

Package ‘threeBrain’

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Type Package

Title 3D Brain Visualization

Version 0.1.4

Description In neuroscience, 'AFNI/SUMA' is a great tool to visualize 3D brain. However, it takes efforts to interact and share the viewer to others. In addition, 'AFNI/SUMA' doesn't support Windows platform. In the 'EEG/iEEG' field, it's hard to have multiple cortical electrodes mapped to a template brain for group analysis. Therefore this package is written aimed at providing a fast, stable, interactive and easy to share tool based on 'Three.js', a 'WebGL' engine to render 3D objects in the web browser such that we can display brain surfaces on webpage interactively. This package translates R objects to JavaScript objects via 'JSON' format, and provides 'R-Shiny' interface to manipulate geometries interactively. The visualizations can also serve as standalone widgets that can be easily shared across different platforms. Along with 'rave', another package developed by Beauchamp's lab at Baylor College Medicine, this package provides solutions to easily map surface electrodes from multiple subjects to one template 141 brain.

License GPL-3

Encoding UTF-8

LazyData true

RoxygenNote 6.1.1

Language en-US

URL <https://github.com/dipterix/threeBrain>

BugReports <https://github.com/dipterix/threeBrain/issues>

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Suggests knitr, rmarkdown, pryr

NeedsCompilation no

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AbstractGeom	<i>R6 Class - Abstract Class of Geometries</i>
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Description

R6 Class - Abstract Class of Geometries

Author(s)

Zhengjia Wang

BlankGeom	<i>A geometry that renders nothing</i>
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Description

This is mainly used when you want to upload group data only

Usage

BlankGeom

Format

An object of class R6ClassGenerator of length 24.

brain_setup	<i>Setup Package, Install Environment</i>
-------------	---

Description

Setup Package, Install Environment

Usage

```
brain_setup(continued = FALSE, show_example = TRUE,
            use_python = TRUE, try_conda = TRUE)
```

Arguments

continued	logical, there are two phases of setting up environment. You probably need to restart R session after the first phase and continue setting up.
show_example	whether to show example of 'N27' subject at the end.
use_python	whether to install python toolbox (recommended)
try_conda	try to use 'conda' to create 'RAVEPy' environment

Author(s)

Zhengjia Wang

 check_freesurfer_path *Function to check whether 'FreeSurfer' folder has everything we need*

Description

Function to check whether 'FreeSurfer' folder has everything we need

Usage

```
check_freesurfer_path(fs_subject_folder, autoinstall_template = TRUE,
  return_path = FALSE, check_volume = FALSE, check_surface = FALSE)
```

Arguments

fs_subject_folder	character, path to 'fs' project directory or 'RAVE' subject directory
autoinstall_template	logical, whether 'N27' brain should be installed is missing
return_path	logical, whether to return 'FreeSurfer' path
check_volume	logical, whether to check volume data
check_surface	logical, whether to check surface data (not implemented yet)

Value

logical whether the directory is valid or, if return_path is true, return 'FreeSurfer' path

 create_group *Create a geometry group containing multiple geometries*

Description

Create a geometry group containing multiple geometries

Usage

```
create_group(name, position = c(0, 0, 0), layer = 1)
```

Arguments

name	string, name of the geometry
position	x,y,z location of the group
layer	layer of the group. reserved

Details

A geometry group is a container of multiple geometries. The geometries within the same group share the same shift and rotations (see example 1). In ECoG/iEEG world, you might have 'MRI', 'CT', 'FreeSurfer' that have different orientations. For example, if you want to align MRI to FreeSurfer, Instead of calculating the position of each geometries, you can just put all MRI components into a group, and then set transform of this group, making the group aligned to FreeSurfer.

GeomGroup also can be used to store large data. To generate 3D viewer, 'threeBrain' needs to dynamically serialize data into JSON format, which can be read by browsers. However, a FreeSurfer brain might be ~30 MB. This is a very large size and might take ~5 seconds to serialize. To solve this problem, GeomGroup supports cache in its 'set_group_data' method. This method supports caching static serialized data into a JSON file, and allows the files to be loaded as static data objects. By "static", I mean the data is not supposed to be dynamic, and it should be "read-only". In JavaScript code, I also optimized such that you don't need to load these large datasets repeatedly. And this allows you to load multiple subjects' brain in a short time.

Value

a GeomGroup instance

Author(s)

Zhengjia Wang

Examples

```
# Example 1: relative position

# create group
g = create_group('Group A')

# create two spheres at 10,0,0, but s2 is relative to group A
s1 = geom_sphere('Sphere 1', radius = 2, position = c(10,0,0))
s2 = geom_sphere('Sphere 2', radius = 2, position = c(10,0,0), group = g)

# set transform (rotation)
g$set_transform(matrix(c(
  0,1,0,0,
  1,0,0,0,
  0,0,1,0,
  0,0,0,1
), byrow = TRUE, ncol = 4))

# global position for s2 is 0,10,0
threejs_brain(s1, s2)

# Example 2: cache

# download N27 brain
# Make sure you have N27 brain downloaded to ~/rave_data/others/threeBrain/N27
# download_N27()
```

```

dat = threeBrain::read_fs_asc('~/.rave_data/others/three_brain/N27/surf/lh.pial.asc')
vertex = dat$vertices[,1:3]
face = dat$faces[,1:3]

# 1. dynamically serialize
mesh = geom_freemesh('lh', vertex = vertex, face = face, layer = 1)
pryr::object_size(mesh) # ~10 MB
threejs_brain(mesh) # ~3 seconds to serialize

# 2. cache
# Create group, all geometries in this group are relatively positioned
tmp_file = tempfile()
mesh = geom_freemesh('Left Hemisphere cached', vertex = vertex,
                    face = face, cache_file = tmp_file)
pryr::object_size(mesh) # ~0.5 MB
threejs_brain(mesh) # serialize at once, load in browser

```

DataCubeGeom

R6 Class - Generate Data Cube Geometry

Description

R6 Class - Generate Data Cube Geometry

Author(s)

Zhengjia Wang

DataCubeGeom2

R6 Class - Generate Data Cube Geometry via 3D Volume Texture

Description

R6 Class - Generate Data Cube Geometry via 3D Volume Texture

Author(s)

Zhengjia Wang

FreeGeom

*R6 Class - Generate Geometry from Vertices and Face Indices***Description**

R6 Class - Generate Geometry from Vertices and Face Indices

freesurfer_brain

*Read 'FreeSurfer' surface and volume files***Description**

Read 'FreeSurfer' surface and volume files

Usage

```
freesurfer_brain(fs_subject_folder, subject_name,
  additional_surfaces = NULL, aligned_ct = NULL, use_cache = TRUE,
  use_141 = TRUE)
```

Arguments

fs_subject_folder	character, 'FreeSurfer' subject folder, or 'RAVE' subject folder
subject_name	character, subject code to display with only letters and digits
additional_surfaces	character array, additional surface types to load, such as 'white', 'smoothwm'
aligned_ct	character, path to 'ct_aligned_mri.nii.gz', used for electrode localization
use_cache	logical, whether to use cached 'json' files or from raw 'FreeSurfer' files
use_141	logical, whether to use standard 141 brain for surface file

Details

This function is under FreeSurfer license. 1. Volumes: 3D viewer uses 'mri/T1.mgz' from 'FreeSurfer' to show the volume information. 'T1.mgz' results from step 1 to 5 in 'FreeSurfer' command 'recon-all -autorecon1', which aligns the original 'DICOM' image to 'RAS' coordinate system, resamples to volume with 256x256x256 voxels (tri-linear by default, check <https://surfer.nmr.mgh.harvard.edu/fswiki/recon-all> for more information).

2. Surface: There are two options for surface files. The first choice is using 'std.141' brain generated by 'AFNI/SUMA'. This surface file re-calculates vertices from standard 141 space, which averages the "surface" of 141 subjects. If you want to map surface electrodes across different subjects, you might want to consider this case as it's especially designed for surface mapping. However, you'll need 'AFNI/SUMA' installed to generate the surface file. The details can be found via <https://openwetware.org/wiki/Beauchamp:CorticalSurfaceHCP>, and the 'AFNI/SUMA' command

related is ‘SurfToSurf’. Please generate the files to ‘[FREESURFER SUBJECT DIR]/SUMA/'. The file name follows the convention of ‘std.141.[lr]h.[SURFACE TYPE].[POSTFIX]’, where ‘lh’ means left hemisphere and ‘rh’ means right hemisphere; ‘SURFACE TYPE’ can be ‘pial’, ‘white’, ‘smoothwm’, and ‘POSTFIX’ can be ‘asc’, ‘gii’. If multiple files for the same surface type exists, the search order will be ‘asc > gii’. The other option is to use mesh files directly from ‘FreeSurfer’ output located at ‘[FREESURFER SUBJECT DIR]/surf’. If you want to use these surface, make sure they are converted to ‘asc’ or ‘gii’ format.

3. Electrode registration and transforms This package provides two ways to map electrodes to standard space. For surface electrodes, if standard 141 brain is provided, then the first option is to snap electrodes to the nearest vertices in subject space. The key is the vertex number matches across different subjects, hence the location of corresponding vertices at template brain are the mapped electrode coordinates. If standard 141 brain is missing, or the electrode type is ‘stereo EEG’, then the second option is volume mapping. The idea is to map electrodes to ‘MNI305’ brain. The details can be found at <https://surfer.nmr.mgh.harvard.edu/fswiki/CoordinateSystems>. To perform volume mapping, we need ‘FreeSurfer’ folder ‘mri/transforms’. Currently, only linear ‘Talairach’ transform matrix is supported (located at ‘talairach.xfm’).

4. Coordinates The 3D viewer in this package uses the center of volume as the origin (0, 0, 0).

Author(s)

Zhengjia Wang

Examples

```
# Please run `download_N27()` if `N27` is not at `~/rave_data/others/three_brain/`

# Import from `FreeSurfer` subject folder
brain = threeBrain::freesurfer_brain(
  fs_subject_folder = '~/rave_data/others/three_brain/N27/', subject_name = 'N27',
  additional_surfaces = c('white', 'smoothwm')
)

# Visualize. Alternatively, you can use brain$plot(...)
plot( brain )
```

GeomGroup

R6 Class - Generate Group of Geometries

Description

R6 Class - Generate Group of Geometries

Author(s)

Zhengjia Wang

geom_freemesh	<i>Creates any mesh geometry given vertices and face indices</i>
---------------	--

Description

Creates any mesh geometry given vertices and face indices

Usage

```
geom_freemesh(name, vertex = NULL, face = NULL, position = c(0, 0,
  0), layer = 1, cache_file = NULL, group = NULL)
```

Arguments

name	unique string in a scene to tell apart from different objects
vertex	position of each vertices (3 columns)
face	face indices indicating which 3 vertices to be linked (3 columns)
position	x,y,z location of the geometry
layer	visibility of the geometry, used when there are multiple cameras 1 is visible for all cameras
cache_file	cache vertex and face data into group
group	a GeomGroup object, if null, then the group will be generated automatically

Details

When generating a free mesh internally, a group must be specified, therefore if group is NULL here, then a group will be generated. However, it's always recommended to pass a group to the free mesh.

Author(s)

Zhengjia Wang

Examples

```
# Make sure you have N27 brain downloaded to ~/rave_data/others/threeBrain/N27
# threeBrain::download_N27()

n27_dir = '~/rave_data/others/three_brain/N27/'
surf_type = 'pial'

# Locate mesh files
lh = read_fs_asc(file.path(n27_dir, sprintf('surf/lh.%s.asc', surf_type)))
rh = read_fs_asc(file.path(n27_dir, sprintf('surf/rh.%s.asc', surf_type)))

# Create groups
group = create_group(name = sprintf('Surface - %s (N27)', surf_type))
```

```

# create mesh
lh_mesh = geom_freemesh(
  name = sprintf('FreeSurfer Left Hemisphere - %s (N27)', surf_type),
  vertex = lh$vertices[,1:3],
  face = lh$faces[,1:3],
  group = group
)
rh_mesh = geom_freemesh(
  name = sprintf('FreeSurfer Right Hemisphere - %s (N27)', surf_type),
  vertex = rh$vertices[,1:3],
  face = rh$faces[,1:3],
  group = group
)

# Render
threejs_brain(lh_mesh, rh_mesh)

```

geom_sphere

Create sphere geometry

Description

Create sphere geometry

Usage

```
geom_sphere(name, radius, position = c(0, 0, 0), layer = 1,
  group = NULL, value = NULL, time_stamp = NULL)
```

Arguments

name	unique string in a scene to tell apart from different objects
radius	size of sphere
position	x,y,z location of the sphere
layer	visibility of the geometry, used when there are multiple cameras 1 is visible for all cameras
group	a GeomGroup object
value, time_stamp	color of the sphere, used for animation/color rendering

Author(s)

Zhengjia Wang

Examples

```
# Create a sphere with animation
g = lapply(1:10, function(ii){
  v = rep(ii, 10)
  v[1:ii] = 1:ii
  geom_sphere(paste0('s', ii), ii, value = v, position = c(11 * ii, 0,0), time_stamp = (1:10)/10)
})
threejs_brain(.list = g)
```

merge_brain	<i>Create Multi-subject Template</i>
-------------	--------------------------------------

Description

Create Multi-subject Template

Usage

```
merge_brain(..., .list = NULL, template_surface_types = NULL,
  template_subject = getOption("threeBrain.template_subject", "N27"),
  template_dir = getOption("threeBrain.template_dir",
    "~/rave_data/others/three_brain"))
```

Arguments

...	.list	Brain2 objects
	template_surface_types	which template surface types to load, default is auto-guess
	template_subject	character, subject code to be treated as template, default is 'N27'
	template_dir	the parent directory where template subject is stored in

Author(s)

Zhengjia Wang

ravepy	<i>Manage Python Environment from RAVE</i>
--------	--

Description

Manage Python Environment from RAVE

Usage

```
ravepy_remove(conda = TRUE)

ravepy_check(quiet = FALSE)

ravepy_register()

ravepy_virtualenv_install(python_path = NULL)

ravepy_conda_install(python_path = NULL)

ravepy_info(quiet = FALSE, return_libs = FALSE)
```

Arguments

conda	logical, is your environment created using conda?
quiet	logical, suppress printing information.
python_path	character, python path, auto-detected if NULL. Please specify Python3 path
return_libs	logical, return python modules?

Author(s)

Zhengjia Wang

read_fs_asc	<i>Read 'FreeSurfer' ascii file</i>
-------------	-------------------------------------

Description

Read 'FreeSurfer' ascii file

Usage

```
read_fs_asc(file)
```

Arguments

file	file location
------	---------------

Value

a list of vertices and face indices

read_fs_m3z	<i>Read 'FreeSurfer' m3z file</i>
-------------	-----------------------------------

Description

Read 'FreeSurfer' m3z file

Usage

```
read_fs_m3z(filename)
```

Arguments

filename	file location, usually located at 'mri/transforms/talairach.m3z'
----------	--

Details

An 'm3z' file is a 'gzip' binary file containing a dense vector field that describes a 3D registration between two volumes/images. This implementation follows the 'Matlab' implementation from the 'FreeSurfer'. This function is released under the 'FreeSurfer' license: <https://surfer.nmr.mgh.harvard.edu/fswiki/FreeSurferSoftwareLicense>.

Value

registration data

read_fs_mgh_mgz	<i>Read 'FreeSurfer' 'mgz/mgh' file</i>
-----------------	---

Description

Read 'FreeSurfer' 'mgz/mgh' file

Usage

```
read_fs_mgh_mgz(filename)
```

Arguments

filename	file location
----------	---------------

Value

list contains coordinate transforms and volume data

`read_gii2`*Function to load surface data from 'Gifti' files*

Description

The function `'read_gii2'` is a dynamic wrapper of Python `'nibabel'` loader. If no Python is detected, it will switch to `'gifti::readgii'`.

Usage

```
read_gii2(path)
```

Arguments

`path` `'Gifti'` file path

Format

An R function acting as safe wrapper for `nibabel.load`.

`read_mgz`*Function to load 'FreeSurfer' 'mgz/mgh' file*

Description

The function `'read_mgz'` is a dynamic wrapper of Python `'nibabel'` loader. If no Python is detected, it will switch to built-in function `'read_fs_mgh_mgz'`, which has limited features.

Usage

```
read_mgz(path)
```

Arguments

`path` `'mgz/mgh'` file path

Format

An R function acting as safe wrapper for `nibabel.load`.

`renderBrain`*Shiny Renderer for threeBrain Widgets*

Description

Shiny Renderer for threeBrain Widgets

Arguments

<code>expr</code>	R expression that calls <code>three_brain</code> function or Brain object
<code>env</code>	environment of expression to be evaluated
<code>quoted</code>	is <code>expr</code> quoted? Default is false.

Author(s)

Zhengjia Wang

`reorient_volume`*Function to reshape data to 'RAS' order*

Description

Function to reshape data to 'RAS' order

Usage

```
reorient_volume(volume, Norig)
```

Arguments

<code>volume</code> ,	3-mode tensor (voxels), usually from 'mgz', 'nii', or 'BRIK' files
<code>Norig</code>	a 4x4 transform matrix mapping volume ('CRS') to 'RAS'

Value

Reshaped tensor with dimensions corresponding to 'R', 'A', and 'S'

save_brain

Save threeBrain widgets to local file system

Description

Save threeBrain widgets to local file system

Usage

```
save_brain(widget, directory, filename = "index.html",  
           assetpath = "lib/", datapath = "lib/threebrain_data-0/",  
           title = "3D Viewer", as_zip = FALSE)
```

Arguments

widget	generated from function 'threejs_brain'.
directory	directory to save the widget.
filename	default is 'index.html', filename of the widget index file.
assetpath	where to put css or JavaScript to, must be relative to directory.
datapath	where to store data to, must be relative to directory.
title	widget title.
as_zip	whether to create zip file "compressed.zip".

Author(s)

Zhengjia Wang

SphereGeom

R6 Class - Generate Sphere Geometry

Description

R6 Class - Generate Sphere Geometry

Author(s)

Zhengjia Wang

template_subject	<i>Download and Manage Template Subjects</i>
------------------	--

Description

Download and Manage Template Subjects

Usage

```
download_template_subject(subject_code = "N27",
    url = "https://rave-data.s3.amazonaws.com/sample-data/N27_fs.zip",
    template_dir = getOption("threeBrain.template_dir",
        "~/rave_data/others/three_brain"))
```

```
download_N27(make_default = FALSE, ...)
```

```
set_default_template(subject_code, view = TRUE,
    template_dir = getOption("threeBrain.template_dir",
        "~/rave_data/others/three_brain"))
```

Arguments

subject_code	character with only letters and numbers (Important). Default is ‘N27’
url	zip file address
template_dir	parent directory where subject’s ‘FreeSurfer’ folder should be stored
make_default	logical, whether to make ‘N27’ default subject
...	more to pass to download_template_subject
view	whether to view the subject

Details

To view electrodes implanted in multiple subjects, it’s highly recommended to view them in a template space. The detail mapping method is discussed in function `freesurfer_brain`.

To map to a template space, one idea is to find someone whose brain is normal. In our case, the choice is subject ‘N27’, also known as ‘Colin 27’. function `download_N27` provides a simple and easy way to download a partial version from the Internet.

If you have any other ideas about template brain, you can use function `set_default_template(subject_code, template_dir)` to redirect to your choice. If your template brain is a ‘Zip’ file on the Internet, we provide function `download_template_subject` to automatically install it.

Author(s)

Zhengjia Wang

threejsBrainOutput	<i>Shiny Output for threeBrain Widgets</i>
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Description

Shiny Output for threeBrain Widgets

Arguments

outputId	unique identifier for the widget
width, height	width and height of the widget. By default width="100 and height="500px".

Author(s)

Zhengjia Wang

threejs_brain	<i>Create a Threejs Brain and View it in Browsers</i>
---------------	---

Description

Create a Threejs Brain and View it in Browsers

Usage

```
threejs_brain(..., .list = list(), width = NULL, height = NULL,
  side_canvas = FALSE, side_zoom = 1, side_width = 250,
  side_shift = c(0, 0), side_display = TRUE, control_panel = TRUE,
  control_presets = NULL, control_display = TRUE,
  camera_center = c(0, 0, 0), camera_pos = c(0, 0, 500),
  start_zoom = 1, coords = NULL, symmetric = 0,
  default_colormap = "Value", palettes = NULL, val_ranges = NULL,
  show_inactive_electrodes = TRUE, widget_id = "threebrain_data",
  tmp_dirname = NULL, debug = FALSE, token = NULL,
  optionals = list(), browser_external = TRUE, global_data = list())
```

Arguments

..., .list	geometries inherit from AbstractGeom
width, height	positive integers. Width and height of the widget. By default width='100%', and height varies.
side_canvas	logical, enable side cameras to view objects from fixed perspective
side_zoom	numerical, if side camera is enabled, zoom-in level, from 1 to 5
side_width	positive integer, side panel size in pixels

side_shift	integer of length two, side panel shift in pixels ('CSS style': top, left)
side_display	logical, show/hide side panels at beginning
control_panel	logical, enable control panels for the widget
control_presets	characters, presets to be shown in control panels
control_display	logical, whether to expand/collapse control UI at the beginning
camera_center	numerical, length of three, XYZ position where camera should focus at
camera_pos	XYZ position of camera itself, default (0, 0, 500)
start_zoom	numerical, positive number indicating camera zoom level
coords	NULL to hide coordinates or numeric vector of three.
symmetric	numerical, default 0, color center will be mapped to this value
default_colormap	character, which color map name to display at startup
palettes	named list, names corresponds to color-map names if you want to change color palettes
val_ranges	named list, similar to palettes, value range for each values
show_inactive_electrodes	logical, whether to show electrodes with no values
widget_id	character, internally used as unique identifiers for widgets. Only use it when you have multiple widgets in one website
tmp_dirname	character path, internally used, where to store temporary files
debug	logical, internally used for debugging
token	unique character, internally used to identify widgets in JS localStorage
optionals	internally used, to be deprecated
browser_external	logical, use system default browser (default) or builtin one.
global_data	internally use, mainly to store orientation matrices.

Author(s)

Zhengjia Wang

three_scatter	<i>3D Scatter Plot</i>
---------------	------------------------

Description

3D Scatter Plot

Usage

```
three_scatter(x, y, z, size = 1, col = 1, label = NULL, group = 1,
  timestamp = NULL, pal = NULL, scale = 1, axis = TRUE,
  control_panel = TRUE, control_presets = NULL, camera_pos, ...)
```

Arguments

x, y, z	numeric vectors with the same length n.
size	size for each point.
col	color vector/matrix, can be either numeric or factor. Its length (vector) or nrow (matrix) must be either n or 1.
label	text label of each observation.
group	categorical group names of each points.
timestamp	numeric vector, length of 0 or ncol(col).
pal	color palette, vector of colors, can be integers.
scale	'auto', NULL, or numeric, rescale the final coordinates. Default 1, no re-scale.
axis	logical, draw axis.
control_panel	logical, show sidebar (control panel).
control_presets	if control_panel is true, which widgets to show.
camera_pos	initial camera position, auto assign if missing.
...	other arguments passing to threejs_brain.

Author(s)

Zhengjia Wang

Examples

```
## Continuous color example:
data("iris")
three_scatter(x = iris$Sepal.Length, y = iris$Sepal.Width,
  z = iris$Petal.Length, size = 0.1,
  col = iris$Petal.Width, group = iris$Species,
```

```
pal = c('orange', 'blue3', 'darkgreen'),
start_zoom = 12, axis = FALSE)

# Discrete example:

x = rnorm(26, c(10, 10, -20))
y = rnorm(26, c(10, -10, 10))
z = rnorm(26, c(10, 40, -10))
three_scatter(x, y, z, size = 1, col = sample(letters[1:3], 20, TRUE),
pal = c('orange', 'blue3', 'darkgreen'))
```

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