

Package ‘landmap’

April 21, 2021

Title Automated Spatial Prediction using Ensemble Machine Learning

Version 0.0.9

Description Functions and tools for spatial interpolation and/or prediction of environmental variables (points to grids) based on using Ensemble Machine Learning with geographical distances. Package also provides access to Global Environmental Layers (<<https://www.OpenLandMap.org>>) produced by the OpenGeoHub.org foundation and collaborators. Some functions have been migrated and adopted from the Global Soil Information Facilities package.

Depends R (>= 3.5.0)

License GPL-3

Encoding UTF-8

LazyData true

URL <https://github.com/envirometrix/landmap/>

BugReports <https://github.com/envirometrix/landmap/issues/>

Imports methods, utils, parallel, matrixStats, ranger, forestError, glmnet, mlr, parallelMap, sp, rgdal, meteo, gdalUtils, raster

Suggests geoR, ParamHelpers, mda, psych, spdep, fossil, xgboost, plyr, kernlab, nnet, rjson, spatstat, spatstat.core, maptools, maxlike, RCurl, aqp, deepnet, RSAGA, soiltexture, snowfall, plotKML, boot

RoxygenNote 7.1.1

SystemRequirements C++11, GDAL (>= 2.0.1), GEOS (>= 3.4.0), PROJ (>= 4.8.0)

NeedsCompilation no

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`buffer.dist,SpatialPointsDataFrame,SpatialPixelsDataFrame-method`
Derive buffer distances for a list of points

Description

Derive buffer distances using the `raster::distance` function, so that these can be used as predictors for spatial prediction i.e. to account for spatial proximity to low, medium and high values.

Usage

```
## S4 method for signature 'SpatialPointsDataFrame,SpatialPixelsDataFrame'  
buffer.dist(  
  observations,  
  predictionDomain,  
  classes,  
  width,  
  parallel = TRUE,  
  ...  
)
```

Arguments

observations	SpatialPointsDataFrame.
predictionDomain	SpatialPixelsDataFrame.
classes	vector of selected points as factors.
width	maximum width for buffer distance.
parallel	optional parallelization setting.
...	optional arguments to pass to raster::distance function.

Value

object of class SpatialPixelsDataFrame with distances to points

Author(s)

Tom Hengl

References

- Hengl, T., Nussbaum, M., Wright, M. N., Heuvelink, G. B., and Gräler, B. (2018) Random Forest as a generic framework for predictive modeling of spatial and spatio-temporal variables. PeerJ 6:e5518. doi: [10.7717/peerj.5518](https://doi.org/10.7717/peerj.5518)

Examples

```
library(raster)  
library(rgdal)  
demo(meuse, echo=FALSE)  
b <- buffer.dist(meuse["zinc"], meuse.grid[1],  
  classes=as.factor(1:nrow(meuse)), parallel=FALSE)
```

 cookfarm

The Cook Agronomy Farm data set

Description

The **R.J. Cook Agronomy Farm** (cookfarm) is a Long-Term Agroecosystem Research Site operated by Washington State University, located near Pullman, Washington, USA. Contains spatio-temporal (3D+T) measurements of three soil properties and a number of spatial and temporal regression covariates.

Usage

```
data(cookfarm)
```

Format

The cookfarm data set contains four data frames. The readings data frame contains measurements of volumetric water content (cubic-m/cubic-m), temperature (degree C) and bulk electrical conductivity (dS/m), measured at 42 locations using 5TE sensors at five standard depths (0.3, 0.6, 0.9, 1.2, 1.5 m) for the period "2011-01-01" to "2012-12-31":

SOURCEID factor; unique station ID

Date date; observation day

Port*VW numeric; volumetric water content measurements at five depths

Port*C numeric; soil temperature measurements at five depths

Port*EC numeric; bulk electrical conductivity measurements at five depths

The profiles data frame contains soil profile descriptions from 142 sites:

SOURCEID factor; unique station ID

Easting numeric; x coordinate in the local projection system

Northing numeric; y coordinate in the local projection system

TAXNUSDA factor; Keys to Soil Taxonomy taxon name e.g. "Caldwell"

HZDUSD factor; horizon designation

UHDICM numeric; upper horizon depth from the surface in cm

LHDICM numeric; lower horizon depth from the surface in cm

BLD bulk density in tonnes per cubic-meter

PHIHOX numeric; pH index measured in water solution

The grids data frame contains values of regression covariates at 10 m resolution:

DEM numeric; Digital Elevation Model

TWI numeric; SAGA GIS Topographic Wetness Index

MUSYM factor; soil mapping units e.g. "Thatuna silt loam"

NDRE.M numeric; mean value of the Normalized Difference Red Edge Index (time series of 11 RapidEye images)

NDRE.sd numeric; standard deviation of the Normalized Difference Red Edge Index (time series of 11 RapidEye images)

Cook_fall_EC*a* numeric; apparent electrical conductivity image from fall

Cook_spr_EC*a* numeric; apparent electrical conductivity image from spring

X2011 factor; cropping system in 2011

X2012 factor; cropping system in 2012

The weather data frame contains daily temperatures and rainfall from the nearest meteorological station:

Date date; observation day

Precip_wrcc numeric; observed precipitation in mm

MaxT_wrcc numeric; observed maximum daily temperature in degree C

MinT_wrcc numeric; observed minimum daily temperature in degree C

Note

The farm is 37 ha, stationed in the hilly Palouse region, which receives an annual average of 550 mm of precipitation, primarily as rain and snow in November through May. Soils are deep silt loams formed on loess hills; clay silt loam horizons commonly occur at variable depths. Farming practices at Cook Farm are representative of regional dryland annual cropping systems (direct-seeded cereal grains and legume crops).

Author(s)

Caley Gasch, Tomislav Hengl and David J. Brown

References

- Gasch, C.K., Hengl, T., Graeler, B., Meyer, H., Magney, T., Brown, D.J., 2015. Spatio-temporal interpolation of soil water, temperature, and electrical conductivity in 3D+T: the Cook Agronomy Farm data set. *Spatial Statistics*, 14, pp. 70–90. doi: [10.1016/j.spasta.2015.04.001](https://doi.org/10.1016/j.spasta.2015.04.001)
- Gasch, C. K., Brown, D. J., Campbell, C. S., Cobos, D. R., Brooks, E. S., Chahal, M., & Poggio, M. 2017. A Field-Scale Sensor Network Data Set for Monitoring and Modeling the Spatial and Temporal Variation of Soil Water Content in a Dryland Agricultural Field. *Water Resources Research*, 53(12), 10878-10887. doi: [10.1002/2017wr021307](https://doi.org/10.1002/2017wr021307)

Examples

```
library(rgdal)
data(cookfarm)

## gridded data:
grid10m <- cookfarm$grids
gridded(grid10m) <- ~x+y
proj4string(grid10m) <- CRS(cookfarm$proj4string)
```

```
#spplot(grid10m["DEM"], col.regions=SAGA_pal[[1]])

## soil profiles:
profs <- cookfarm$profiles
levels(cookfarm$profiles$HZDUSD)
## Bt horizon:
sel.Bt <- grep("Bt", profs$HZDUSD, ignore.case=FALSE, fixed=FALSE)
profs$Bt <- 0
profs$Bt[sel.Bt] <- 1
```

download.landgis	<i>Access and download layers from OpenLandMap.org (LandGIS data service)</i>
------------------	---

Description

Access and download layers from OpenLandMap.org (LandGIS data service)

Usage

```
download.landgis(
  coverageId,
  filename,
  scalefactor = NULL,
  subset = NULL,
  service = paste0(c("https://geoserver.opengeohub.org/landgisgeoserver/ows",
    "?service=WCS&version=2.0.1")),
  silent = TRUE,
  ...
)
```

Arguments

coverageId	Coverage ID.
filename	Download filename.
scalefactor	Scale factor for WCS request.
subset	Subset string for WCS request.
service	URL of the WCS service.
silent	Silent output.
...	optional utils::download.file settings.

Value

Locally downloaded GeoTIFF.

Author(s)

Tom Hengl

Examples

```
search.landgis(pattern=c("clay", "10..10cm"))
```

edgeroi

*The Edgeroi Data Set***Description**

Soil samples and covariate layers for the Edgeroi area in NSW, Australia (ca 1500 square-km).

Usage

```
data(edgeroi)
```

Format

The `edgeroi` data set contains two data frames — `sites` and `horizons`. `Sites` table contains the following columns:

`SOURCEID` factor; unique label to help a user identify a particular site (ID in the [NatSoil](#))

`LONGDA94` numeric; longitude in decimal degrees on the GDA94 datum

`LATGDA94` numeric; latitude in decimal degrees on the GDA94 datum

`TAXGAUC` factor; Australian Great Soil Groups (GSG; see details)

`NOTE0BS` character; free-form observation notes

`Horizons` table contains the following columns:

`SOURCEID` factor; unique identifier used in the NatSoil DB

`LSQINT` integer; a layer sequence number 1 to N

`HZDUSD` factor; horizon designation (primary letter)

`UHDICM` numeric; upper horizon depth from the surface in cm

`LHDICM` numeric; lower horizon depth from the surface in cm

`CLYPPT` numeric; weight percentage of the clay particles (<0.0002 mm)

`SNDPPT` numeric; weight percentage of the silt particles (0.0002–0.05 mm)

`SLTPPT` numeric; weight percentage of the sand particles (0.05–2 mm)

`PHIH05` numeric; pH index measured in water solution (`ph_h2o` in the NSCD)

`ORCDRC` numeric; soil organic carbon content in permille

The `edgeroi.grids` data frame contains a list of covariates at 250 m resolution:

`DEMSRT5` numeric; SRTM DEM

TWISRT5 numeric; SAGA Topographic Wetness Index based on the SRTM DEM

PMTGE05 factor; parent material class based on the National Geological map at scale 1:250,000 — sand with minor silty sand ("Qd"), alluvium gravel, sand, silt, clay ("Qrs"), quartz sandstone obscured by quaternary sands ("Qrt/Jp"), quartz sandstone obscured by talus material ("Qrt/Rn"), basalt obscured by talus material ("Qrt/Tv"), mottled clay, silt, sandstone and gravel ("Ts"), and basalt, dolerite, trachyte, techenite ("Tv")

EV1MOD5 numeric; first principal component of the MODIS EVI (MOD13Q1) time series data (year 2011)

EV2MOD5 numeric; second principal component of the MODIS EVI (MOD13Q1) time series data (year 2011)

EV3MOD5 numeric; third principal component of the MODIS EVI (MOD13Q1) time series data (year 2011)

x numeric; x-coordinate in the GDA94 / MGA zone 55

y numeric; y-coordinate in the GDA94 / MGA zone 55

The `edgeroi.grids100` data frame contains a list of covariates at 100 m resolution prepared for the study area:

LNUABS6 factor; Australian National scale land use data

MVBSRT6 numeric; SAGA GIS Multi-resolution Index of Valley Bottom Flatness based on the SRTM DEM

TI1LAN6 numeric; principal component 1 for the Landsat band 7 (thermal) based on three periods of the Global Land Survey Landsat images (GLS1990, GLS2000, GLS2005)

TI2LAN6 numeric; principal component 2 for the Landsat band 7 (thermal) based on three periods of the Global Land Survey Landsat images (GLS1990, GLS2000, GLS2005)

PCKGAD6 numeric; percentage of Potassium estimated based on the gamma radiometrics radmap09 (GADDS)

RUTGAD6 numeric; ratio Uranium over Thorium estimated based on the gamma radiometrics radmap09 (GADDS)

PCTGAD6 numeric; parts per million of Thorium estimated based on the gamma radiometrics radmap09 (GADDS)

x numeric; x-coordinate in the GDA94 / MGA zone 55

y numeric; y-coordinate in the GDA94 / MGA zone 55

Details

The Edgeroi is one of the standard soil data sets used to test soil mapping methods in Australia. Out of 359 profiles, 210 sites were sampled on a systematic, equilateral triangular grid with a spacing of 2.8 km between sites, the other sites are distributed more irregularly or on transects. The data set is described in detail in Malone et al. (2010; doi: [10.1016/j.geoderma.2009.10.007](https://doi.org/10.1016/j.geoderma.2009.10.007)) and McGarry et al. (1989). The `edgeroi` contains only a subset of the original **NatSoil** records. Observed soil classes for TAXGAUC are (alphabetically): Alluvial soil ("A"), Brown clay ("BC"), Black earth ("BE"), Earthy sand ("ES"), Grey clay ("GC"), Grey earth ("GE"), No suitable group ("NSG"), Prairie soil ("PS"), Rendzina ("R"), Red-brown earth ("RBE"), Red clay ("RC"), Red earth ("RE"), Red podzolic soil ("RP"), Solodic soil ("SC"), Soloth ("SH"), Solonchak ("SK"), Siliceous sand ("SS"), and Solonetz ("SZ").

Note

The Landsat images and SRTM DEM have been obtained from the [Global Land Cover Facility](#). Scanned geology map (paper sheets) has been obtained from the [Geoscience Australia](#), then georeferenced and rasterized to 250 m resolution. The land use map has been obtained from the Australian Collaborative Land Use and Management program. The Radiometric Map of Australia grids has been downloaded using the Geophysical Archive Data Delivery System (GADDS) on the Australian Government's Geoscience Portal (Mitny et al, 2009; doi: [10.1071/EG09025](#)).

Listed gridded layers follow a standard naming convention used by WorlGrids.org (the standard 8.3 filename convention with at most eight characters): first three letter are used for the variable type e.g. DEM (digital elevation model); the next three letters represent the data source or collection method e.g. SRT (SRTM mission); the 6th character is the effective scale e.g. 5 indicates the 5th standard scale i.e. 1/600 decimal degrees (in this case 250 m).

Author(s)

The [original detailed profile description and laboratory analysis](#) was funded by a Cotton Research and Development Corporation project in the mid-late 1980's by the CSIRO Division of Soils and available via the [NatSoil DB](#). The gamma radiometrics images are property of the NSW Department of Primary Industries — Mineral Resources.

References

- Malone, B.P., McBratney, A.B., Minasny, B. (2010) Mapping continuous depth functions of soil carbon storage and available water capacity. *Geoderma* 154, 138-152. doi: [10.1016/j.geoderma.2009.10.007](#)
- McGarry, D., Ward, W.T., McBratney, A.B. (1989) Soil Studies in the Lower Namoi Valley: Methods and Data. The Edgeroi Data Set. (2 vols) (CSIRO Division of Soils: Adelaide).
- Minty, B., Franklin, R., Milligan, P., Richardson, L.M., and Wilford, J., (2009) The Radiometric Map of Australia. *Exploration Geophysics*, 40(4), 325-333. doi: [10.1071/EG09025](#)

Examples

```
library(rgdal)
library(aqp)
library(sp)

data(edgeroi)
edgeroi$sites[edgeroi$sites$SOURCEID=="399_EDGEROI_ed095_1",]
edgeroi$horizons[edgeroi$horizons$SOURCEID=="399_EDGEROI_ed095_1",]
## spPoints:
sites <- edgeroi$sites
coordinates(sites) <- ~ LONGDA94 + LATGDA94
proj4string(sites) <- CRS("+proj=longlat +ellps=GRS80 +towgs84=0,0,0,0,0,0,0 +no_defs")
sites <- spTransform(sites, CRS("+init=epsg:28355"))

## plot points and grids:
pnts <- list("sp.points", sites, pch="+", col="black")
## load the 250 m grids:
```

```

library(RCurl)
rep = "https://raw.githubusercontent.com/Envirometrix/PredictiveSoilMapping/master/extdata/"
x = tempfile(fileext = ".rda")
wget.check = Sys.which("wget")
if(!wget.check==""){
  con <- download.file(paste0(rep, "edgeroi.grids.rda"), x, method="wget")
  load(x)
  str(edgeroi.grids)
  gridded(edgeroi.grids) <- ~x+y
  proj4string(edgeroi.grids) <- CRS("+init=epsg:28355")
  spplot(edgeroi.grids[1], sp.layout=pnts)
  ## load the 100 m grids:
  x2 = tempfile(fileext = ".rda")
  con2 <- download.file(paste0(rep, "edgeroi.grids100.rda"), x2, method="wget")
  load(x2)
  str(edgeroi.grids100)
  gridded(edgeroi.grids100) <- ~x+y
  proj4string(edgeroi.grids100) <- CRS("+init=epsg:28355")
  spplot(edgeroi.grids100["TI1LAN6"], sp.layout=pnts)
}

```

fit.vgmModel,formula,data.frame,SpatialPixelsDataFrame-method

Fit variogram using point data

Description

Fit variogram using point data

Usage

```

## S4 method for signature 'formula,data.frame,SpatialPixelsDataFrame'
fit.vgmModel(
  formulaString.vgm,
  rmatrix,
  predictionDomain,
  cov.model = "exponential",
  dimensions = list("2D", "3D", "2D+T", "3D+T"),
  lambda = 0.5,
  psiR = NULL,
  subsample = nrow(rmatrix),
  ini.var,
  ini.range,
  fix.psiA = FALSE,
  fix.psiR = FALSE,
  ...
)

```

Arguments

formulaString.vgm	formula.
rmatrix	data.frame with coordinates and values of covariates.
predictionDomain	SpatialPixelsDataFrame.
cov.model	covariance model type used by the geoR package.
dimensions	optional 2D or 3D dimensions.
lambda	transformation value used by the geoR package.
psiR	range parameter used by the geoR package.
subsample	number of subset of original samples.
ini.var	initial variance (sill) used by the geoR package.
ini.range	initial range parameter used by the geoR package.
fix.psiA	setting used by the geoR package.
fix.psiR	setting used by the geoR package.
...	optional arguments to pass to the geoR package.

Value

Fitted variogram model

Note

Extends variogram fitting functionality from the geoR package. Can be used for 2D or 3D point data sets, with and without trend variables. Models need to be in the form $zinc \sim dist$ and only numeric variables are allowed. Often reports Singular matrix. Covariates may have different orders of magnitude. if the covariates are perfectly aligned.

Author(s)

Tom Hengl

Examples

```
library(raster)
library(rgdal)
library(geoR)
demo(meuse, echo=FALSE)
vgm = fit.vgmModel(zinc~dist, as.data.frame(meuse), meuse.grid["dist"], lambda=1)
plot(variog(vgm$geodata))
lines(vgm$vgm)
```

`getSpatialTiles, ANY-method`

Estimate a tiling system

Description

Estimate a tiling system

Usage

```
## S4 method for signature 'ANY'
getSpatialTiles(
  obj,
  block.x,
  block.y = block.x,
  overlap.percent = 0,
  limit.bbox = TRUE,
  return.SpatialPolygons = FALSE
)
```

Arguments

<code>obj</code>	ANY.
<code>block.x</code>	size of the block in x dimension.
<code>block.y</code>	size of the block in y dimension.
<code>overlap.percent</code>	optional overlap percent between tiles.
<code>limit.bbox</code>	optional bounding box.
<code>return.SpatialPolygons</code>	logical specifies whether to return a data frame or Spatial Polygons.

Value

Tiling system for a spatial object

`getSpatialTiles, Spatial-method`

Split a Spatial object into tiles

Description

Split a Spatial object into tiles

Usage

```
## S4 method for signature 'Spatial'  
getSpatialTiles(  
  obj,  
  block.x,  
  block.y = block.x,  
  overlap.percent = 0,  
  limit.bbox = TRUE,  
  return.SpatialPolygons = TRUE  
)
```

Arguments

obj	output of the GDALInfo.
block.x	size of the block in x dimension.
block.y	size of the block in y dimension.
overlap.percent	optional overlap percent between tiles.
limit.bbox	optional bounding box.
return.SpatialPolygons	logical specificities whether to return a data frame or Spatial Polygons.

Value

List of object result of clipping

Author(s)

[Tom Hengl](#)

Examples

```
library(sp)  
data(meuse.grid)  
gridded(meuse.grid) <- ~x+y  
tl <- getSpatialTiles(meuse.grid, block.x=1000)  
image(meuse.grid)  
lines(as(tl, "SpatialLines"))  
## all at once:  
pix.lst <- tile(meuse.grid, block.x=1000)  
  
library(plotKML)  
## raster files via rgdal:  
library(rgdal)  
fn = system.file("pictures/SP27GTIF.TIF",  
                 package = "rgdal")  
obj <- GDALInfo(fn)  
ras.lst <- getSpatialTiles(obj, block.x=1000)  
offset <- c(ras.lst$offset.y[1], ras.lst$offset.x[1])
```

```

region.dim <- c(ras.lst$region.dim.y[1],
               ras.lst$region.dim.x[1])
## read the first tile:
SP27GTIF_T1 <- readGDAL(fn, offset=offset,
                       region.dim=region.dim)
str(SP27GTIF_T1)

```

 isis

ISRIC Soil Information System

Description

ISRIC's collection of global soil monoliths that represent the main soil reference groups of the World Reference Base for Soil Resources (WRB). Includes some 950 monoliths (785 with coordinates) from over 70 countries with detailed soil profile and environmental data.

Usage

```
data(isis)
```

Format

The *isis* data set contains two data frames — *sites* and *horizons*. *Sites* table contains the following columns:

SOURCEID factor; unique ISIS code
 LONWGS84 numeric; longitude in decimal degrees on the WGS84 datum
 LATWGS84 numeric; latitude in decimal degrees on the WGS84 datum
 TIMESTRR Date; the date on which this particular soil was described or sampled
 TAXGWRB factor; soil group based on the WRB classification system
 TAXNUSDA factor; Keys to Soil Taxonomy taxon name e.g. "Natraqualf"
 BDRICM numeric; depth to bedrock (R horizon) if observed
 SOURCEDB factor; source data base

Horizons table contains the following columns:

SOURCEID factor; unique ISIS code
 UHDICM numeric; upper horizon depth from the surface in cm
 LHDICM numeric; lower horizon depth from the surface in cm
 CRFVOL numeric; volume percentage of coarse fragments (> 2 mm)
 PHIHOX numeric; pH index measured in water solution
 PHIKCL numeric; pH index measured in KCl solution
 ORCDRC numeric; soil organic carbon content in permilles

SNDPPT numeric; weight percentage of the sand particles (0.05–2 mm)
 SLTPPT numeric; weight percentage of the silt particles (0.0002–0.05 mm)
 CLYPPT numeric; weight percentage of the clay particles (<0.0002 mm)
 CEC numeric; Cation Exchange Capacity in cmol+/kg
 BLD bulk density in tonnes per cubic-meter

Author(s)

ISRIC — World Soil Information

Examples

```
library(rgdal)
library(sp)

data(isis)
sites <- isis$sites
coordinates(sites) <- ~ LONWGS84 + LATWGS84
proj4string(sites) <- "+proj=longlat +datum=WGS84"
## Not run:
## obtain country borders:
library(maps)
country.m = map('world', plot=FALSE, fill=TRUE)
IDs <- sapply(strsplit(country.m$names, ":"), function(x) x[1])
require(maptools)
country <- as(map2SpatialPolygons(country.m, IDs=IDs), "SpatialLines")
proj4string(country) = "+proj=longlat +datum=WGS84"
## overlay and plot points and maps:
plot(country, col="darkgrey")
points(sites, pch=21, bg="red", cex=.6, col="black")

## End(Not run)
```

landgis.tables

OpenLandMap list of GeoTIFFs global mosaics

Description

Computer names of the layers in the www.OpenLandMap.org.

Usage

```
data(landgis.tables)
```

Format

The `landgis.tables` data set contains four objects:

`tables` `data.frame`; layer metadata

`layers` `list`; list of layers at different resolutions

`classes` `list`; list of classes

`zenodo.files` `list`; list of URI addressed to download all OpenLandMap.org layers

References

- <https://openlandmap.org>

Examples

```
data(landgis.tables)
str(landgis.tables$tables[1,])
```

landmap	<i>landmap: Automated Spatial Prediction using Ensemble Machine Learning</i>
---------	--

Description

Geographical distances can be used with remote sensing covariates and process-based derivatives to improve spatial prediction and/or interpolation from point data. This package shows how to fully automate process so that predictions and model errors can be generated using unbiased estimation (`train.spLearner` package). Additional functions are used to access global layers (from www.openlandmap.org), to process large rasters (spatial tiling) including running own customized functions in parallel.

makeTiles	<i>Make a tiling system from a bounding box</i>
-----------	---

Description

Make a tiling system from a bounding box

Usage

```
makeTiles(
  bb,
  block.x,
  block.y,
  overlap.percent,
  limit.bbox,
  columns = NULL,
  rows = NULL
)
```


Arguments

bb	Bounding Box
block.x	Size of the block in X
block.y	Size of the block in Y
overlap.percent	Percent of overlap; default 0
limit.bbox	Optional limiting bounding box
columns	Optional number of columns
rows	Optional number of rows

Value

A regular tiling system

Author(s)

Tom Hengl

model.data

Overlay points and grids and prepare regression matrix

Description

Overlay points and grids and prepare regression matrix

Usage

```
model.data(
  observations,
  formulaString,
  covariates,
  dimensions = c("2D", "3D", "2D+T", "3D+T")
)
```

Arguments

observations	SpatialPointsDataFrame
formulaString	Model definition
covariates	List of covariates column names
dimensions	2D, 3D models

Value

Regression matrix data.frame

predict.spLearner *Predict using spLearner at new locations*

Description

Predict using spLearner at new locations

Usage

```
## S3 method for class 'spLearner'
predict(
  object,
  predictionLocations,
  model.error = TRUE,
  error.type = c("forestError", "quantreg", "weighted.sd", "interval")[1],
  t.prob = 1/3,
  w,
  quantiles = c((1 - 0.682)/2, 1 - (1 - 0.682)/2),
  n.cores = parallel::detectCores(),
  what = c("mspe", "bias", "interval"),
  ...
)
```

Arguments

object	of type spLearner.
predictionLocations	SpatialPixelsDataFrame with values of all features.
model.error	Logical specify if prediction errors should be derived.
error.type	Specify how should be the prediction error be derived.
t.prob	Threshold probability for significant learners; only applies for meta-learners based on lm model.
w	optional weights vector.
quantiles	Lower and upper quantiles for quantreg forest (0.159 and 0.841 for 1 standard deviation).
n.cores	Number of cores to use (for parallel computation in ranger).
what	A vector of characters indicating what estimates are desired for the quantForestError.
...	optional parameters.

Value

Object of class SpatialPixelsDataFrame with predictions and model error.

```
print.spLearner      Print object of type 'spLearner'
```

Description

Print object of type 'spLearner'

Usage

```
## S3 method for class 'spLearner'
print(x, ...)
```

Arguments

```
x                of type spLearner
...              optional parameters
```

Value

Model summary

```
sample.grid,SpatialPointsDataFrame-method
      Sample spatial points by grids
```

Description

Get a subset of a object of class "SpatialPoints" or "SpatialPointsDataFrame" avoiding spatial clustering.

Usage

```
## S4 method for signature 'SpatialPointsDataFrame'
sample.grid(obj, cell.size, n, bbox, ...)
```

Arguments

```
obj              "SpatialPoints*" object,
cell.size        numeric; the cell size of the overlaid "SpatialGridDataFrame" in the form
                  of c(x,y),
n                integer; specifies maximum number points in each grid,
bbox             matrix; the bounding box of output "SpatialPoints" or "SpatialPointsDataFrame";
                  it is set the same as the obj if missing
...             other optional arguments that can be passed to over
```

Value

Returns a list of two objects: (1) an object of type "SpatialPoints" or "SpatialPointsDataFrame" that contains a subset of the obj, and (2) resulting grid.

Note

Spatial points are overlaid with spatial grids with a specified cell size and then get a subset from each grid with a specified number at most. If one grid has less points than the specified number, all the points are taken. If one grid has more points than the specified number, only this number of points are taken by [sample](#). This function can be used when there are too much point observations to be handled, especially for spatially clustered observations. The total number of sampled points are determined by `cell.size` and `n` together. You will get fewer the sampled points when `cell.size` is larger, or/and when `n` is smaller. Similar sample sizes can be achieved by different combinations of `cell.size` and `n`.

Author(s)

Wei Shangguan

References

- Shangguan, W., Hengl, T., de Jesus, J. M., Yuan, H., & Dai, Y. (2017). Mapping the global depth to bedrock for land surface modeling. *Journal of Advances in Modeling Earth Systems*, 9(1), 65-88. doi: [10.1002/2016MS000686](https://doi.org/10.1002/2016MS000686)

Examples

```
library(sp)
data(edgeroi)
profs <- edgeroi[["sites"]]
coordinates(profs) <- ~ LONGDA94 + LATGDA94
proj4string(profs) <- CRS("+proj=longlat +ellps=GRS80 +towgs84=0,0,0,0,0,0,0 +no_defs")
## sample SpatialPointsDataFrame:
prof1 <- sample.grid(profs, cell.size = c(0.02,0.02), n = 1)
l0 <- list("sp.points", profs, pch=1, col="red")
l1 <- list("sp.points", prof1$subset, pch="+", col="black", cex=1.2)
spplot(prof1$grid, scales=list(draw=TRUE),
        col.regions="grey", sp.layout=list(l0, l1))
## Subsampling ratio in percent:
round(length(prof1$subset)/length(profs)*100, 1)
```

search.landgis

Search for available landgis layers

Description

Search for available landgis layers

Usage

```
search.landgis(
  pattern,
  layersURL = "https://landgisapi.opengeohub.org/query/layers",
  update = FALSE
)
```

Arguments

pattern	String pattern
layersURL	Default URL with the list of layers
update	Logical specify to update the layer list

Value

List of available landgis layers

 sic1997

The SIC 1997 Data Set

Description

Daily rainfall dataset from Switzerland used in the Spatial Interpolation Comparison 1997.

Usage

```
data(sic1997)
```

Format

The sic1997 data set contains two objects — stations (points) and covariates (1 km grids). The `daily.rainfall` contains the following columns:

`rainfall` numeric; daily rainfall measurements at 467 meteo stations on the 8th of May 1986

`X` numeric; easting in the local coordinate system

`Y` numeric; northing in the local coordinate system

Object `swiss1km` contains the following columns:

`CHELSA_rainfall` numeric; monthly rainfall based on the CHELSA climate grids

`DEM` numeric; digital elevation based on the SRTM DEM

`border` character; country border mask

Details

The gathering of the rainfall data, provided by Giovanni Graziani from the Environment Institute of the Joint Research Centre (Ispra, Italy), has been undertaken, under JRC-Ispra funding, by the Air pollution Group at Imperial College, London. The Digital Elevation Model has been provided by EROS Data Centre from the U.S. Geological Survey (USGS). <http://edcwww.cr.usgs.gov/>.

References

- Dubois, G. (1998). Spatial interpolation comparison 97: foreword and introduction. *Journal of Geographic Information and Decision Analysis*, 2(2), 1-10.
- https://wiki.52north.org/AI_GEOSTATS/WebHome

Examples

```
data(sic1997)
```

soil.classes	<i>Soil classification tables</i>
--------------	-----------------------------------

Description

Standard soil classification tables for the United States Department of Agriculture (USDA) and IUSS / FAO World Reference Base (WRB) classification systems, including the tables used to correlate various soil classification systems.

Usage

```
data(soil.classes)
```

Format

Contains a list of tables:

Canadian data frame; Canadian soil classification system (Soil Classification Working Group, 1998)

FAO1990.WRB data frame; FAO 1990 (FAO-Unesco Soil Classification System) system to WRB (2006)

USDA_GreatGroups data frame; list of USDA Great Groups (USDA, 2010)

WRB_versions data frame; correlation between various FAO/WRB versions (Krasilnikov et al. 2009)

FAO1974.WRB data frame; correlation FAO 1974 system to WRB (IUSS Working Group WRB, 2006)

USDA.WRB data frame; correlation USDA system to WRB system

Soils_World data frame; referent soil profiles of the world (van Baren and Lof, 1987)

Note

Some of the original tables from the literature have been adjusted / updated by the author. Correlation between various national and international systems often leads to multiple soil classes being possible equivalents. These are separated in tables using "/" symbol e.g. Dark Gray Chernozem = Boralfic Boroll / Alboll. Some national soil classification systems contain classes which are completely unique and hence most likely can not be correlated to any class in the target system.

Author(s)

Tomislav Hengl

References

- van Baren, H. and Lof, P. (1987) Soils of the World, published by Elsevier in Association with ISRIC, FAO, and UNESCO ISBN 0444425756
- Krasilnikov, P., Marti, J., Arnold, R., and Shoba, S., eds. (2009) A Handbook of Soil Terminology, Correlation and Classification, Earthscan LLC, pp. 448 ISBN 9781136546631
- Soil Classification Working Group, (1998) The Canadian System of Soil Classification. 3rd Ed. Agriculture and Agri-Food Canada Publication 1646, 187 pp. ISBN 0660174049
- USDA / Soil Survey Staff, (2010) Keys to Soil Taxonomy (Eleventh Edition) U.S. Department Of Agriculture, Natural Resources Conservation Service, 346 pp. ISBN 9781782662112
- IUSS Working Group WRB (2006) World Reference Base for Soil Resources 2006: A Framework for International Classification, Correlation and Communication, Food and Agriculture Organization of the United Nations 128 pp.

Examples

```
data(soil.classes)
soil.classes$USDA_GreatGroups[1,]
DGC <- which(soil.classes$Canadian$CSSC_Great_Groups=="Dark Gray Chernozem")
soil.classes$Canadian[DGC,]
```

soil.legends

Standard color palettes for soil properties and classes

Description

Standard color palettes for soil properties and classes that can be used to display global soil data.

Usage

```
data(soil.legends)
```

Format

Contains a list of color palettes (data frames with class names / break points, and cumulative probabilities) for:

ORCDRC numeric; soil organic carbon content in permille
 PHIHOX numeric; pH index measured in water solution
 PHIKCL numeric; pH index measured in KCl solution
 BLDFIE numeric; bulk density (fine earth) in kg per cubic meter
 CECSOL numeric; Cation Exchange Capacity of soil
 SNDPPT numeric; weight percentage of the sand particles (0.05–2 mm)
 SLTPPT numeric; weight percentage of the silt particles (0.0002–0.05 mm)
 CLYPPT numeric; weight percentage of the clay particles (<0.0002 mm)
 CRFVOL numeric; volumetric percentage of coarse fragments (>2 mm)
 TAXOUSA factor; Keys to Soil Taxonomy suborders
 TAXGWRB factor; World Reference Base groups
 TAXNWRB factor; World Reference Base legend for SoilGrids250m

Note

Breaks for continuous soil properties were determined using the `quantiles` function and by visually inspecting the histograms to maximize the contrast in output maps. Based on a compilation of global soil profile data (see ISRIC's World Soil Information Service WoSIS).

Author(s)

Tomislav Hengl

References

- Batjes, N. H., Ribeiro, E., van Oostrum, A., Leenaars, J., Hengl, T., & de Jesus, J. M. (2017). WoSIS: providing standardised soil profile data for the world. *Earth System Science Data*, 9(1), 1. doi: [10.5194/essd912017](https://doi.org/10.5194/essd912017)

Examples

```
data(soil.legends)
pal <- soil.legends$ORCDRC$COLOR
names(pal) <- signif((soil.legends$ORCDRC$MAX +
  soil.legends$ORCDRC$MIN)/2, 3)
pal
## Munsell color codes:
data(munsell)
str(munsell)
```

SpatialComponents-class

A class for gridded components derived using the spc method

Description

A class containing a list of gridded components and results of principal component analysis.

Slots

predicted: object of class "SpatialPixelsDataFrame"; predicted values for components
pca: object of class "list"; output objects from the `stats::prcomp` process — contains objects: 'stdev', 'rotation', 'center' and 'scale'

Author(s)

Tomislav Hengl

SpatialMemberships-class

A class for membership maps derived using the fkmeans classification

Description

A class containing a list of gridded maps and results of model fitting.

Slots

predicted: object of class "SpatialPixelsDataFrame"; predicted values (factor)
model: object of class "multinom"; output object from the `nnet::multinom` method
mu: object of class "SpatialPixelsDataFrame"; a list of predicted memberships
class.c: object of class "matrix"; class centres
class.sd: object of class "matrix"; class deviations
confusion: object of class "matrix"; confusion matrix

Author(s)

Tomislav Hengl

See Also

[SpatialComponents-class](#)

spc, SpatialPixelsDataFrame-method

Generate Principal Components using SpatialPixelsDataFrame object

Description

Combines the `stats::prcomp` method and predicts a list principal components for an object of type "SpatialPixelsDataFrame".

Usage

```
## S4 method for signature 'SpatialPixelsDataFrame'  
spc(obj, formulaString, scale. = TRUE, silent = FALSE)
```

Arguments

<code>obj</code>	SpatialPixelsDataFrame.
<code>formulaString</code>	optional model definition.
<code>scale.</code>	scale all numbers.
<code>silent</code>	silent output.

Value

Object of class `SpatialComponents`. List of grids with generic names `PC1, ..., PCp`, where `p` is the total number of input grids.

Note

This method assumes that the input covariates are cross-correlated and hence their overlap can be reduced. The input variables are scaled by default and the missing values will be replaced with 0 values to reduce loss of data due to missing pixels.

Author(s)

Tom Hengl

Examples

```
library(plotKML)  
library(sp)  
pal = rev(rainbow(65)[1:48])  
data(eberg_grid)  
gridded(eberg_grid) <- ~x+y  
proj4string(eberg_grid) <- CRS("+init=epsg:31467")  
formulaString <- ~ PRMGE06+DEMSRT6+TWISRT6+TIRAST6  
eberg_spc <- spc(eberg_grid, formulaString)
```

```

names(eberg_spc@predicted) # 11 components on the end;

## plot maps:
rd = range(eberg_spc@predicted@data[,1], na.rm=TRUE)
sq = seq(rd[1], rd[2], length.out=48)
splot(eberg_spc@predicted[1:4], at=sq, col.regions=pal)

```

```

spfkm, formula, SpatialPointsDataFrame, SpatialPixelsDataFrame-method
Fit a supervised fuzzy kmeans model and predict memberships

```

Description

Runs supervised fuzzy k -means (Hengl et al., 2004; doi: [10.1080/13658810310001620924](https://doi.org/10.1080/13658810310001620924)) using a list of covariates layers provided as "SpatialPixelsDataFrame-class" object. If class centres and variances are not provided, it first fits a multinomial logistic regression model (spmulinom), then predicts the class centers and variances based on the output from the `nnet::multinom`.

Usage

```

## S4 method for signature
## 'formula,SpatialPointsDataFrame,SpatialPixelsDataFrame'
spfkm(
  formulaString,
  observations,
  covariates,
  class.c = NULL,
  class.sd = NULL,
  fuzzy.e = 1.2
)

```

Arguments

formulaString	formula.
observations	SpatialPointsDataFrame.
covariates	SpatialPixelsDataFrame.
class.c	class centers (per variable).
class.sd	class standard deviation (per variable).
fuzzy.e	fuzzy coefficient.

Value

A fuzzy kmeans model

Author(s)

Tom Hengl

Examples

```

library(plotKML)
library(sp)

data(eberg)
# subset to 20%:
eberg <- eberg[runif(nrow(eberg))<.2,]
data(eberg_grid)
coordinates(eberg) <- ~X+Y
proj4string(eberg) <- CRS("+init=epsg:31467")
gridded(eberg_grid) <- ~x+y
proj4string(eberg_grid) <- CRS("+init=epsg:31467")
# derive soil predictive components:
eberg_spc <- spc(eberg_grid, ~PRMGEO6+DEMSRT6+TWISRT6+TIRAST6)
# predict memberships:
formulaString = soiltype ~ PC1+PC2+PC3+PC4+PC5+PC6+PC7+PC8+PC9+PC10
eberg_sm <- spfkm(formulaString, eberg, eberg_spc@predicted)

# plot memberships:
pal = seq(0, 1, 1/50)
spplot(eberg_sm@mu, col.regions=grey(rev(pal)))

```

spmulinom,formula,SpatialPointsDataFrame,SpatialPixelsDataFrame-method
Fits a multinomial logistic regression to spatial data

Description

Fits a multinomial logistic regression to spatial data

Usage

```

## S4 method for signature
## 'formula,SpatialPointsDataFrame,SpatialPixelsDataFrame'
spmulinom(
  formulaString,
  observations,
  covariates,
  class.stats = TRUE,
  predict.probs = TRUE,
  ...
)

```

Arguments

formulaString formula.
 observations SpatialPointsDataFrame.
 covariates SpatialPixelsDataFrame.
 class.stats class statistics.
 predict.probs specify whether to derive probabilities.
 ... optional arguments.

Value

A multinomial logistic regression model

spsample.prob, SpatialPoints, SpatialPixelsDataFrame-method

Estimate occurrence probabilities of a sampling plan (points)

Description

Estimates occurrence probabilities as an average between the kernel density estimation (spreading of points in geographical space) and MaxLike analysis (spreading of points in feature space). The output 'iprob' indicates whether the sampling plan has systematically missed some important locations / features, and can be used as an input for modelling (e.g. as weights for regression modeling).

Usage

```
## S4 method for signature 'SpatialPoints,SpatialPixelsDataFrame'
spsample.prob(observations, covariates, quant.nddist = 0.95, n.sigma, ...)
```

Arguments

observations SpatialPoints.
 covariates SpatialPixelsDataFrame.
 quant.nddist quantile used for the threshold distance.
 n.sigma sigma parameter for density estimation.
 ... optional arguments.

Value

Returns a list of objects where 'iprob' ("SpatialPixelsDataFrame") is the map showing the estimated occurrence probabilities.

Note

Occurrence probabilities for geographical space are derived using kernel density estimator. The sampling intensities are converted to probabilities by deviding the sampling intensity by the maximum sampling intensity for the study area (Baddeley, 2008). The occurrence probabilities for feature space are determined using MaxLike algorithm (Royle et al., 2012; doi: [10.1111/j.2041-210X.2011.00182.x](https://doi.org/10.1111/j.2041-210X.2011.00182.x)). The lower the average occurrence probability for the whole study area, the lower the representation efficiency of a sampling plan.

MaxLike function might fail to produce predictions (e.g. if not at least one continuous covariate is provided and if the optim function is not able to find the global optima) in which case an error message is generated. Running Principal Component analysis i.e. standardizing the covariates prior to running spsample.prob is, thus, highly recommended.

This function can be time consuming for large grids.

Author(s)

Tom Hengl

References

- Baddeley, A. (2008) [Analysing spatial point patterns in R](#). Technical report, CSIRO Australia. Version 4.
- Royle, J.A., Chandler, R.B., Yackulic, C. and J. D. Nichols. (2012) Likelihood analysis of species occurrence probability from presence-only data for modelling species distributions. *Methods in Ecology and Evolution*. doi: [10.1111/j.2041210X.2011.00182.x](https://doi.org/10.1111/j.2041210X.2011.00182.x)

Examples

```
library(plotKML)
library(maxlike)
library(spatstat)
library(maptools)

data(eberg)
data(eberg_grid)
## existing sampling plan:
sel <- runif(nrow(eberg)) < .2
eberg.xy <- eberg[sel,c("X", "Y")]
coordinates(eberg.xy) <- ~X+Y
proj4string(eberg.xy) <- CRS("+init=epsg:31467")
## covariates:
gridded(eberg_grid) <- ~x+y
proj4string(eberg_grid) <- CRS("+init=epsg:31467")
## convert to continuous independent covariates:
formulaString <- ~ PRMGE06+DEMSRT6+TWISRT6+TIRAST6
eberg_spc <- spc(eberg_grid, formulaString)

## derive occurrence probability:
covs <- eberg_spc@predicted[1:8]
iprob <- spsample.prob(eberg.xy, covs)
```

```

## Note: obvious omission areas:
hist(iprob[[1]]@data[,1], col="gray")

## compare with random sampling:
rnd <- spsample(eberg_grid, type="random",
               n=length(iprob[["observations"]]))
iprob2 <- spsample.prob(rnd, covs)

## compare the two next to each other:
op <- par(mfrow=c(1,2))
plot(raster(iprob[[1]]), zlim=c(0,1), col=SAGA_pal[[1]])
points(iprob[["observations"]])
plot(raster(iprob2[[1]]), zlim=c(0,1), col=SAGA_pal[[1]])
points(iprob2[["observations"]])
par(op)
dev.off()

## fit a weighted lm:
eberg.xy <- eberg[sel,c("SNDMHT_A","X","Y")]
coordinates(eberg.xy) <- ~X+Y
proj4string(eberg.xy) <- CRS("+init=epsg:31467")
eberg.xy$iprob <- over(eberg.xy, iprob[[1]])$iprob
eberg.xy@data <- cbind(eberg.xy@data, over(eberg.xy, covs))
fs <- as.formula(paste("SNDMHT_A ~ ",
                      paste(names(covs), collapse="+")))
## the lower the occurrence probability, the higher the weight:
w <- 1/eberg.xy$iprob
m <- lm(fs, eberg.xy, weights=w)
summary(m)
## compare to standard lm:
m0 <- lm(fs, eberg.xy)
summary(m)$adj.r.squared
summary(m0)$adj.r.squared

```

tile,RasterLayer-method

Tile spatial layers

Description

Tile spatial layers

Usage

```

## S4 method for signature 'SpatialPointsDataFrame'
tile(x, y, block.x, ...)
## S4 method for signature 'SpatialPixelsDataFrame'
tile(x, y, block.x, ...)
## S4 method for signature 'SpatialPolygonsDataFrame'

```

```

tile(x, y, block.x, tmp.file = TRUE,
      program, show.output.on.console = FALSE, ...)
## S4 method for signature 'SpatialLinesDataFrame'
tile(x, y, block.x, tmp.file = TRUE,
      program, show.output.on.console = FALSE, ...)
## S4 method for signature 'RasterLayer'
tile(x, y, block.x, tmp.file = TRUE,
      program, show.output.on.console = FALSE, ...)

```

Arguments

x	RasterLayer.
y	either points, pixels, polygons or lines.
block.x	size of the block in x direction.
tmp.file	temporary file name.
program	optional location of the gdalwarp.
show.output.on.console	shows progress.
...	optional argument.

Value

Regular tiling system

Author(s)

Tom Hengl

```

train.spLearner,SpatialPointsDataFrame,ANY,SpatialPixelsDataFrame-method
Train a spatial prediction and/or interpolation model using Ensemble
Machine Learning

```

Description

Automated spatial predictions and/or interpolation using Ensemble Machine Learning. Extends functionality of the **mlr** package. Suitable for predicting numeric, binomial and factor-type variables.

Usage

```

## S4 method for signature 'SpatialPointsDataFrame,ANY,SpatialPixelsDataFrame'
train.spLearner(
  observations,
  formulaString,
  covariates,

```



```

SL.library,
family = stats::gaussian(),
method = "stack.cv",
predict.type,
super.learner = "regr.lm",
subsets = 5,
lambda = 0.5,
cov.model = "exponential",
subsample = 10000,
parallel = "multicore",
oblique.coords = TRUE,
nearest = FALSE,
buffer.dist = FALSE,
theta.list = seq(0, 180, length.out = 14) * pi/180,
spc = TRUE,
id = NULL,
weights = NULL,
n.obs = 10,
...
)

```

Arguments

observations	SpatialPointsDataFrame.
formulaString	ANY.
covariates	SpatialPixelsDataFrame.
SL.library	List of learners,
family	Family e.g. gaussian(),
method	Ensemble stacking method (see makeStackedLearner) usually stack.cv,
predict.type	Prediction type 'prob' or 'response',
super.learner	Ensemble stacking model usually regr.lm,
subsets	Number of subsets for repeated CV,
lambda	Target variable transformation (0.5 or 1),
cov.model	Covariance model for variogram fitting,
subsample	For large datasets consider random subsetting training data,
parallel	logical, Initiate parallel processing,
oblique.coords	Specify whether to use oblique coordinates as covariates,
nearest	Specify whether to use nearest values and distances i.e. the method of Sekulic et al. (2020),
buffer.dist	Specify whether to use buffer distances to points as covariates,
theta.list	List of angles (in radians) used to derive oblique coordinates,
spc	specifies whether to apply principal components transformation.
id	Id column name to control clusters of data,

weights	Optional weights (per row) that learners will use to account for variable data quality,
n.obs	Number of nearest observations to be found in <code>meteo::near.obs</code> (by default 10),
...	other arguments that can be passed on to <code>mlr::makeStackedLearner</code> ,

Value

object of class `spLearner`, which contains fitted model, variogram model and spatial grid used for Cross-validation.

Note

By default uses oblique coordinates (rotated coordinates) as described in Moller et al. (2020; doi: [10.5194/soil62692020](https://doi.org/10.5194/soil62692020)) to account for geographical distribution of values. By setting the `nearest = TRUE`, distances to nearest observations and values of nearest neighbors will be used (see: Sekulic et al, 2020; doi: [10.3390/rs12101687](https://doi.org/10.3390/rs12101687)). This method closely resembles geostatistical interpolators such as kriging. Buffer geographical distances can be added by setting `buffer.dist=TRUE`. Using either oblique coordinates and/or buffer distances is not recommended for point data set with distinct spatial clustering. Effects of adding geographical distances into modeling are explained in detail in Hengl et al. (2018; doi: [10.7717/peerj.5518](https://doi.org/10.7717/peerj.5518)) and Sekulic et al. (2020; doi: [10.3390/rs12101687](https://doi.org/10.3390/rs12101687)). Default learners used for regression are: `c("regr.ranger", "regr.ksvm", "regr.nnet", "regr.cvglmnet")`. Default learners used for classification / binomial variables are: `c("classif.ranger", "classif.svm", "classif.multino")` with `predict.type="prob"`. When using `method = "stack.cv"` each training and prediction round could produce somewhat different results due to randomization of CV. Prediction errors are derived by default using the `forestError` package method described in Lu & Hardin (2021). Optionally, the `quantreg` (Quantile Regression) option from the `ranger` package (Meinshausen, 2006) can also be used.

Author(s)

Tom Hengl

References

- Moller, A. B., Beucher, A. M., Pouladi, N., and Greve, M. H. (2020). Oblique geographic coordinates as covariates for digital soil mapping. *SOIL*, 6, 269–289. doi: [10.5194/soil6269-2020](https://doi.org/10.5194/soil6269-2020)
- Hengl, T., Nussbaum, M., Wright, M. N., Heuvelink, G. B., and Graler, B. (2018) Random Forest as a generic framework for predictive modeling of spatial and spatio-temporal variables. *PeerJ* 6:e5518. doi: [10.7717/peerj.5518](https://doi.org/10.7717/peerj.5518)
- Lu, B., & Hardin, J. (2021). A unified framework for random forest prediction error estimation. *Journal of Machine Learning Research*, 22(8), 1–41. <https://jmlr.org/papers/v22/18-558.html>
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Examples

```

library(mlr)
library(rgdal)
library(geoR)
library(plotKML)
library(kernlab)
library(ranger)
library(glmnet)
library(boot)
library(raster)
library(forestError)
demo(meuse, echo=FALSE)
## Regression:
sl = c("regr.ranger", "regr.nnet", "regr.glm")
m <- train.spLearner(meuse["lead"], covariates=meuse.grid[,c("dist", "ffreq")],
  lambda=0, parallel=FALSE, SL.library=sl)
summary(m@spModel$learner.model$super.model$learner.model)

## regression-matrix:
str(m@evgmModel$observations@data)
meuse.y <- predict(m)
plot(raster(meuse.y$pred["response"]), col=R_pal[["rainbow_75"]][4:20],
  main="Predictions spLearner", axes=FALSE, box=FALSE)

library(parallelMap)
library(deepnet)
library(xgboost)
## Regression with default settings:
m <- train.spLearner(meuse["zinc"], covariates=meuse.grid[,c("dist", "ffreq")],
  parallel=FALSE, lambda = 0)
## Ensemble model (meta-learner):
summary(m@spModel$learner.model$super.model$learner.model)
meuse.y <- predict(m)
## Plot of predictions and prediction error (RMSPE)
op <- par(mfrow=c(1,2), oma=c(0,0,0,1), mar=c(0,0,4,3))
plot(raster(meuse.y$pred["response"]), col=R_pal[["rainbow_75"]][4:20],
  main="Predictions spLearner", axes=FALSE, box=FALSE)
points(meuse, pch="+")
plot(raster(meuse.y$pred["model.error"]), col=rev(bpy.colors()),
  main="Prediction errors", axes=FALSE, box=FALSE)
points(meuse, pch="+")
par(op)
dev.off()
## Plot of prediction intervals:
pts = list("sp.points", meuse, pch = "+", col="black")
spplot(meuse.y$pred[,c("q.lwr", "q.upr")], col.regions=R_pal[["rainbow_75"]][4:20],
  sp.layout = list(pts),
  main="Prediction intervals (alpha = 0.318)")
dev.off()

## Method from https://doi.org/10.3390/rs12101687
library(meteo)

```

```

mN <- train.spLearner(meuse["zinc"], covariates=meuse.grid[,c("dist", "ffreq")],
  parallel=FALSE, lambda = 0, nearest=TRUE)
meuse.N <- predict(mN)
## Plot of predictions and prediction error (RMSPE)
op <- par(mfrow=c(1,2), oma=c(0,0,0,1), mar=c(0,0,4,3))
plot(raster(meuse.N$pred["response"]), col=R_pal[["rainbow_75"]][4:20],
  main="Predictions spLearner meteo::near.obs", axes=FALSE, box=FALSE)
points(meuse, pch="+")
plot(raster(meuse.N$pred["model.error"]), col=rev(bpy.colors()),
  main="Prediction errors", axes=FALSE, box=FALSE)
points(meuse, pch="+")
par(op)
dev.off()

## Classification:
SL.library <- c("classif.ranger", "classif.xgboost", "classif.nnTrain")
mC <- train.spLearner(meuse["soil"], covariates=meuse.grid[,c("dist", "ffreq")],
  SL.library = SL.library, super.learner = "classif.glmnet", parallel=FALSE)
meuse.soil <- predict(mC)
splot(meuse.soil$pred[grep("prob.", names(meuse.soil$pred))],
  col.regions=SAGA_pal[["SG_COLORS_YELLOW_RED"]], zlim=c(0,1))
splot(meuse.soil$pred[grep("error.", names(meuse.soil$pred))],
  col.regions=rev(bpy.colors()))

## SIC1997
data("sic1997")
X <- sic1997$swiss1km[,c("CHELSA_rainfall", "DEM")]
mR <- train.spLearner(sic1997$daily.rainfall, covariates=X, lambda=1,
  nearest = TRUE, parallel=FALSE)
summary(mR@spModel$learner.model$super.model$learner.model)
rainfall1km <- predict(mR, what="mspe")
op <- par(mfrow=c(1,2), oma=c(0,0,0,1), mar=c(0,0,4,3))
plot(raster(rainfall1km$pred["response"]), col=R_pal[["rainbow_75"]][4:20],
  main="Predictions spLearner", axes=FALSE, box=FALSE)
points(sic1997$daily.rainfall, pch="+")
plot(raster(rainfall1km$pred["model.error"]), col=rev(bpy.colors()),
  main="Prediction errors", axes=FALSE, box=FALSE)
points(sic1997$daily.rainfall, pch="+")
par(op)
dev.off()

## Ebergotzen data set
data(eberg_grid)
gridded(eberg_grid) <- ~x+y
proj4string(eberg_grid) <- CRS("+init=epsg:31467")
data(eberg)
eb.s <- sample.int(nrow(eberg), 1400)
eberg <- eberg[eb.s,]
coordinates(eberg) <- ~X+Y
proj4string(eberg) <- CRS("+init=epsg:31467")
## Binomial variable
summary(eberg$TAXGRSC)
eberg$Parabraunerde <- ifelse(eberg$TAXGRSC=="Parabraunerde", 1, 0)

```

```

X <- eberg_grid[c("PRMGE06", "DEMSRT6", "TWISRT6", "TIRAST6")]
mB <- train.spLearner(eberg["Parabraunerde"], covariates=X,
  family=binomial(), cov.model = "nugget", parallel=FALSE)
eberg.Parabraunerde <- predict(mB)
plot(raster(eberg.Parabraunerde$pred["prob.1"]),
  col=SAGA_pal[["SG_COLORS_YELLOW_RED"]], zlim=c(0,1))
points(eberg["Parabraunerde"], pch="+")

## Factor variable:
data(eberg)
coordinates(eberg) <- ~X+Y
proj4string(eberg) <- CRS("+init=epsg:31467")
X <- eberg_grid[c("PRMGE06", "DEMSRT6", "TWISRT6", "TIRAST6")]
mF <- train.spLearner(eberg["TAXGRSC"], covariates=X, parallel=FALSE)
TAXGRSC <- predict(mF)
plot(stack(TAXGRSC$pred[grep("prob.", names(TAXGRSC$pred))]),
  col=SAGA_pal[["SG_COLORS_YELLOW_RED"]], zlim=c(0,1))
plot(stack(TAXGRSC$pred[grep("error.", names(TAXGRSC$pred))]),
  col=SAGA_pal[["SG_COLORS_YELLOW_BLUE"]], zlim=c(0,0.45))
dev.off()

```

train.spLearner.matrix

Train a spatial prediction and/or interpolation model using Ensemble Machine Learning from a regression/classification matrix

Description

Train a spatial prediction and/or interpolation model using Ensemble Machine Learning from a regression/classification matrix

Usage

```

train.spLearner.matrix(
  observations,
  formulaString,
  covariates,
  SL.library,
  family = stats::gaussian(),
  method = "stack.cv",
  predict.type,
  super.learner,
  subsets = 5,
  lambda = 0.5,
  cov.model = "exponential",
  subsample = 10000,
  parallel = "multicore",
  cell.size,

```

```

    id = NULL,
    weights = NULL,
    quantreg = TRUE,
    ...
  )

```

Arguments

<code>observations</code>	Data frame regression matrix,
<code>formulaString</code>	Model formula,
<code>covariates</code>	SpatialPixelsDataFrame object,
<code>SL.library</code>	List of learners,
<code>family</code>	Family e.g. <code>gaussian()</code> ,
<code>method</code>	Ensemble stacking method (see <code>makeStackedLearner</code>),
<code>predict.type</code>	Prediction type 'prob' or 'response',
<code>super.learner</code>	Ensemble stacking model usually <code>regr.lm</code> ,
<code>subsets</code>	Number of subsets for repeated CV,
<code>lambda</code>	Target variable transformation for geoR (0.5 or 1),
<code>cov.model</code>	Covariance model for variogram fitting,
<code>subsample</code>	For large datasets consider random subsetting training data,
<code>parallel</code>	Initiate parallel processing,
<code>cell.size</code>	Block size for spatial Cross-validation,
<code>id</code>	Id column name to control clusters of data,
<code>weights</code>	Optional weights (per row) that learners will use to account for variable data quality,
<code>quantreg</code>	Fit additional ranger model as meta-learner to allow for derivation of prediction intervals,
<code>...</code>	other arguments that can be passed on to <code>mlr::makeStackedLearner</code> ,

Value

Object of class `spLearner`

Author(s)

Tom Hengl

TT2tri	<i>Soil texture class to texture fractions conversion</i>
--------	---

Description

Soil texture class to texture fractions conversion

Usage

```
TT2tri(  
  TT.class,  
  se.fit = TRUE,  
  TT.im = NULL,  
  soil.var = "TEXMHT",  
  levs = c("S", "LS", "SL", "SCL", "SiL", "SiCL", "CL", "L", "Si", "SC", "SiC", "C",  
           "HC")  
)
```

Arguments

TT.class	based on the soiltexture package
se.fit	derive errors
TT.im	soil texture triangle image
soil.var	column name in the TT.im file
levs	texture class legends (USDA system)

Value

Data frame with estimated sand, silt and clay values

Examples

```
library(soiltexture)  
## convert textures by hand to sand, silt and clay:  
TEXMHT <- c("CL", "C", "SiL", "SiL", "missing")  
x <- TT2tri(TEXMHT)  
x
```

 tune.spLearner, spLearner-method

Optimize spLearner by fine-tuning parameters and running feature selection

Description

Optimize spLearner by fine-tuning parameters and running feature selection

Usage

```
## S4 method for signature 'spLearner'
tune.spLearner(
  object,
  num.trees = 85,
  blocking,
  discrete_ps,
  rdesc = mlr::makeResampleDesc("CV", iters = 2L),
  inner = mlr::makeResampleDesc("Holdout"),
  maxit = 20,
  xg.model_Params,
  xg.skip = FALSE,
  parallel = "multicore",
  hzn_depth = FALSE,
  ...
)
```

Arguments

object	spLearner object (unoptimized),
num.trees	number of random forest trees,
blocking	blocking columns,
discrete_ps	settings for random forest,
rdesc	resampling method for fine-tuning,
inner	resampling method for feature selection,
maxit	maximum number of iterations for feature selection,
xg.model_Params	xgboost parameter set,
xg.skip	logical, should the tuning of the XGboost should be skipped?
parallel	Initiate parallel processing,
hzn_depth	specify whether horizon depth available in the training dataframe,
...	other arguments that can be passed on to mlr::makeStackedLearner,

Value

optimized object of type spLearner

Note

Currently requires that two base learners are `regr.ranger` and `regr.xgboost`, and that there are at least 3 base learners in total. Fine-tuning and feature selection can be quite computational and it is highly recommended to start with smaller subsets of data and then measure processing time. The function `mlr::makeFeatSelWrapper` can result in errors if the covariates have a low variance or follow a zero-inflated distribution. Reducing the number of features via feature selection and fine-tuning of the Random Forest `mtry` and XGboost parameters, however, can result in significantly higher prediction speed and accuracy.

Author(s)

Tom Hengl

Examples

```
library(mlr)
library(ParamHelpers)
library(geoR)
library(xgboost)
library(kernlab)
library(ranger)
library(glmnet)
library(boot)
library(raster)
demo(meuse, echo=FALSE)
## Regression:
sl = c("regr.ranger", "regr.xgboost", "regr.ksvm", "regr.cvglmnet")
m <- train.spLearner(meuse["lead"], covariates=meuse.grid[,c("dist", "ffreq")],
  lambda=0, parallel=FALSE, SL.library=sl)
summary(m@spModel$learner.model$super.model$learner.model)
## Optimize model:
m0 <- tune.spLearner(m, xg.skip = TRUE, parallel=FALSE)
summary(m0@spModel$learner.model$super.model$learner.model)
```

Description

Probability density for texture triangle (USDA system) based on global soil profile data (see ISRIC WoSIS).

Usage

```
data(USDA.TT.im)
```

Format

The USDA.TT.im data frame contains the following columns:

v numeric; probability density derived using the `soiltexture::TT.kde2d` function and global soil profile data

TEXTMHT factor; USDA soil texture class estimated by hand (one of the following: "C", "SiC", "SC", "CL", "SiCL", "SCL", "L", "SiL", "SL", "Si", "LS", "S")

s1 numeric; horizontal coordinate (sand content 0–1) in the texture triangle system

s2 numeric; vertical coordinate (0–0.85) in the texture triangle system

Note

Texture by hand class can be converted to sand, silt, clay content fractions by using the `TT2tri` function. This function uses the `v` column in the `USDA.TT.im` (i.e. prior probability densities) to adjust for texture fraction combinations that are more probable.

Author(s)

Tomislav Hengl

References

- Skaggs, T. H., Arya, L. M., Shouse, P. J., Mohanty, B. P., (2001) Estimating Particle-Size Distribution from Limited Soil Texture Data. *Soil Science Society of America Journal* 65 (4): 1038-1044.

Examples

```
## plot prior probabilities:  
library(sp)  
data(USDA.TT.im)  
gridded(USDA.TT.im) <- ~s1+s2  
splot(USDA.TT.im["v"])
```

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