks taken on them*

---

**Description**

Given a list of files (lf) that includes matching filenames with .jpg (black masks) and .txt (landmark positions on them as .txt), returns an Out with \$ldk defined. Typically be useful if you use ImageJ to define landmarks on your outlines.

**Usage**

```
tie_jpg_txt(lf)
```

**Arguments**

lf a list of filenames

**Note**

Not optimized (images are read twice). Please do not hesitate to contact me should you have a particular case or need something.

**See Also**

Other babel functions: [lf\\_structure](#)

---

tps2d

*Thin Plate Splines for 2D data*

---

**Description**

tps2d is the core function for Thin Plate Splines. It is used internally for all TPS graphical functions. tps\_apply is the very same function but with arguments properly named (I maintain tps2d as it is for historical reasons) when we want a apply a transformation grid.

**Usage**

```
tps2d(grid0, fr, to)
```

```
tps_apply(fr, to, new)
```

**Arguments**

grid0	a matrix of coordinates on which to calculate deformations
fr	the reference $(x; y)$ coordinates
to	the target $(x; y)$ coordinates
new	the target coordinates (again)

**Value**

a matrix of  $(x; y)$  coordinates with TPS-interpolated deformations

**See Also**

Other thin plate splines: [tps\\_arr](#), [tps\\_grid](#), [tps\\_iso](#), [tps\\_raw](#)

tps\_arr

*Deformation 'vector field' using Thin Plate Splines***Description**

tps\_arr(ows) calculates deformations between two configurations and illustrate them using arrows.

**Usage**

```
tps_arr(fr, to, amp = 1, grid = TRUE, over = 1.2, palette = col_summer,
  arr.nb = 200, arr.levels = 100, arr.len = 0.1, arr.ang = 20,
  arr.lwd = 0.75, arr.col = "grey50", poly = TRUE, shp = TRUE,
  shp.col = rep(NA, 2), shp.border = col_qual(2), shp.lwd = c(2, 2),
  shp.lty = c(1, 1), legend = TRUE, legend.text, ...)
```

**Arguments**

fr	the reference $(x; y)$ coordinates
to	the target $(x; y)$ coordinates
amp	an amplification factor of differences between fr and to
grid	whether to calculate and plot changes across the graphical window TRUE or just within the starting shape (FALSE)
over	numeric that indicates how much the thin plate splines extends over the shapes
palette	a color palette such those included in Momocs or produced with <a href="#">colorRamp-Palette</a>
arr.nb	numeric The number of arrows to calculate
arr.levels	numeric. The number of levels for the color of arrows
arr.len	numeric for the length of arrows
arr.ang	numeric for the angle for arrows' heads
arr.lwd	numeric for the lwd for drawing arrows
arr.col	if palette is not used the color for arrows
poly	whether to draw polygons (for outlines) or points (for landmarks)
shp	logical. whether to draw shapes
shp.col	two colors for filling the shapes
shp.border	two colors for drawing the borders
shp.lwd	two lwd for drawing shapes
shp.lty	two lty fro drawing the shapes
legend	logical whether to plot a legend
legend.text	some text for the legend
...	additional arguments to feed <a href="#">coo_draw</a>

**Value**

Nothing.

**See Also**

Other thin plate splines: [tps2d](#), [tps\\_grid](#), [tps\\_iso](#), [tps\\_raw](#)

**Examples**

```
botF <- efourier(bot)
x <- mshapes(botF, 'type', nb.pts=80)$shp
fr <- x$beer
to <- x$whisky
tps_arr(fr, to, arr.nb=200, palette=col_sari, amp=3)
tps_arr(fr, to, arr.nb=200, palette=col_sari, amp=3, grid=FALSE)
```

---

 tps\_grid

*Deformation grids using Thin Plate Splines*


---

**Description**

tps\_grid calculates and plots deformation grids between two configurations.

**Usage**

```
tps_grid(fr, to, amp = 1, over = 1.2, grid.size = 15,
  grid.col = "grey80", poly = TRUE, shp = TRUE, shp.col = rep(NA, 2),
  shp.border = col_qual(2), shp.lwd = c(1, 1), shp.lty = c(1, 1),
  legend = TRUE, legend.text, ...)
```

**Arguments**

fr	the reference $(x; y)$ coordinates
to	the target $(x; y)$ coordinates
amp	an amplification factor of differences between fr and to
over	numeric that indicates how much the thin plate splines extends over the shapes
grid.size	numeric to specify the number of grid cells on the longer axis on the outlines
grid.col	color for drawing the grid
poly	whether to draw polygons (for outlines) or points (for landmarks)
shp	logical. Whether to draw shapes
shp.col	Two colors for filling the shapes
shp.border	Two colors for drawing the borders
shp.lwd	Two lwd for drawing shapes
shp.lty	Two lty fro drawing the shapes



legend	logical whether to plot a legend
legend.text	some text for the legend
...	additional arguments to feed <a href="#">coo_draw</a>

**Value**

Nothing

**See Also**

Other thin plate splines: [tps2d](#), [tps\\_arr](#), [tps\\_iso](#), [tps\\_raw](#)

**Examples**

```
botF <- efourier(bot)
x <- mshapes(botF, 'type', nb.pts=80)$shp
fr <- x$beer
to <- x$whisky
tps_grid(fr, to, amp=3, grid.size=10)
```

---

 tps\_iso

*Deformation isolines using Thin Plate Splines.*

---

**Description**

tps\_iso calculates deformations between two configurations and map them with or without isolines.

**Usage**

```
tps_iso(fr, to, amp = 1, grid = FALSE, over = 1.2, palette = col_spring,
  iso.nb = 1000, iso.levels = 12, cont = TRUE, cont.col = "black",
  poly = TRUE, shp = TRUE, shp.border = col_qual(2), shp.lwd = c(2, 2),
  shp.lty = c(1, 1), legend = TRUE, legend.text, ...)
```

**Arguments**

fr	The reference ( $x; y$ ) coordinates
to	The target ( $x; y$ ) coordinates
amp	An amplification factor of differences between fr and to
grid	whether to calculate and plot changes across the graphical window TRUE or just within the starting shape (FALSE)
over	A numeric that indicates how much the thin plate splines extends over the shapes
palette	A color palette such those included in Momocs or produced with <a href="#">colorRamp-Palette</a>

iso.nb	A numeric. The number of points to use for the calculation of deformation
iso.levels	numeric. The number of levels for mapping the deformations
cont	logical. Whether to draw contour lines
cont.col	A color for drawing the contour lines
poly	whether to draw polygons (for outlines) or points (for landmarks)
shp	logical. Whether to draw shapes
shp.border	Two colors for drawing the borders
shp.lwd	Two lwd for drawing shapes
shp.lty	Two lty fro drawing the shapes
legend	logical whether to plot a legend
legend.text	some text for the legend
...	additional arguments to feed <a href="#">coo_draw</a>

**Value**

No returned value

**See Also**

Other thin plate splines: [tps2d](#), [tps\\_arr](#), [tps\\_grid](#), [tps\\_raw](#)

**Examples**

```
botF <- efourier(bot)
x <- mshapes(botF, 'type', nb.pts=80)$shp
fr <- x$beer
to <- x$whisky
tps_iso(fr, to, iso.nb=200, amp=3)
tps_iso(fr, to, iso.nb=200, amp=3, grid=TRUE)
```

---

 tps\_raw

*Vanilla Thin Plate Splines*


---

**Description**

tps\_raw calculates deformation grids and returns position of sampled points on it.

**Usage**

```
tps_raw(fr, to, amp = 1, over = 1.2, grid.size = 15)
```

**Arguments**

fr	the reference $(x; y)$ coordinates
to	the target $(x; y)$ coordinates
amp	an amplification factor of differences between fr and to
over	numeric that indicates how much the thin plate splines extends over the shapes
grid.size	numeric to specify the number of grid cells on the longer axis on the outlines

**Value**

a list with two components: grid the xy coordinates of sampled points along the grid; dim the dimension of the grid.

**See Also**

Other thin plate splines: [tps2d](#), [tps\\_arr](#), [tps\\_grid](#), [tps\\_iso](#)

**Examples**

```
## Not run:
ms <- mshapes(efourier(bot, 10), "type")
b <- ms$shp$beer
w <- ms$shp$whisky
g <- tps_raw(b, w)
ldk_plot(g$grid)

# a wavy plot
ldk_plot(g$grid, pch=NA)
cols_ids <- 1:g$dim[1]
for (i in 1:g$dim[2]) lines(g$grid[cols_ids + (i-1)*g$dim[1], ])

## End(Not run)
```

---

TraCoe

*Traditional morphometrics class*


---

**Description**

Defines the builder for traditional measurement class in Momocs. Is intended to ease calculations, data handling and multivariate statistics just ad the other Momocs' classes

**Usage**

```
TraCoe(coe = matrix(), fac = dplyr::data_frame())
```

**Arguments**

coe	a matrix of measurements
fac	a data.frame for covariates

**See Also**

Other classes: [Coe](#), [Coo](#), [OpnCoe](#), [Opn](#), [OutCoe](#), [Out](#)

**Examples**

```
# let's (more or less) rebuild the flower dataset
fl <- TraCoe(iris[, 1:4], dplyr::data_frame(sp=iris$Species))
fl %>% PCA() %>% plot("sp")
```

---

trilo

*Data: Outline coordinates of cephalic outlines of trilobite*


---

**Description**

Data: Outline coordinates of cephalic outlines of trilobite

**Format**

A [Out](#) object 64 coordinates of 50 cephalic outlines from different ontogenetic stages of trilobite.

**Source**

Arranged from: <http://folk.uio.no> (used to be in ohammer website but seems to be deprecated now). The original data included 51 outlines and 5 ontogenetic stages, but one of them has just a single outline that has been removed.

**See Also**

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [wings](#)

---

validate

*Validates Coo objects*


---

**Description**

No validation for S3 objects, so this method is a (cheap) attempt at checking [Coo](#) objects, [Out](#), [Opn](#) and [Ldk](#) objects.

**Usage**

```
validate(Coo)
```

**Arguments**

Coo                    any Coo object

**Details**

Implemented before all morphometric methods and handling verbs. To see what is checked, try eg `Momocs:::validate.Coo`

**Value**

a Coo object.

**Examples**

```
## Not run:
validate(bot)
bot[12] <- NA
validate(bot)

validate(hearts)
hearts$ldk[[4]] <- c(1, 2)
validate(hearts)

## End(Not run)
```

---

which_out	<i>Identify outliers</i>
-----------	--------------------------

---

**Description**

A simple wrapper around `dnorm` that helps identify outliers. In particular, it may be useful on `Coe` object (in this case a PCA is first calculated) and also on `Ldk` for detecting possible outliers on freshly digitized/imported datasets.

**Usage**

```
which_out(x, conf, nax, ...)
```

**Arguments**

x	object, either <code>Coe</code> or a numeric on which to search for outliers
conf	confidence for <code>dnorm</code> (1e-3 by default)
nax	number of axes to retain (only for <code>Coe</code> ), if <1 retain enough axes to retain this proportion of the variance
...	additional parameters to be passed to PCA (only for <code>Coe</code> )

**Note**

experimental. `dnorm` parameters used are `median(x)`, `sd(x)`

**Examples**

```

# on a numeric
x <- rnorm(10)
x[4] <- 99
which_out(x)

# on a Coe
bf <- bot %>% efourier(6)
bf$coe[c(1, 6), 1] <- 5
which_out(bf)

# on Ldk
w_no <- w_ok <- wings
w_no$coo[[2]][1, 1] <- 2
w_no$coo[[6]][2, 2] <- 2
which_out(w_ok, conf=1e-12) # with low conf, no outliers
which_out(w_no, conf=1e-12) # as expected

# a way to illustrate, filter outliers
# conf has been chosen deliberately low to show some outliers
x_f <- bot %>% efourier
x_p <- PCA(x_f)
# which are outliers (conf is ridiculously low here)
which_out(x_p$x[, 1], 0.5)
cols <- rep("black", nrow(x_p$x))
outliers <- which_out(x_p$x[, 1], 0.5)
cols[outliers] <- "red"
plot(x_p, col=cols)
# remove them for Coe, rePCA, replot
x_f %>% slice(-outliers) %>% PCA %>% plot

# or directly with which_out.Coe
# which relies on a PCA
outliers <- x_f %>% which_out(0.5, nax=0.95) %>% na.omit()
x_f %>% slice(-outliers) %>% PCA %>% plot

```

---

wings

*Data: Landmarks coordinates of mosquito wings*


---

**Description**

Data: Landmarks coordinates of mosquito wings

**Format**

A [Ldk](#) object containing 18 (x; y) landmarks from 127 mosquito wings, from

**Source**

Rohlf and Slice 1990 and <http://life.bio.sunysb.edu/morph/data/RohlfSlice1990Mosq.nts>

**See Also**

Other datasets: [apodemus](#), [bot](#), [chaff](#), [charring](#), [flower](#), [hearts](#), [molars](#), [mosquito](#), [mouse](#), [nsfishes](#), [oak](#), [olea](#), [shapes](#), [trilo](#)

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