

Package ‘learNN’

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Title Examples of Neural Networks

Version 0.2.0

Description Implementations of several basic neural network concepts in R, as based on posts on [\url{http://qua.st/}](http://qua.st/).

Depends R (>= 2.10.0)

License GPL-3

Suggests testthat

NeedsCompilation no

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learnn	<i>Learn Neural Networks</i>
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Description

Learn Neural Networks

`learn_bp`*Learn Back Propagation*

Description

Learn Back Propagation

Usage`learn_bp(X, y)`**Arguments**

<code>X</code>	input data
<code>y</code>	output data

References<http://qua.st/handcoding-neural-network/><http://qua.st/handcoding-neural-network/> <http://iamtrask.github.io/2015/07/12/basic-python-network/>**Examples**

```
# create data
X = matrix(c(0,0,1,
            0,1,1,
            1,0,1,
            1,1,1), nrow=4, byrow=TRUE)

y = matrix(c(0,
            1,
            1,
            0),
            nrow=4)

# run full function
learn_bp(X, y)
```

`learn_bp11`*Learn Back Propagation in 11 lines*

Description

Learn Back Propagation in 11 lines

Usage

```
learn_bp11(X, y)
```

Arguments

X	input data
y	output data

References

<http://qua.st/handcoding-neural-network/> <http://iamtrask.github.io/2015/07/12/basic-python-network/>

See Also

[learn_bp](#)

Examples

```
# construct new data
X = matrix(c(0,0,1,0,1,1,1,0,1,1,1,1), nrow=4, byrow=TRUE)
y = matrix(c(0,1,1,0),nrow=4)

# run 11 lines function
learn_bp11(X, y)

# view output
syn0
syn1
```

learn_do

Learn Dropout

Description

Learn Dropout

Usage

```
learn_do(X, y, alpha, hidden_dim, dropout_percent, do_dropout = TRUE)
```

Arguments

X	input data
y	output data
alpha	proportion of gradient descent
hidden_dim	dimension of the hidden layer
dropout_percent	percentage to be used for the dropout
do_dropout	should dropout be used

References

<http://qua.st/handcoding-dropout/> <http://iamtrask.github.io/2015/07/28/dropout/>

Examples

```
# construct data
X = matrix(c(0,0,1,0,1,1,1,0,1,1,1,1), nrow=4, byrow=TRUE)
y = matrix(c(0,1,1,0),nrow=4)

# set hyperparameters
alpha = 0.5
hidden_dim = 4
dropout_percent = 0.2
do_dropout = TRUE

# run 11 lines function
learn_do(X, y, alpha, hidden_dim, dropout_percent, TRUE)

# view output
synapse_0
synapse_1
```

learn_do15

Learn Dropout in 15 lines

Description

Learn Dropout in 15 lines

Usage

```
learn_do15(X, y, alpha, hidden_dim, dropout_percent, do_dropout = TRUE)
```

Arguments

X	input data
y	output data
alpha	proportion of gradient descent
hidden_dim	dimension of the hidden layer
dropout_percent	percentage to be used for the dropout
do_dropout	should dropout be used

References

<http://qua.st/handcoding-dropout/> <http://iamtrask.github.io/2015/07/28/dropout/>

See Also[learn_do](#)**Examples**

```
# construct data
X = matrix(c(0,0,1,0,1,1,1,0,1,1,1,1), nrow=4, byrow=TRUE)
y = matrix(c(0,1,1,0),nrow=4)

# set hyperparameters
alpha = 0.5
hidden_dim = 4
dropout_percent = 0.2
do_dropout = TRUE

# run 11 lines function
learn_do15(X, y, alpha, hidden_dim, dropout_percent, TRUE)

# view output
synapse_0
synapse_1
```

`learn_gd`*Learn Gradient Descent*

Description

Learn Gradient Descent

Usage`learn_gd(X, y, alpha, hiddenSize)`**Arguments**

X	input data
y	output data
alpha	fraction of gradient descent
hiddenSize	size of the hidden layer

References

<http://qua.st/handcoding-gradient-descent/> <http://iamtrask.github.io/2015/07/27/python-network-part2/>

Examples

```
# input dataset
X = matrix(c(0,0,1,
            0,1,1,
            1,0,1,
            1,1,1), nrow=4, byrow=TRUE)

# output dataset
y = matrix(c(0,
            1,
            1,
            0), nrow=4)

# set parameters
alpha = 0.1
hiddenSize = 32
# also try using:
# alphas = c(0.001,0.01,0.1,1,10,100,1000)
# for (alpha in alphas) {
#   print(paste("Training With Alpha", alpha))
#   learn_gd(X, y, alpha, hiddenSize)
# }

# run gradient descent function
learn_gd(X, y, alpha, hiddenSize)
```

learn_gd13

Learn Gradient Descent in 13 lines

Description

Learn Gradient Descent in 13 lines

Usage

```
learn_gd13(X, y, alpha, hidden_dim)
```

Arguments

X	input data
y	output data
alpha	alpha to be used
hidden_dim	dimension of the hidden layer

References

<http://qua.st/handcoding-gradient-descent/> <http://iamtrask.github.io/2015/07/27/python-network-part2/>

See Also

[learn_gd](#)

Examples

```
# create new data
alpha = 0.5
hidden_dim = 4
X = matrix(c(0,0,1,0,1,1,1,0,1,1,1,1), nrow=4, byrow=TRUE)
y = matrix(c(0,1,1,0),nrow=4)

# run 13 lines function
learn_gd13(X, y, alpha, hidden_dim)
```

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